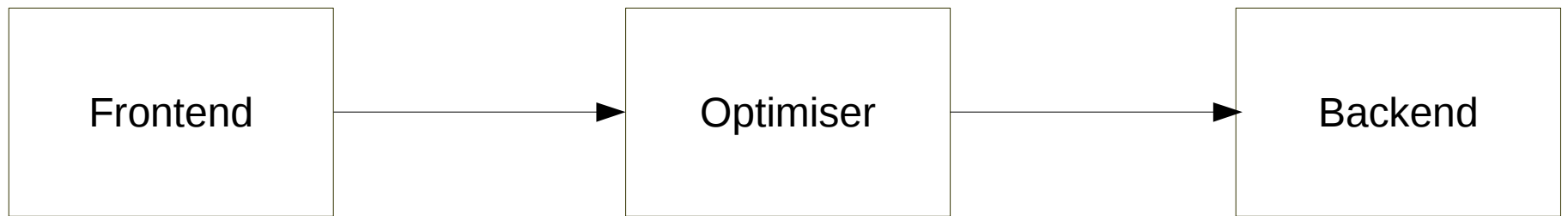


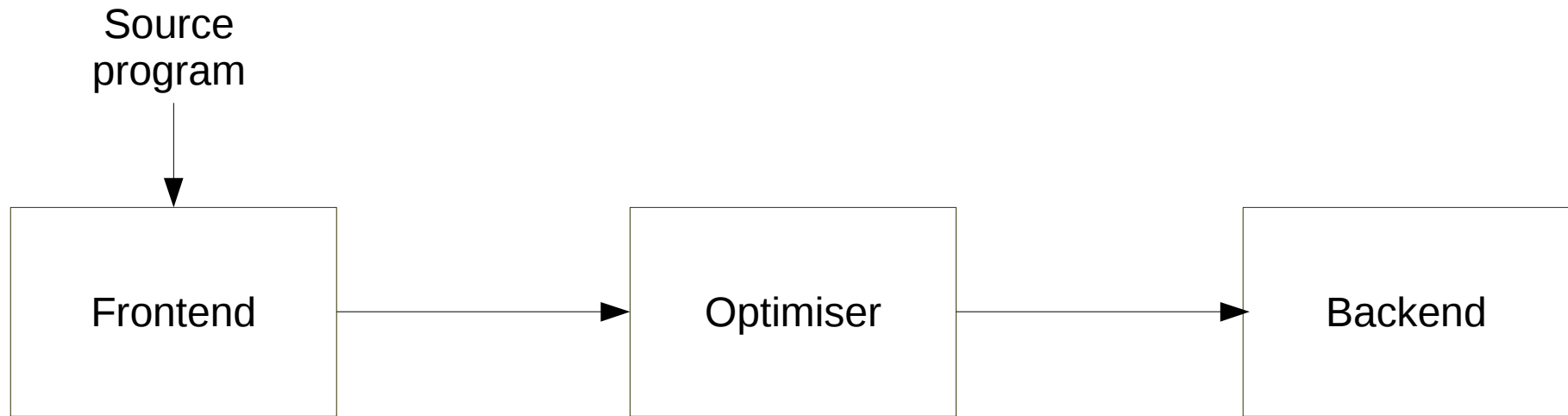
Exploring the fundamental differences between compiler optimisations for energy and for time

James Pallister and Kerstin Eder
University of Bristol

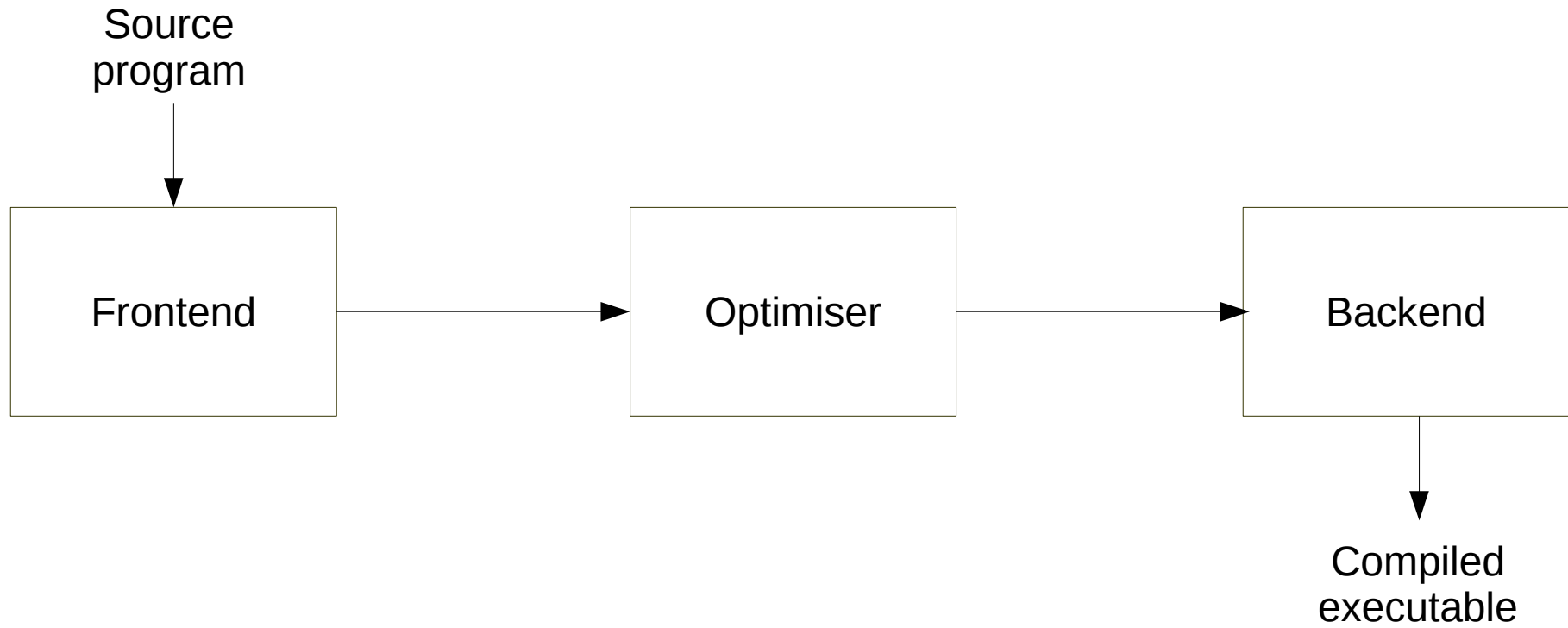
Compilers



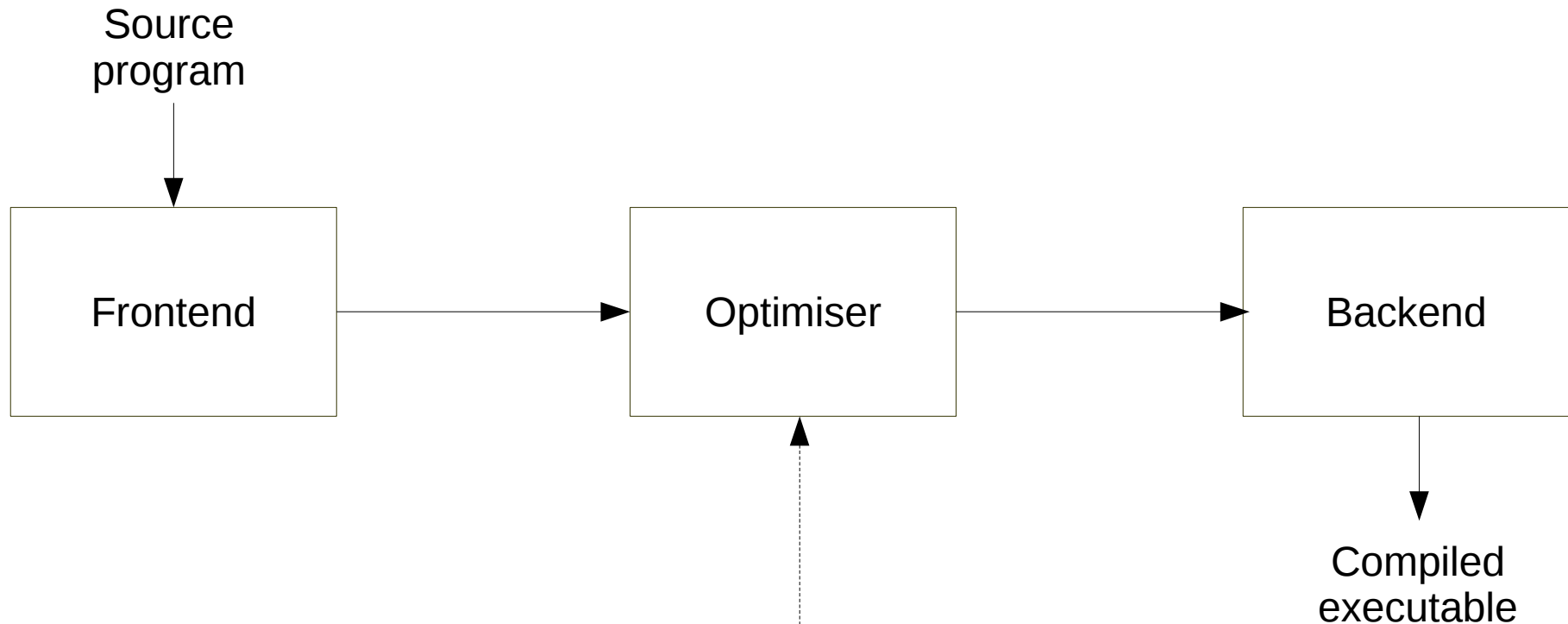
Compilers



Compilers



Compilers



Large impact on program:

- runtime
- energy
- code size

Topics of interest



Topics of interest

How do compiler optimisations affect energy, power and time?

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Are there different “types” of optimisation?

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Compilers → automatic

Embedded systems

Overview

Overview

Introduction

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Introduction

Optimisations for execution time

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Optimisations for execution time

Optimisations for energy consumption

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Optimisations for energy consumption

Combining optimisations for energy and time

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Optimisations for execution time

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Combining optimisations for energy and time

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Overview

► *Introduction*

Optimisations for execution time

Optimisations for energy consumption

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Conclusion

An optimisation's effect

$$E = P \times T$$

An optimisation's effect

Average power



$$E = P \times T$$

An optimisation's effect

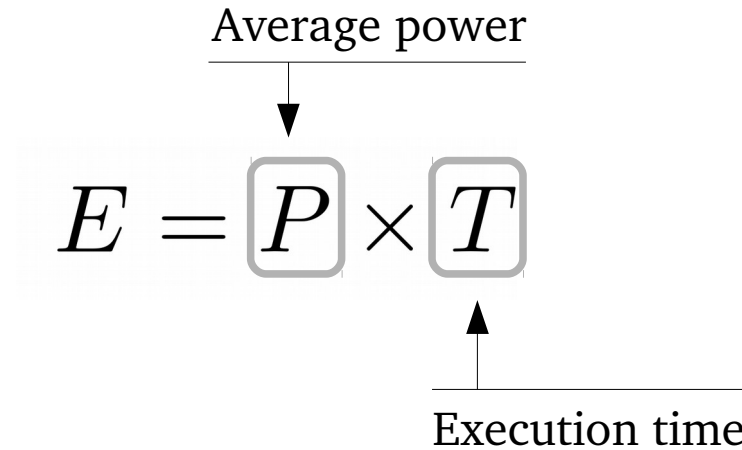
Average power

↓

$$E = P \times T$$

↑

Execution time



An optimisation's effect

$$\begin{array}{c} \text{Average power} \\ \hline \downarrow \\ \boxed{E} = \boxed{P} \times \boxed{T} \\ \begin{array}{ccc} \uparrow & & \uparrow \\ \hline \text{Energy} & & \text{Execution time} \end{array} \end{array}$$

An optimisation's effect

$$E = P \times T$$

An optimisation's effect

$$E = P \times T$$

$$T' = k_T \cdot T$$

An optimisation's effect

$$E = P \times T$$

Optimisation's effect on time



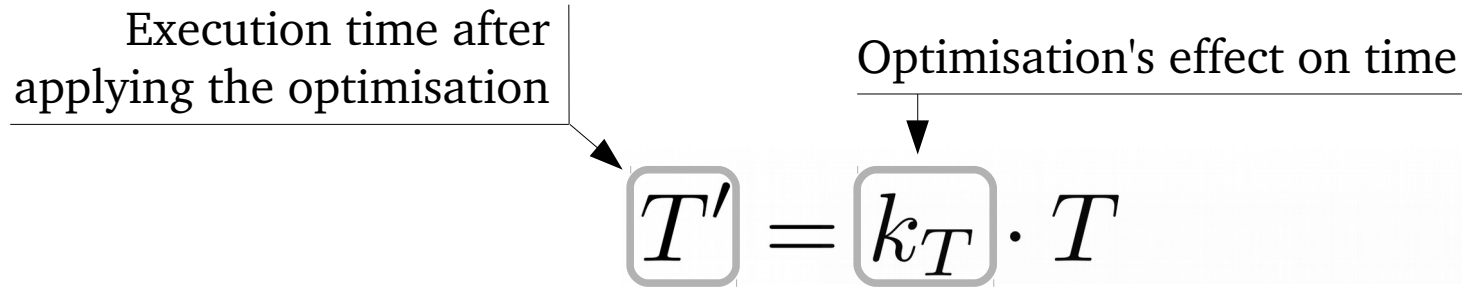
$$T' = k_T \cdot T$$

An optimisation's effect

$$E = P \times T$$

Execution time after
applying the optimisation

Optimisation's effect on time


$$T' = k_T \cdot T$$

An optimisation's effect

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An optimisation's effect

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An optimisation's effect

$$E = P \times T$$

$$T' = k_T \cdot T$$

$$P' = k_P \cdot P$$

$$E' = (k_P \cdot P) \times (k_T \cdot T)$$

An optimisation's effect

$$T' = k_T \cdot T$$

$$P' = k_P \cdot P$$

$$E' = (k_P \cdot P) \times (k_T \cdot T)$$

An optimisation's effect

Energy is saved if:

$$(k_T \cdot k_P) < 1$$

$$T' = k_T \cdot T$$

$$P' = k_P \cdot P$$

$$E' = (k_P \cdot P) \times (k_T \cdot T)$$

An optimisation's effect

$$T' = k_T \cdot T$$

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An optimisation's effect

Hypothesis:

The existing optimisations in the compiler only affect energy by reducing k_T .

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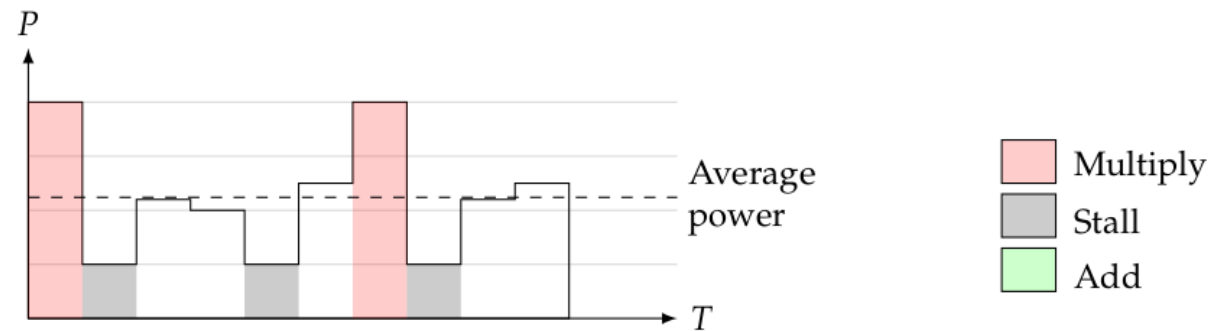
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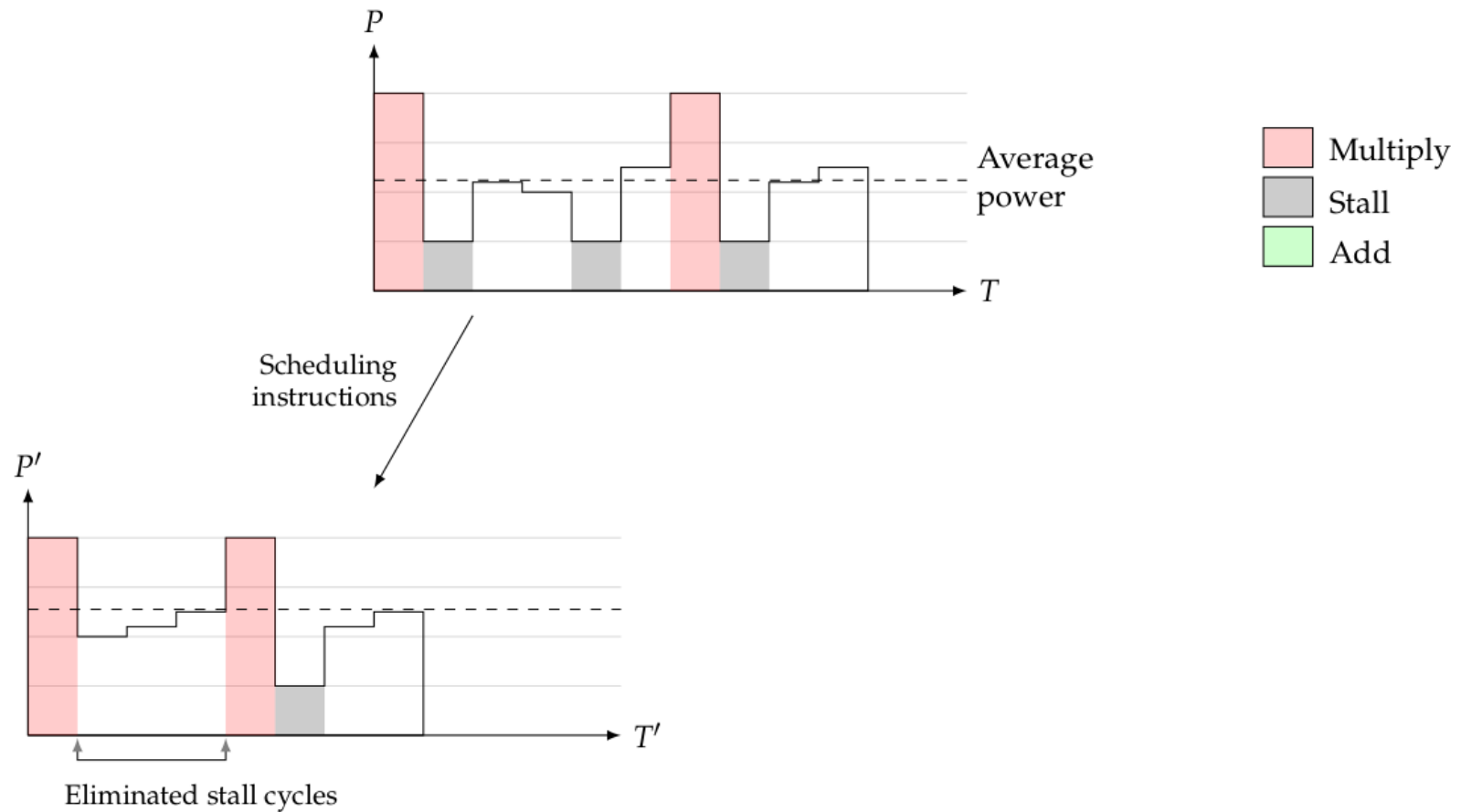
The existing optimisations in the compiler only affect energy by reducing k_T .

Optimisations in the compiler have been designed for reducing execution time.

Optimisation example



Optimisation example

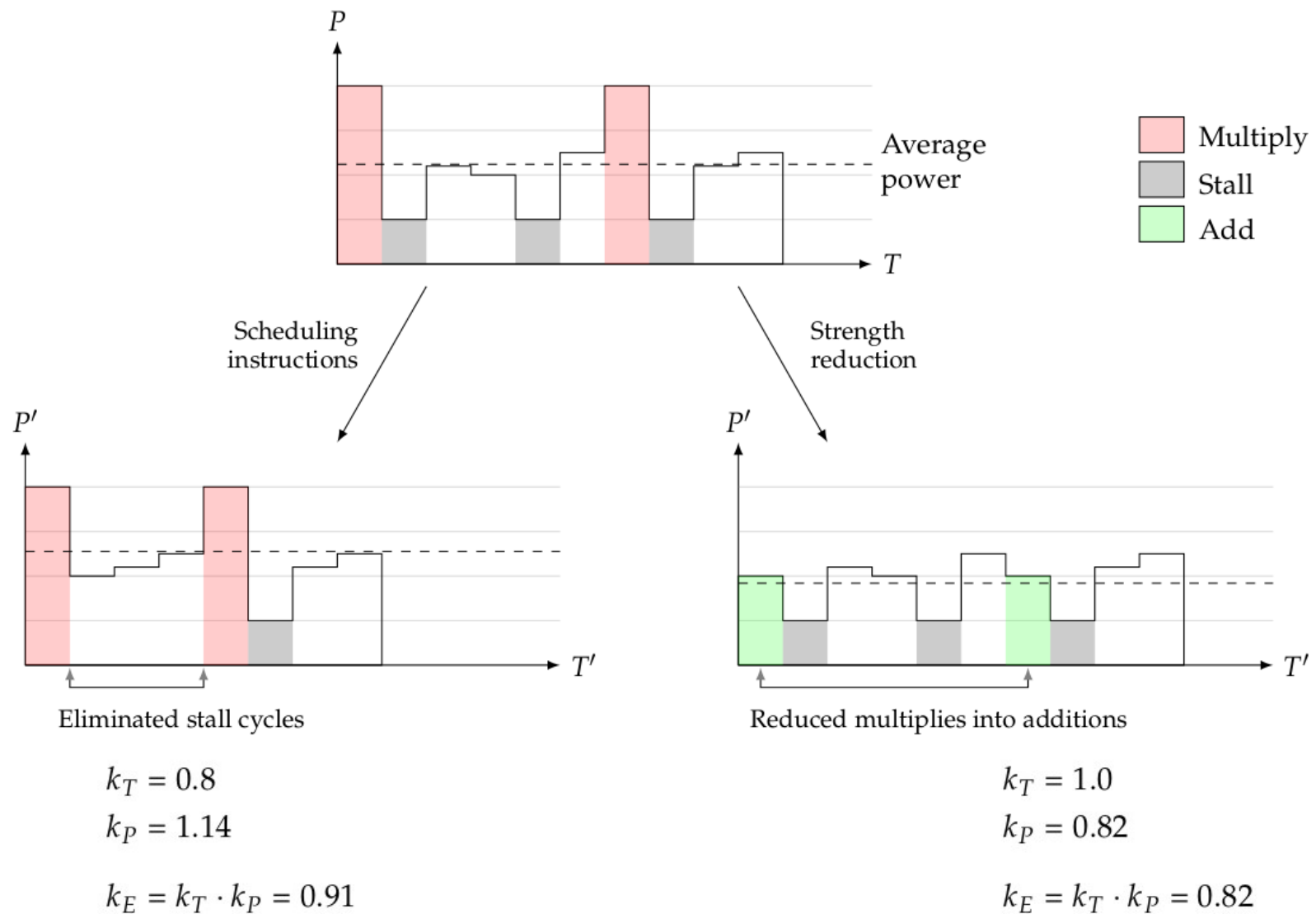


$$k_T = 0.8$$

$$k_P = 1.14$$

$$k_E = k_T \cdot k_P = 0.91$$

Optimisation example



Interactions and ordering



Interactions and ordering

No transformations

```
int function1(int a)
{
    return a * a;
}

int function2(int b)
{
    return function1(b + 1)
           * function1(b + 1);
}
```

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CSE

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int function1(int a)
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Inlining

```
int function2(int b)
{
    return ((b + 1) * (b + 1))
           * ((b + 1) * (b + 1));
}
```

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CSE, then inlining

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Inlining, then CSE

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int function2(int b)
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}
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Research questions



Research questions

Standard compiler optimisations

- Do existing compiler optimisations save energy purely by reducing the k_T coefficient?
- Are there any optimisations which affect k_P ?

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Standard compiler optimisations

- Do existing compiler optimisations save energy purely by reducing the k_T coefficient?
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Compiler optimisations for energy

- Is there a class of optimisations which can lower the energy via the k_P coefficient?
- How are they different?
- Are they effective?

Research questions

Combining optimisations

- Do optimisations designed to lower k_P interact with existing compiler optimisations?
- Are different sets of optimisations effective when including energy optimisations?

Overview

Introduction

► *Optimisations for execution time*

Optimisations for energy consumption

Combining optimisations for energy and time

Conclusion

Optimisations for time



Optimisations for time

Optimisations already in the compiler

Optimisations for time

Optimisations already in the compiler

Typically reducing code

- Common subexpression elimination
- Dead code elimination

Optimisations for time

Optimisations already in the compiler

Typically reducing code

- Common subexpression elimination
- Dead code elimination

Typically reordering code

- Instruction scheduling
- Array access patterns
- Moving invariant code out of loops

Optimisations for time

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Optimisations for time

Test how the compiler optimisations affect energy, by measuring both time and energy

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Optimisations for time

Test how the compiler optimisations affect energy, by measuring both time and energy

- Individual optimisations

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Optimisations for time

Test how the compiler optimisations affect energy, by measuring both time and energy

- Individual optimisations
- Sets of optimisations

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Optimisations for time

Test how the compiler optimisations affect energy, by measuring both time and energy

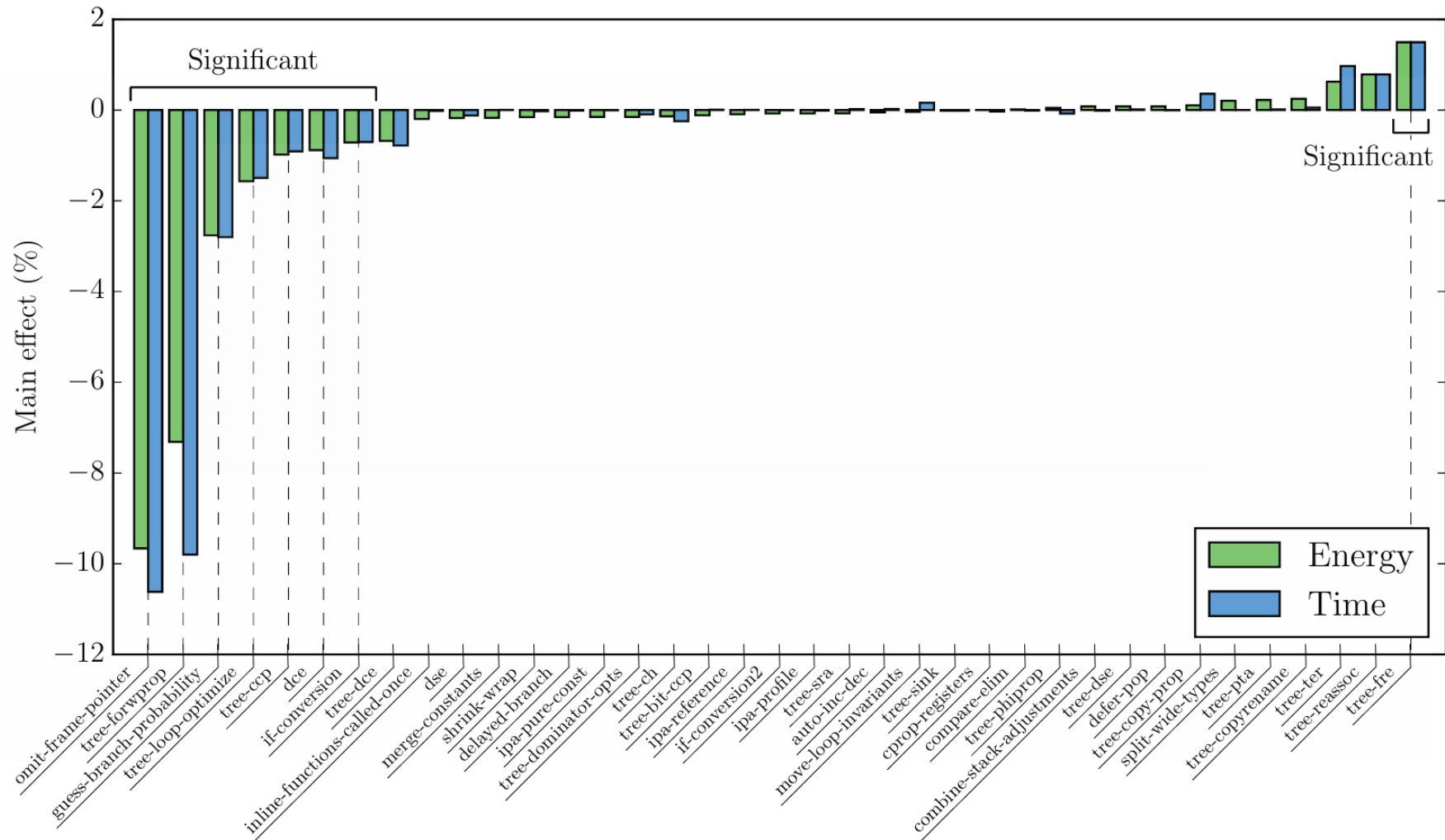
- Individual optimisations
- Sets of optimisations
- The “best” set of optimisations

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Individual optimisations

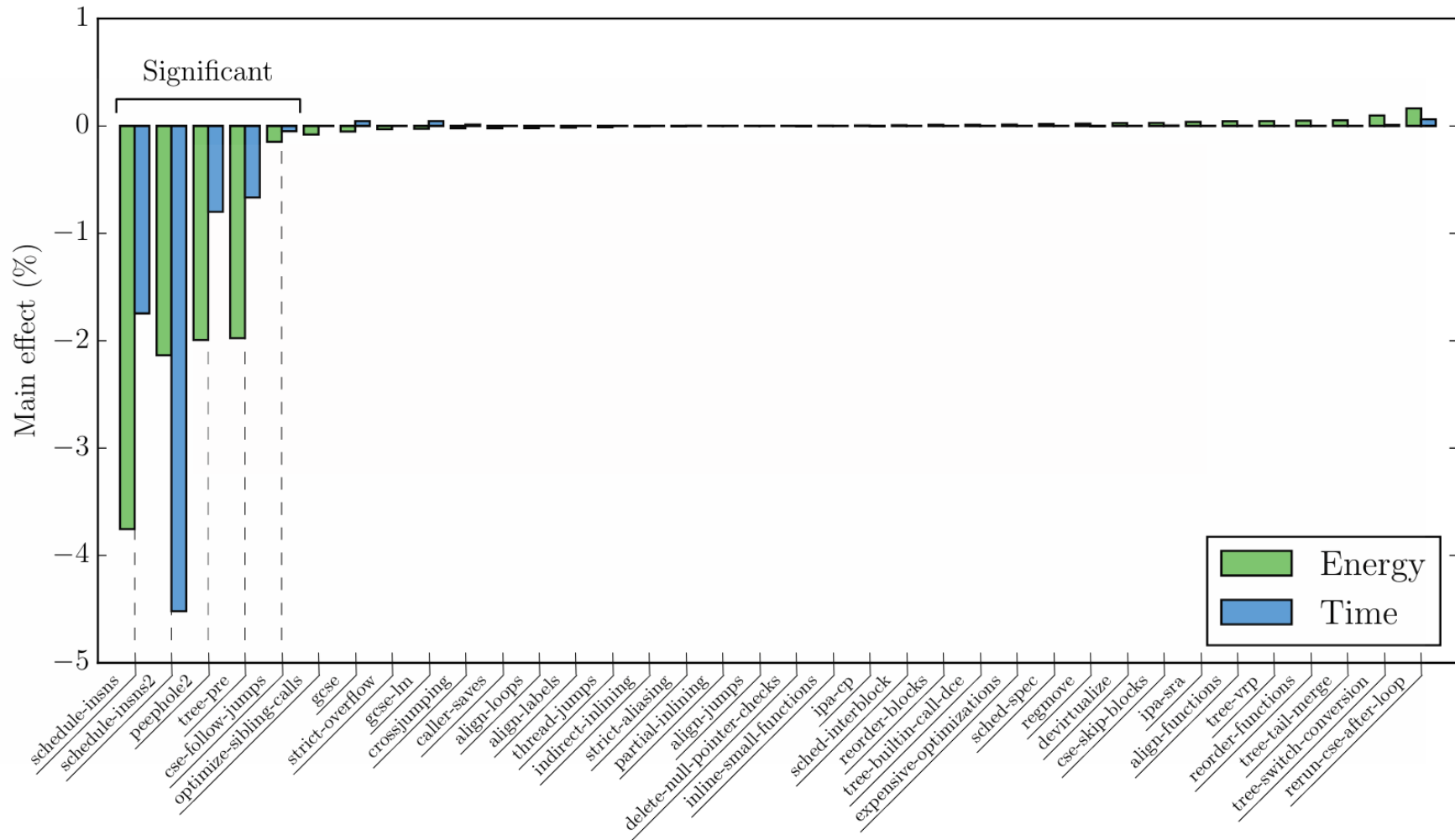
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Individual optimisations



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Individual optimisations



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No single set of optimisations is good for all benchmarks or all SoCs.

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Sets of optimisations

No single set of optimisations is good for all benchmarks or all SoCs.

The set of effective optimisations for each benchmark is different

- But the same for time and energy

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

The best set

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

“Are there any optimisations which affect k_P ?”

The best set

Attempt to pick good combinations of optimisations which maximise a fitness function

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Attempt to pick good combinations of optimisations which maximise a fitness function

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Compare the results of finding the best set for energy and for time.

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

“Are there any optimisations which affect k_P ?”

The best set

Attempt to pick good combinations of optimisations which maximise a fitness function

- Genetic algorithms

Compare the results of finding the best set for energy and for time.

- If similar, most of the energy savings are coming from a reduction in time.

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

“Are there any optimisations which affect k_P ?”

The best set

Minimise energy. $F(e, t) = \frac{1}{e}$.

Minimise time. $F(e, t) = \frac{1}{t}$.

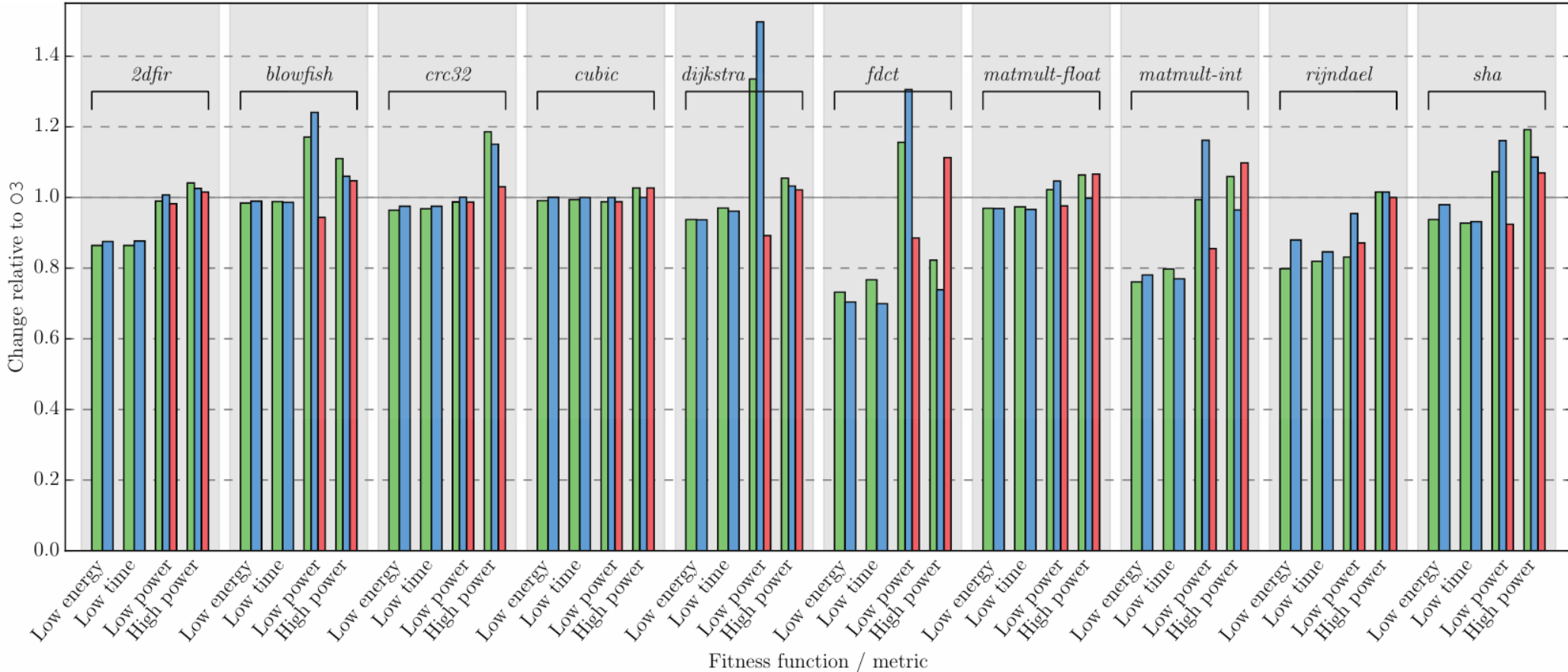
Minimise power. $F(e, t) = \frac{e}{t}$.

Maximise power. $F(e, t) = \frac{t}{e}$.

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

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Optimisations for time



Optimisations for time

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Overview

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Optimisations for execution time

► ***Optimisations for energy consumption***

Combining optimisations for energy and time

Conclusion

Optimisations for energy



Optimisations for energy

Try to find some optimisations which change the power coefficient

Optimisations for energy

Try to find some optimisations which change the power coefficient

Exploit some characteristics of the target processors:

- Embedded flash structure
- Flash and RAM differences

Embedded flash energy

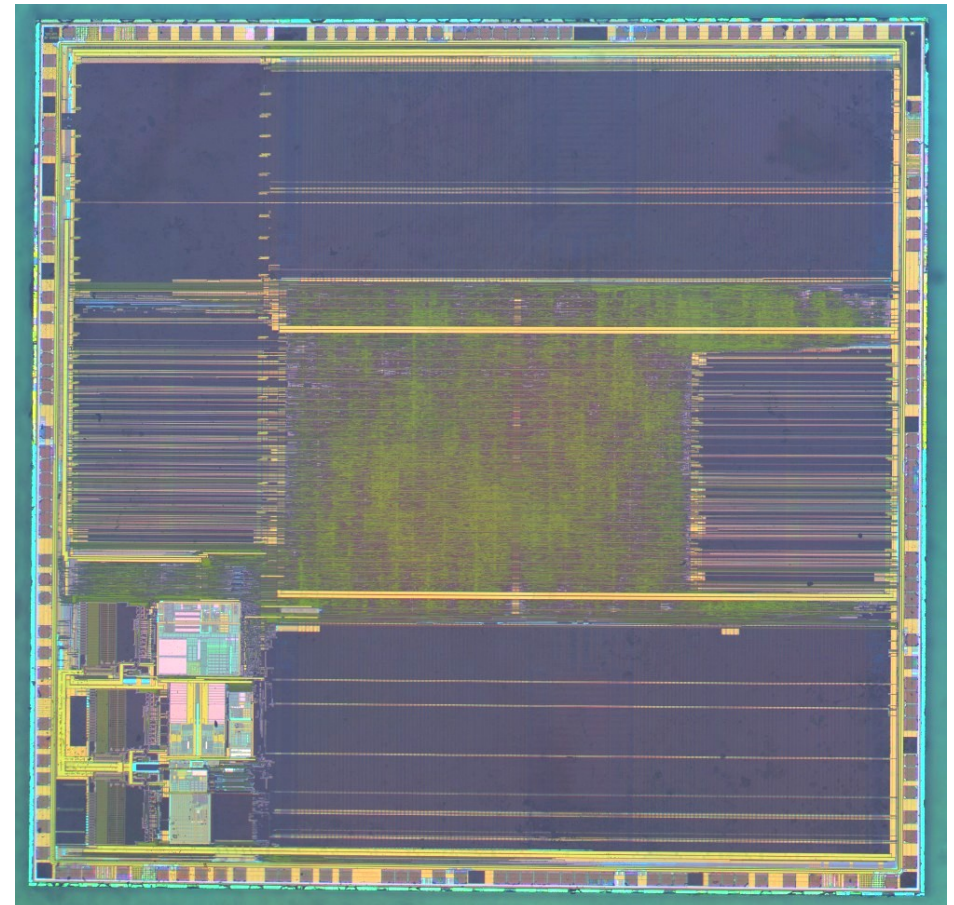


Embedded flash energy

Flash on the same die as the rest of the SoC

Embedded flash energy

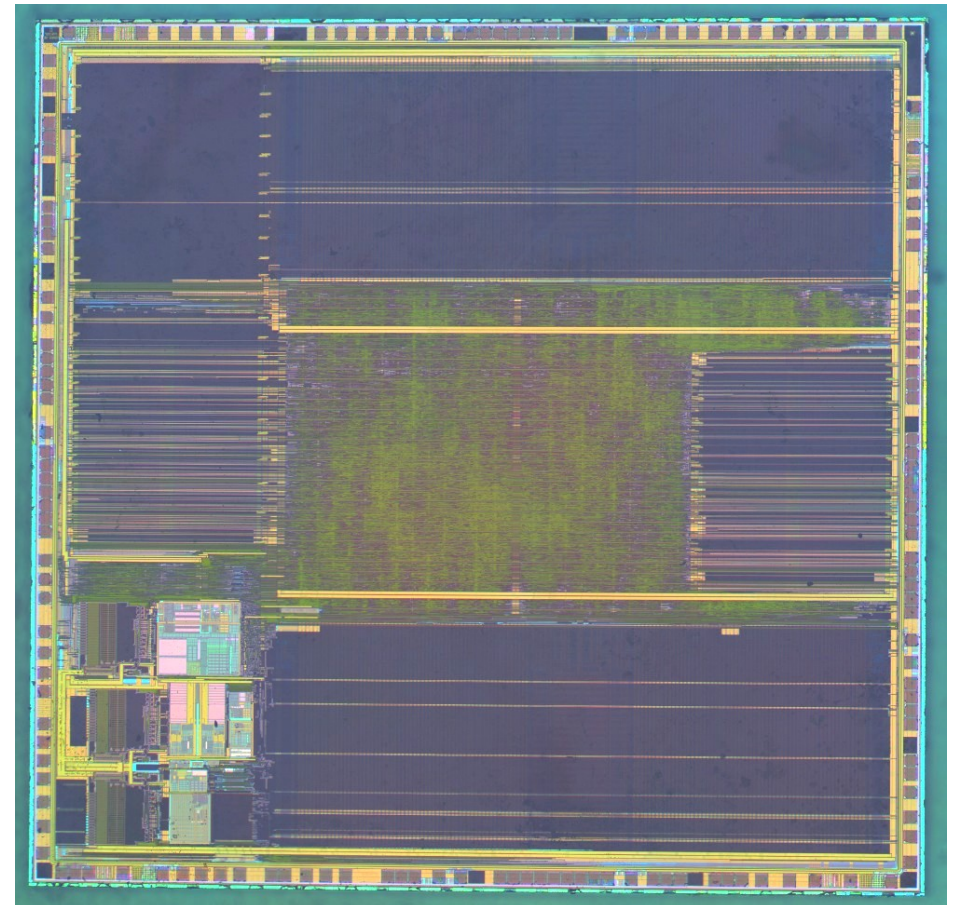
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Embedded flash energy

Flash on the same die as the rest of the SoC

Code execution directly
from flash

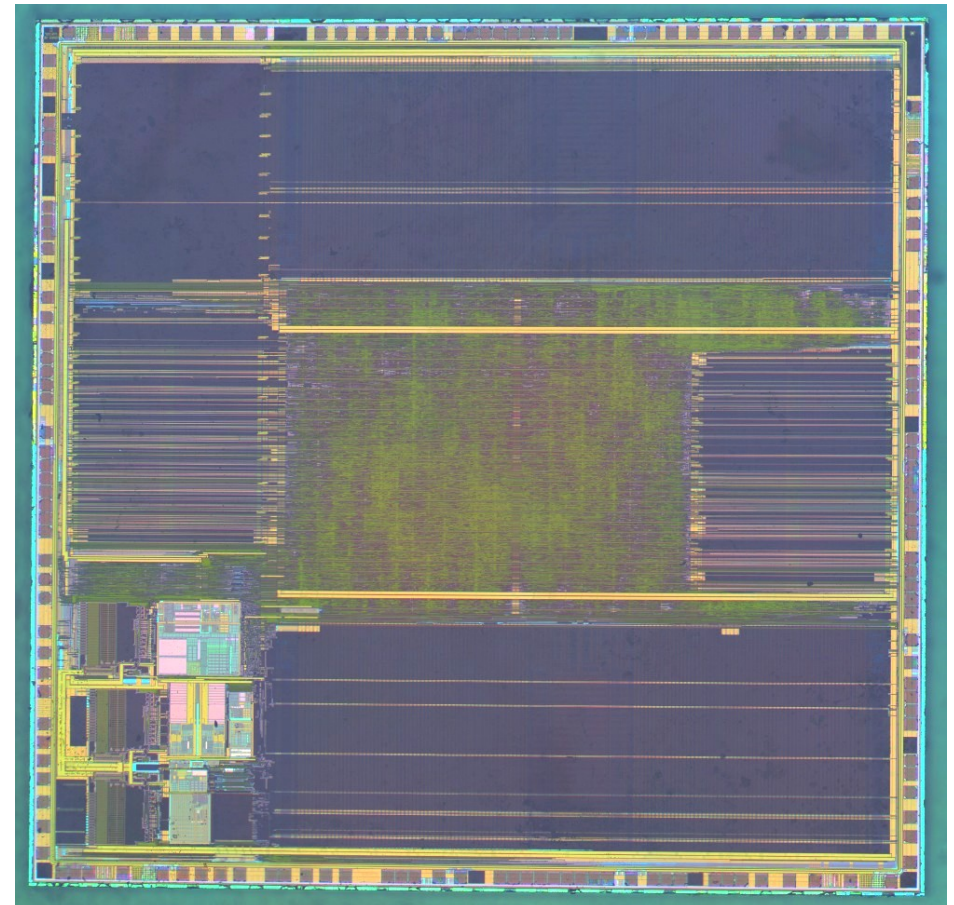


Embedded flash energy

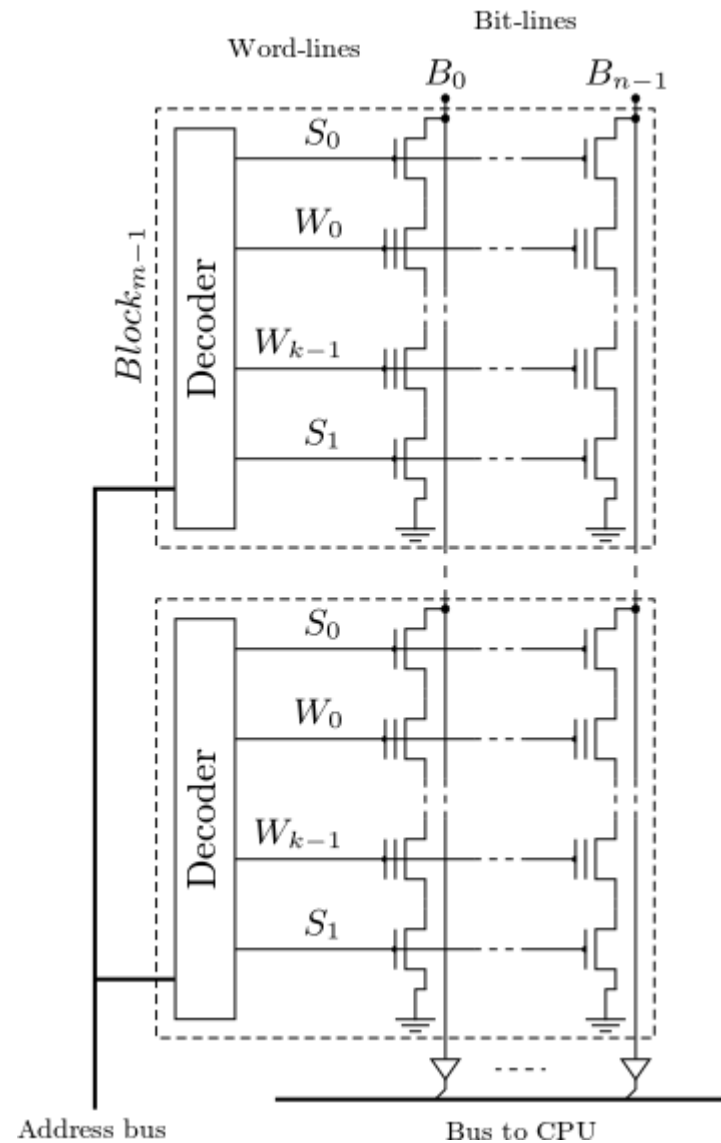
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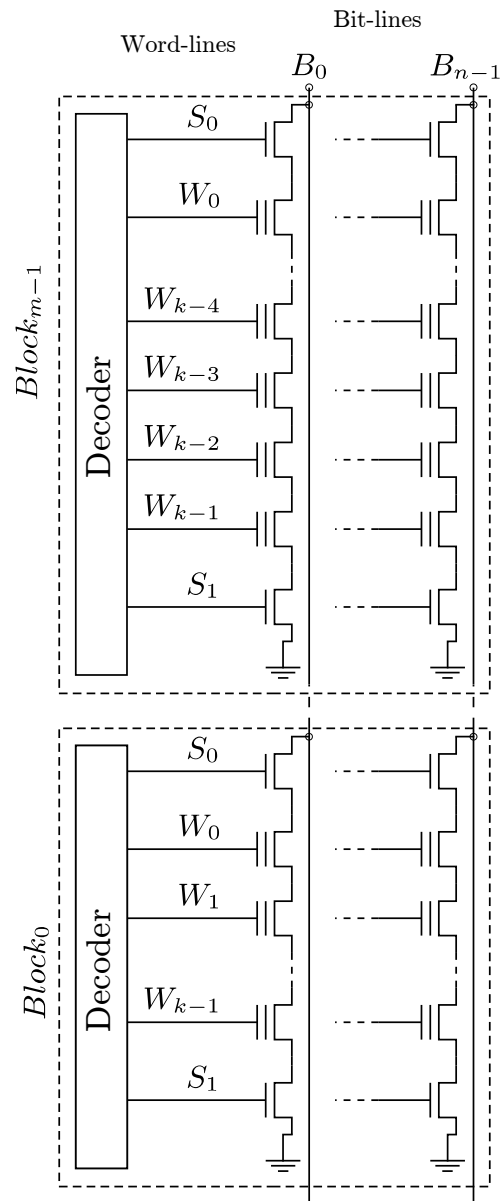
Structure of embedded
flash is non-uniform



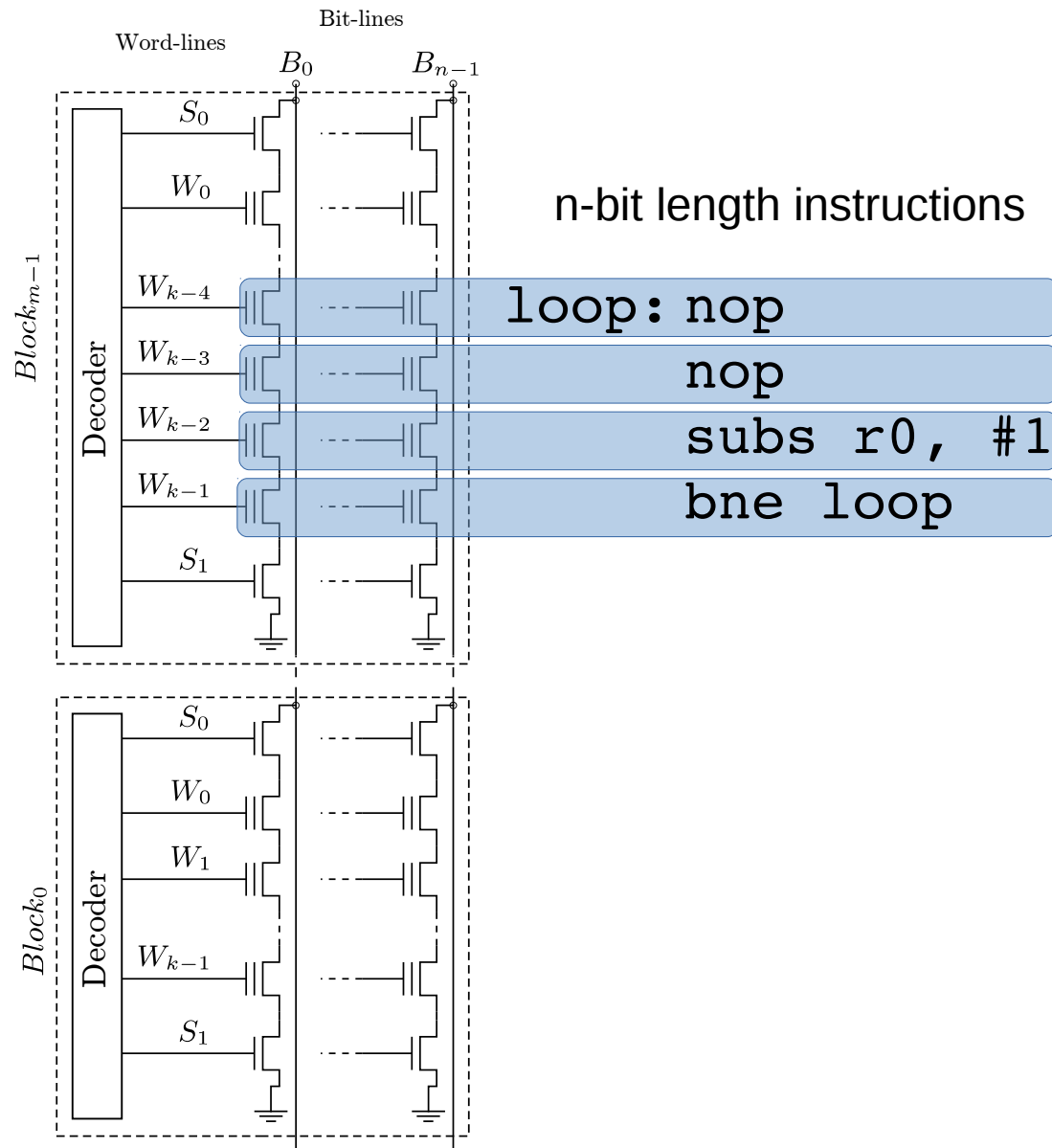
Embedded flash memory



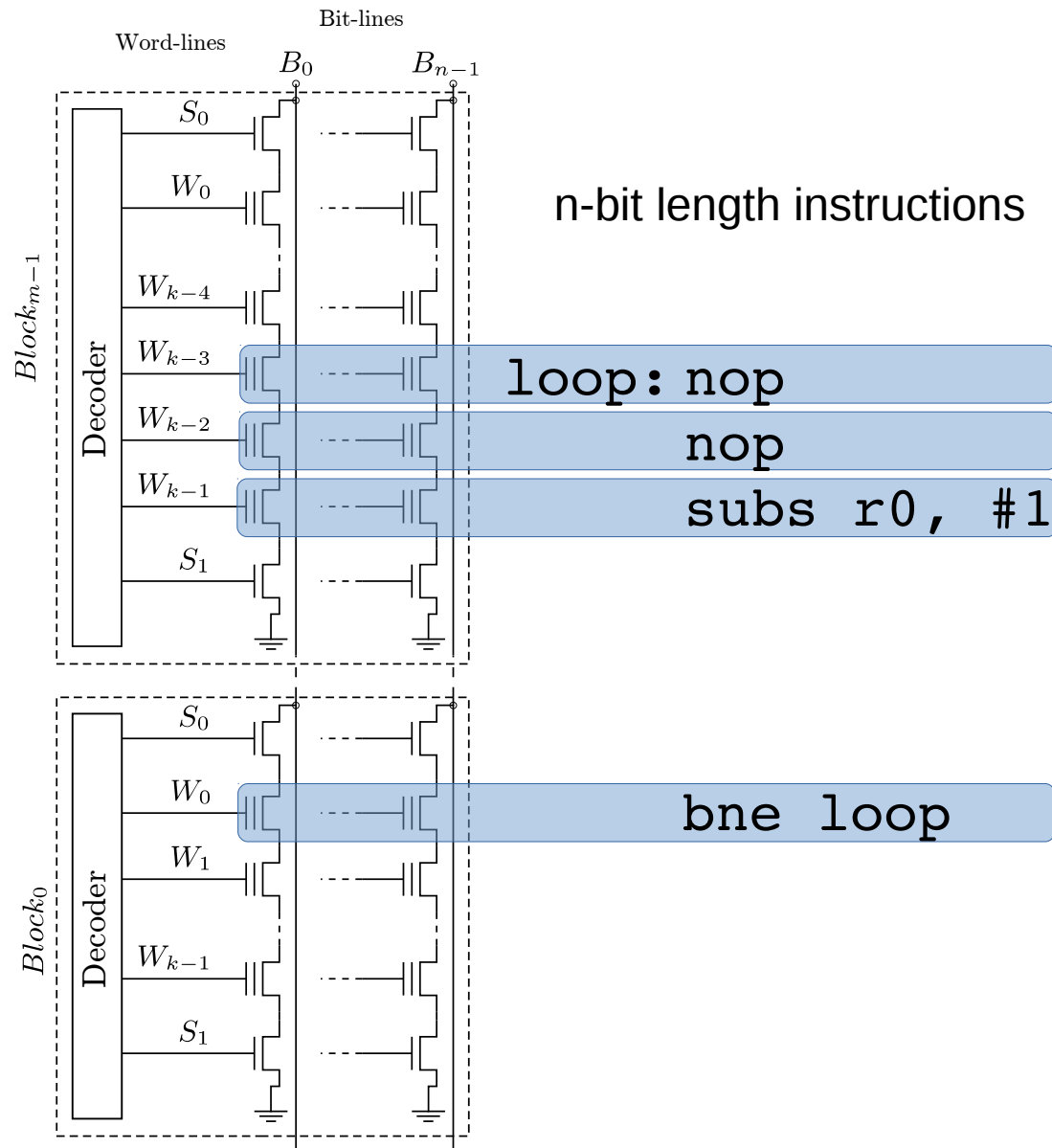
Expected energy effect



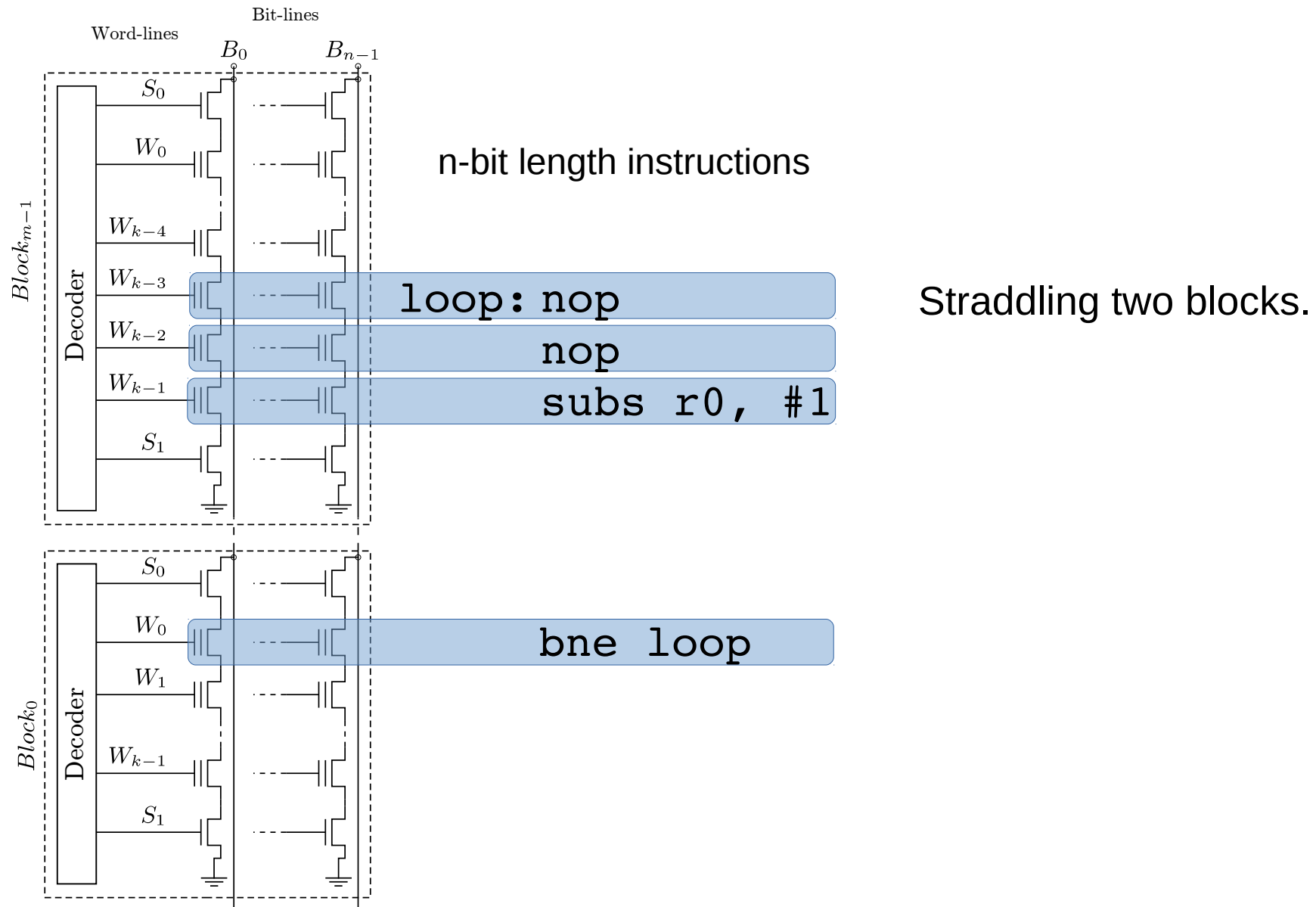
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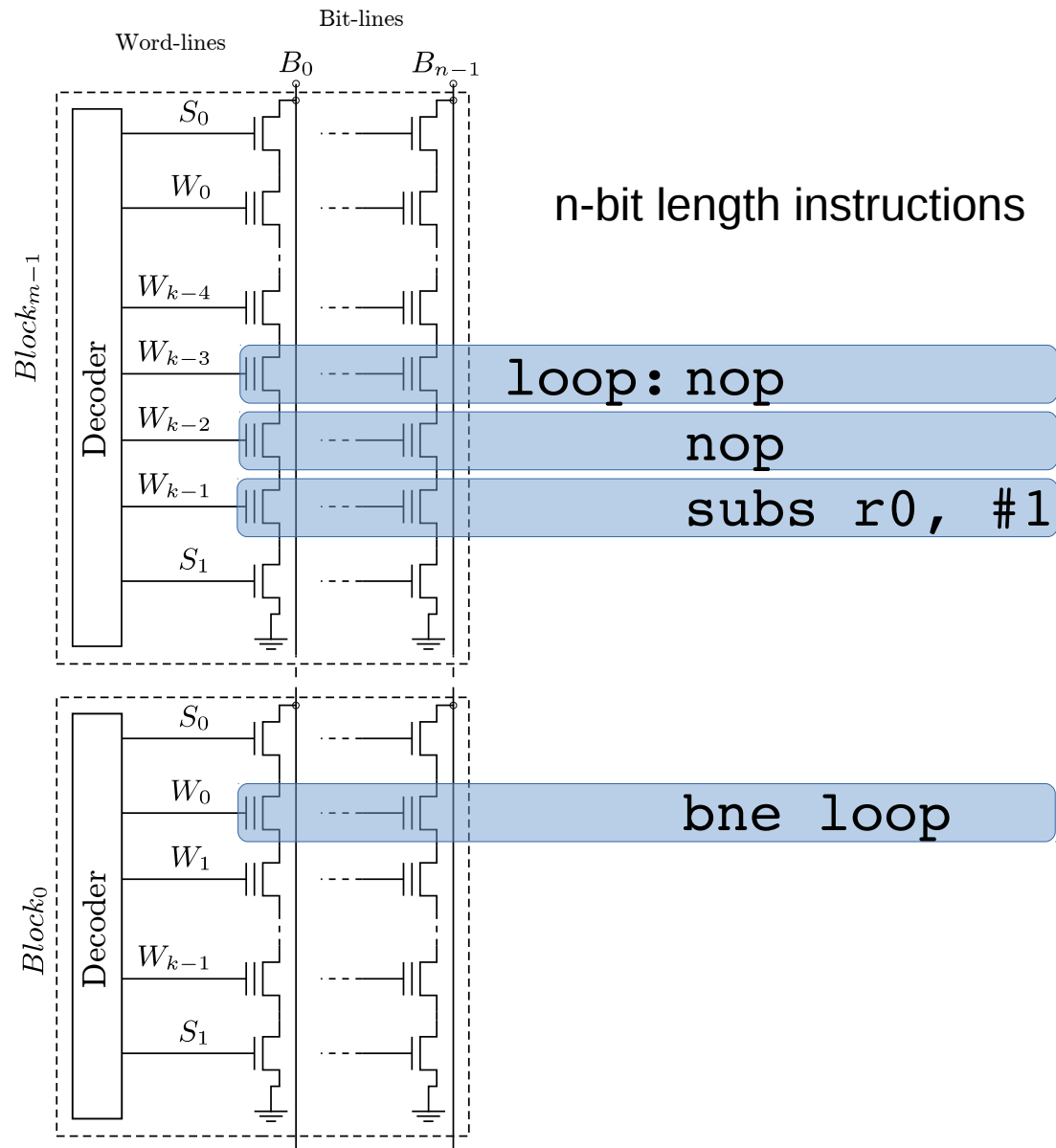
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Expected energy effect



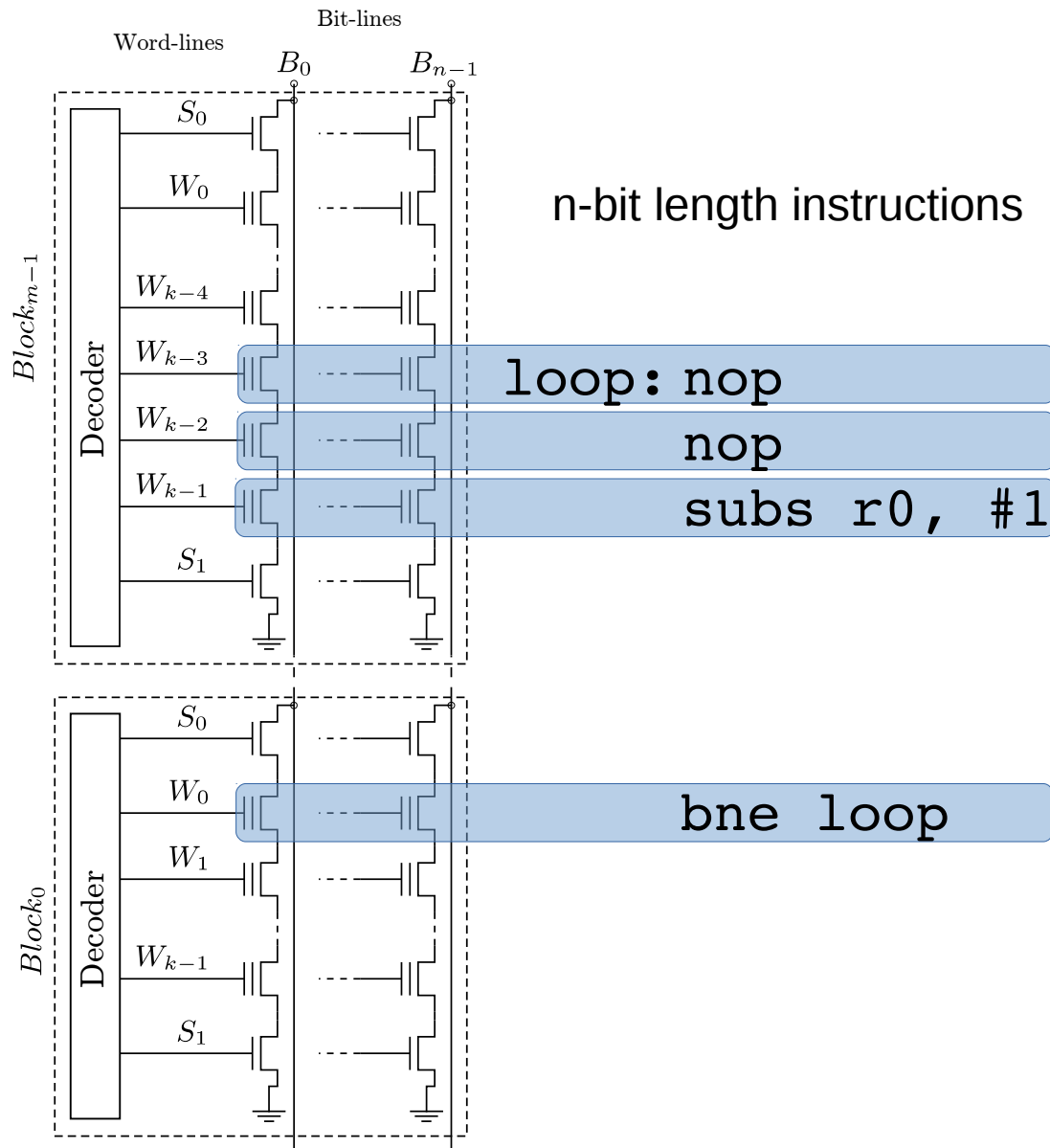
Expected energy effect



Straddling two blocks.

Each iteration must repeatedly power up one, then the other

Expected energy effect

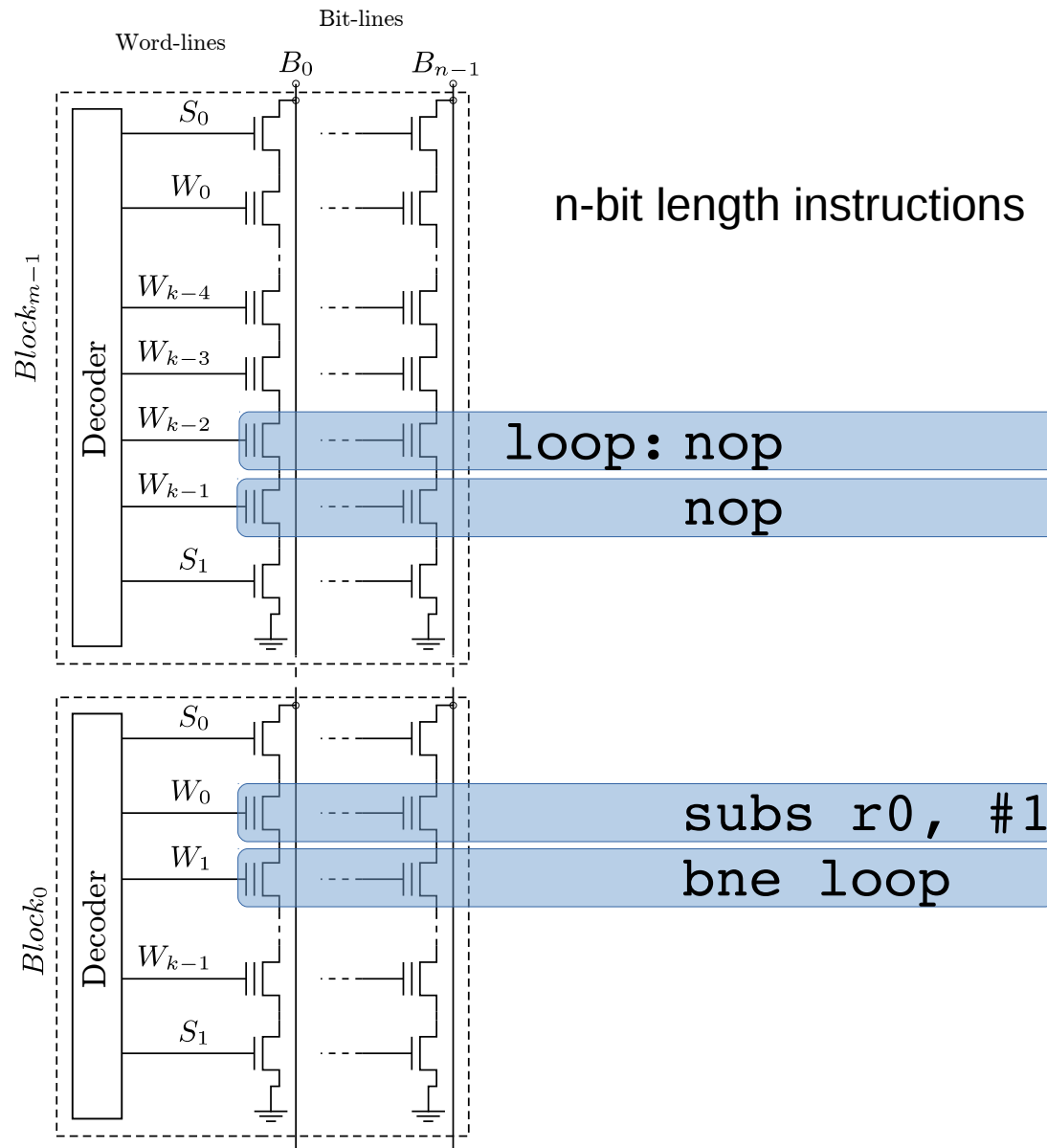


Straddling two blocks.

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Higher energy cost when an instruction jumps from one 'region' to another.

Expected energy effect

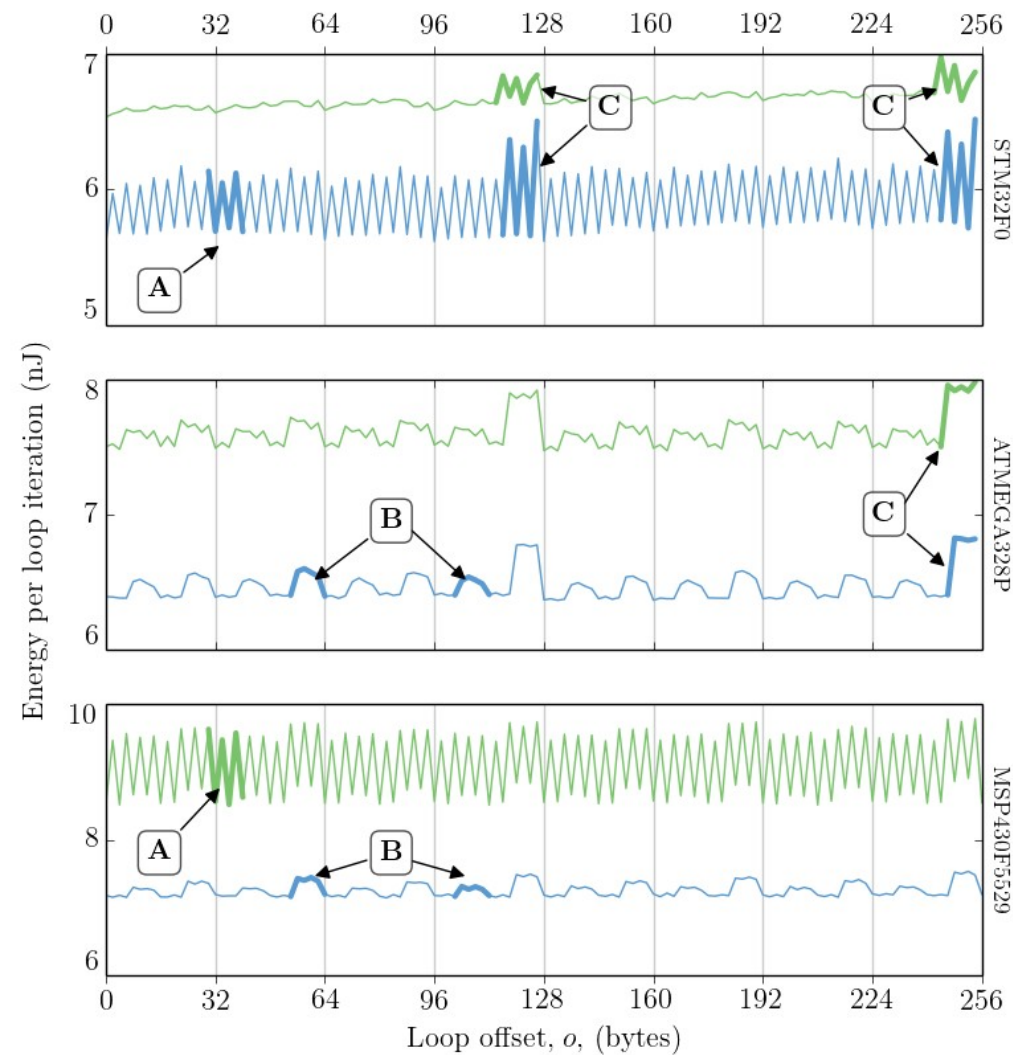


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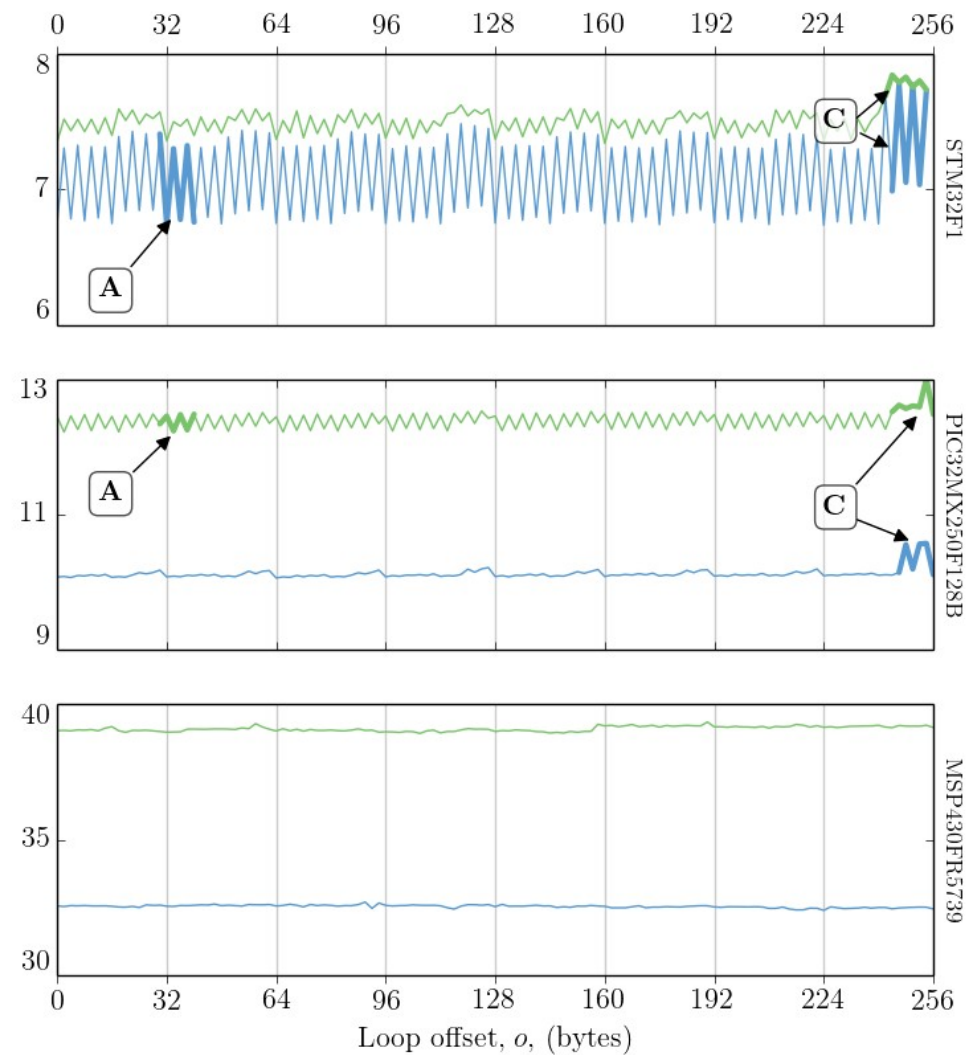
Each iteration must repeatedly power up one, then the other

Higher energy cost when an instruction jumps from one 'region' to another.

Actual results



Bottom line (blue) → 8-byte loop

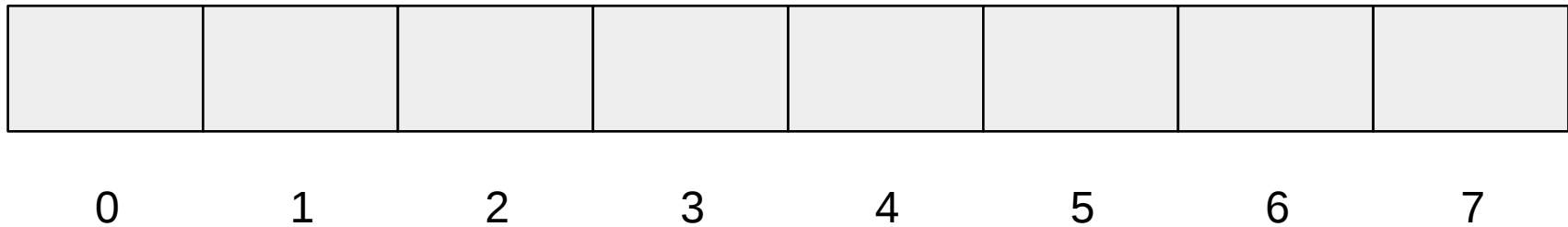


Top line (green) → 10-byte loop

Modelling

Each consecutive memory access has an address dependent energy consumption.

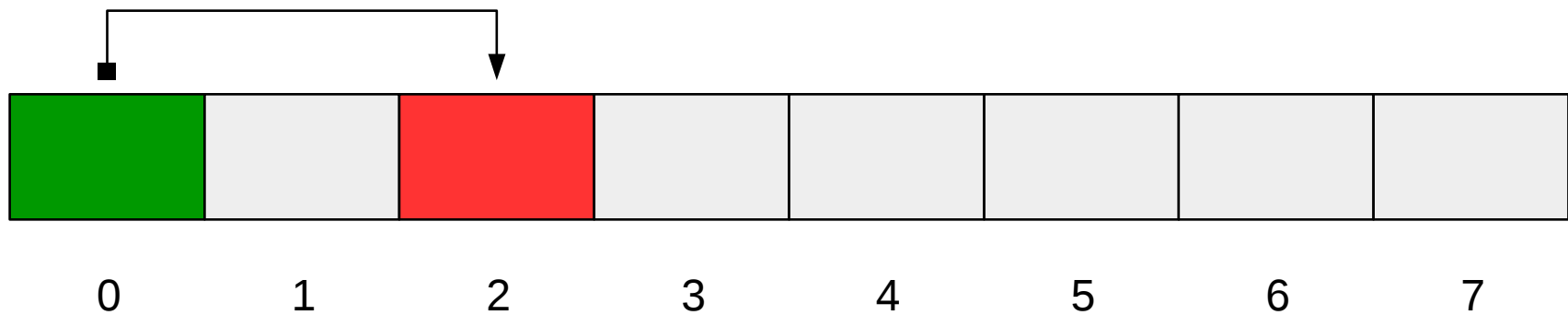
E.g. $0 \rightarrow 2$



Modelling

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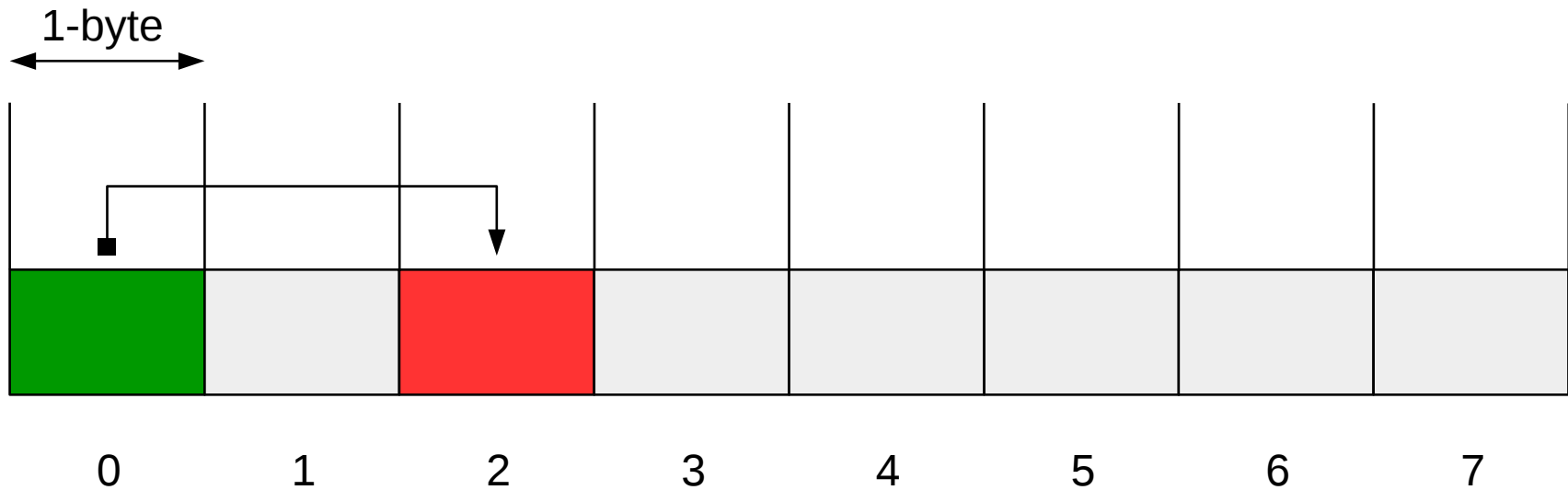
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Modelling

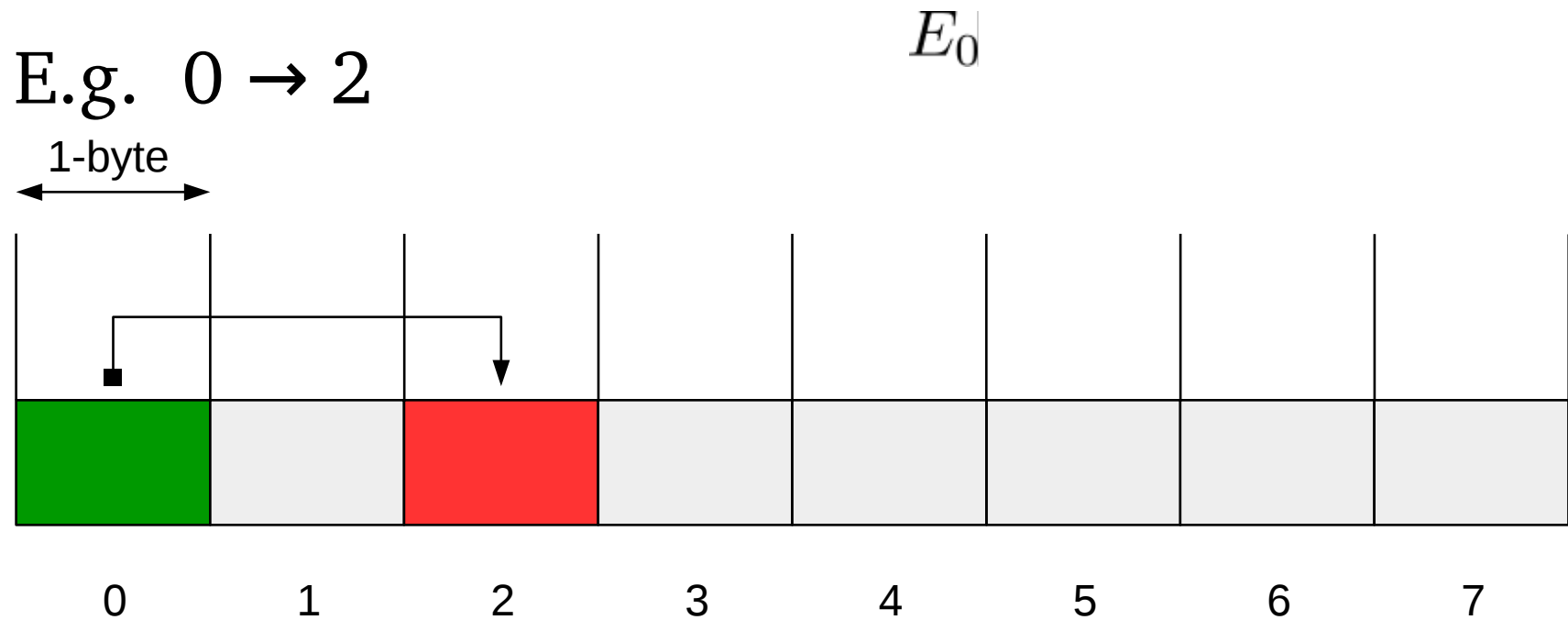
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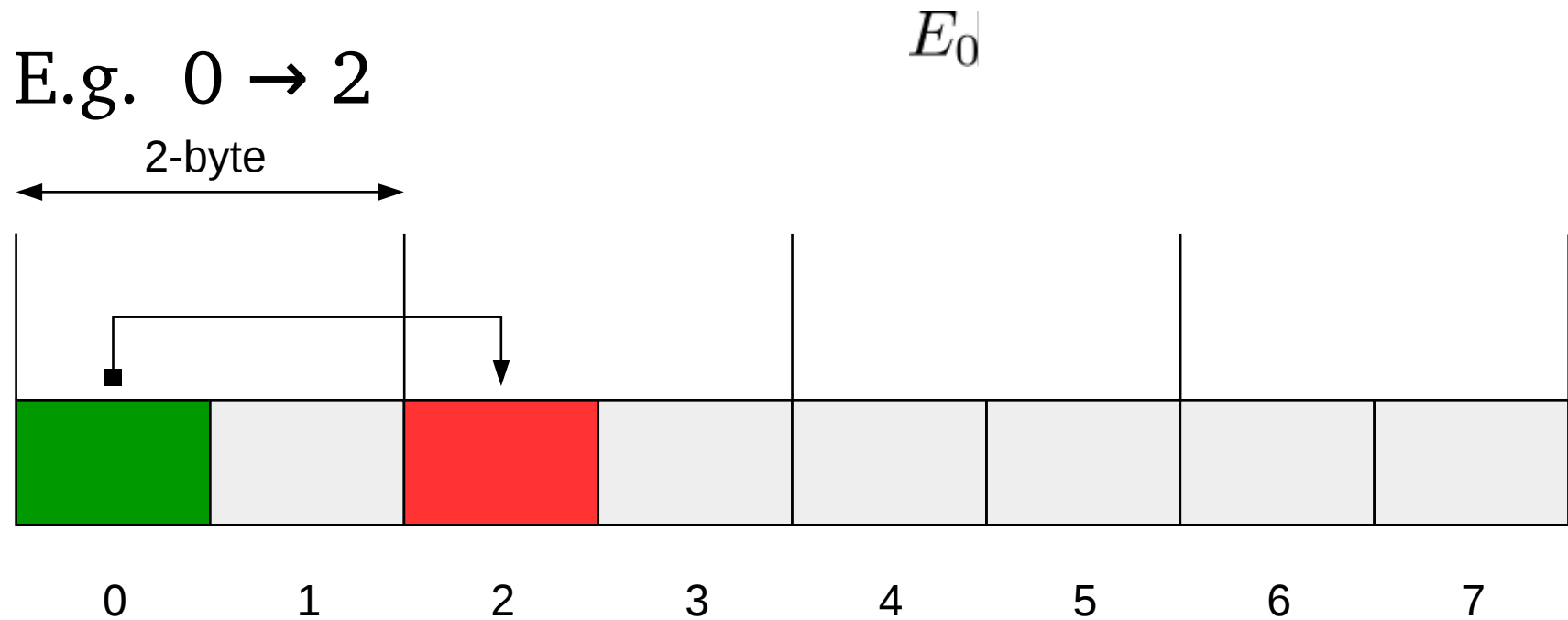
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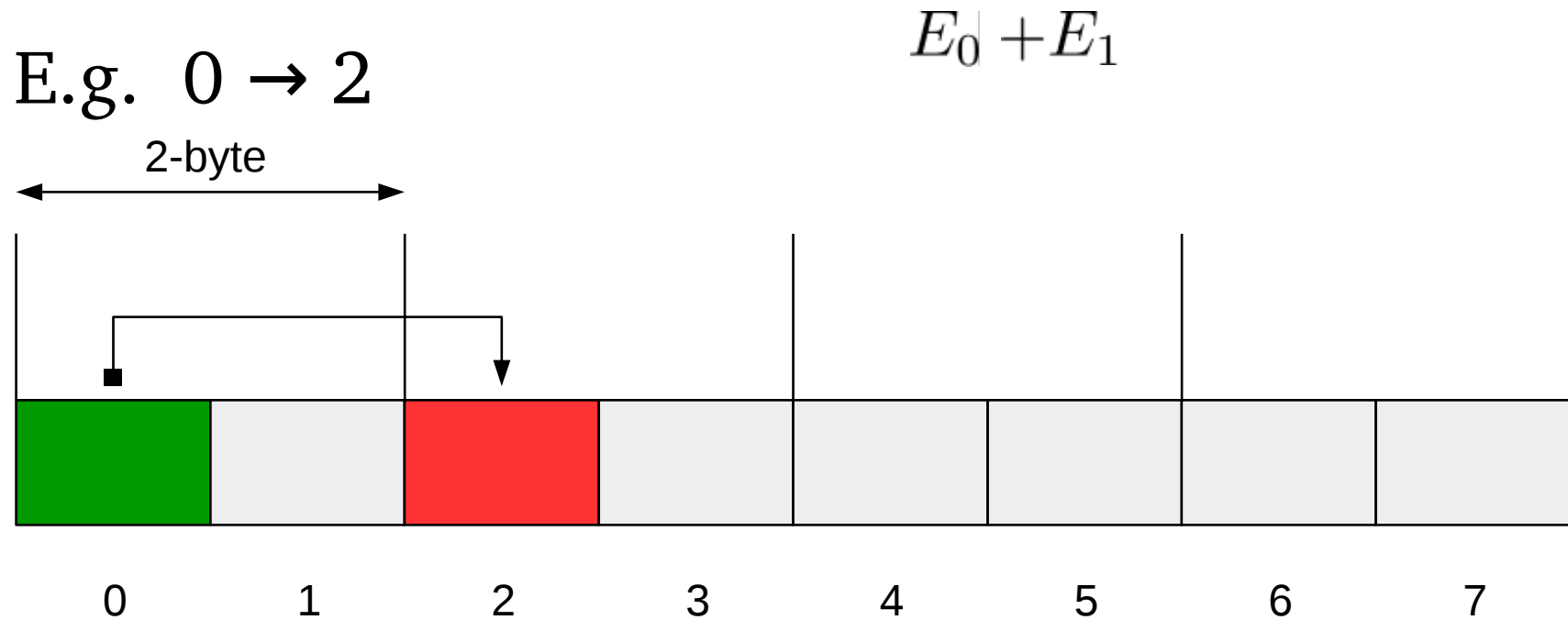
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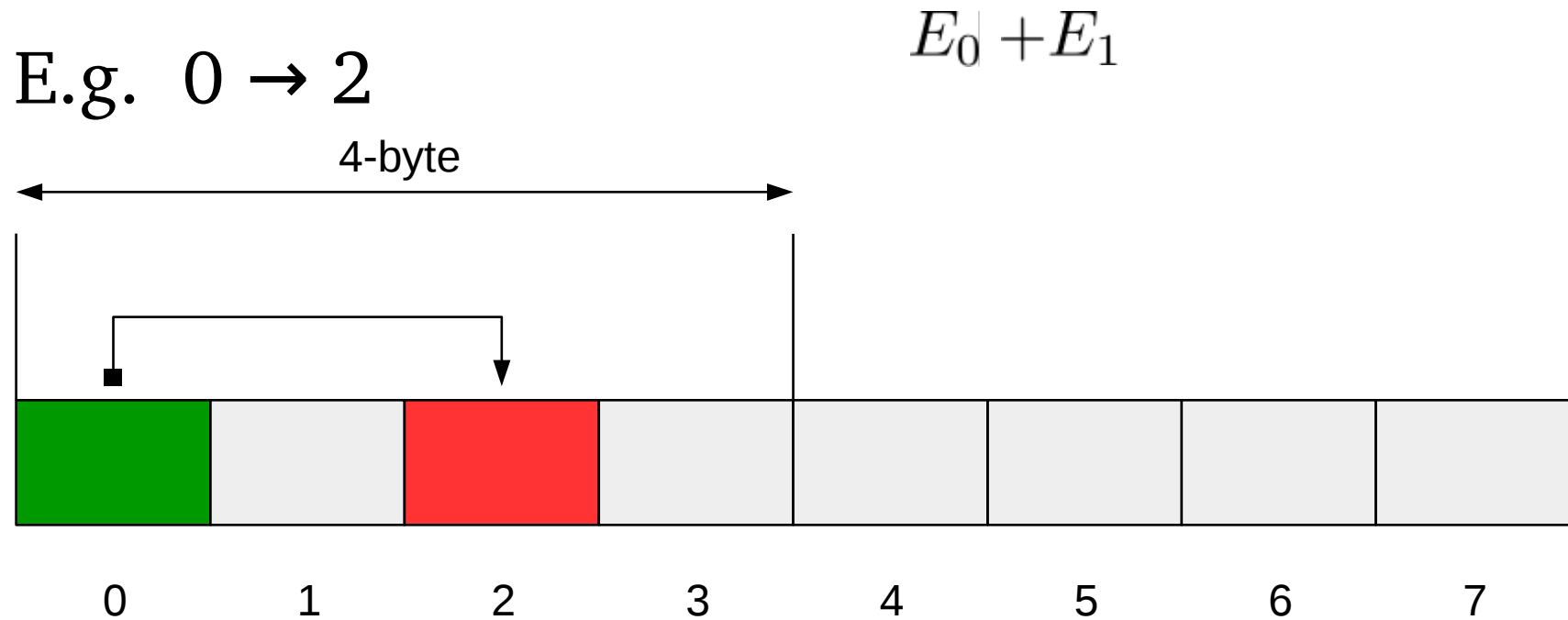
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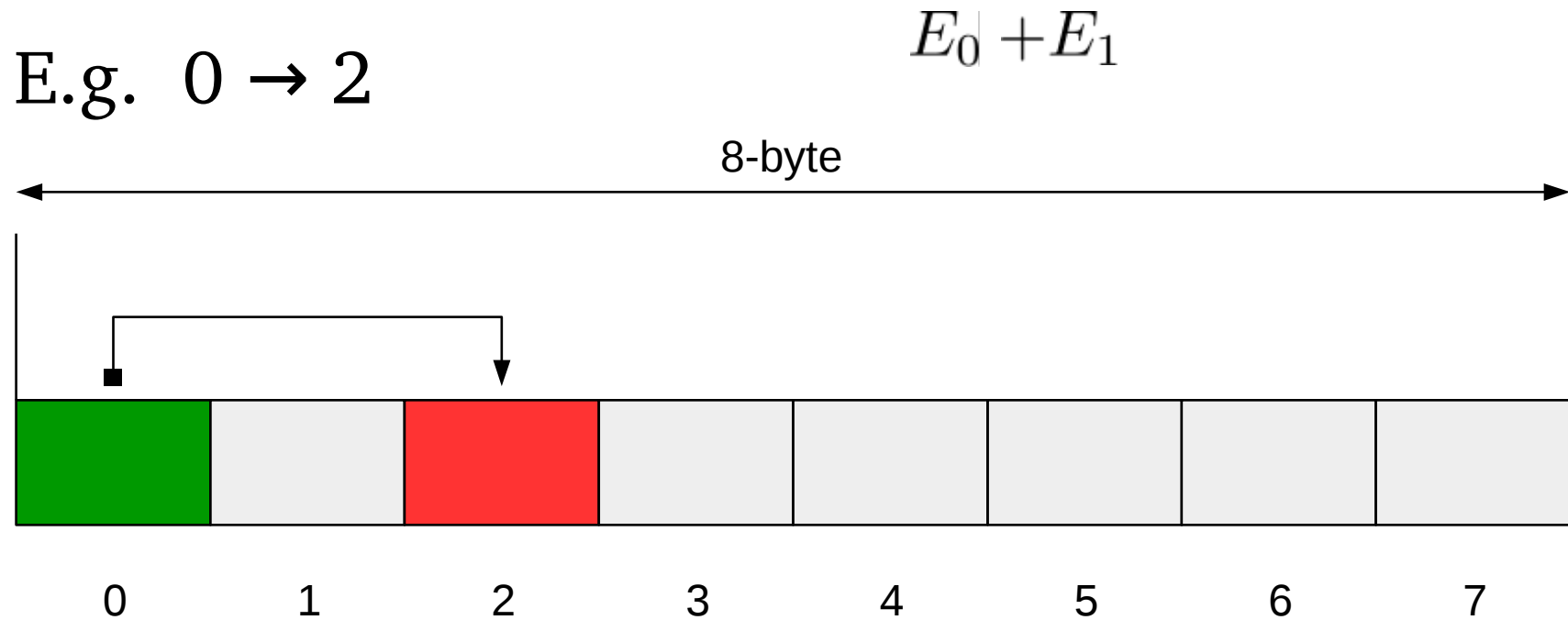
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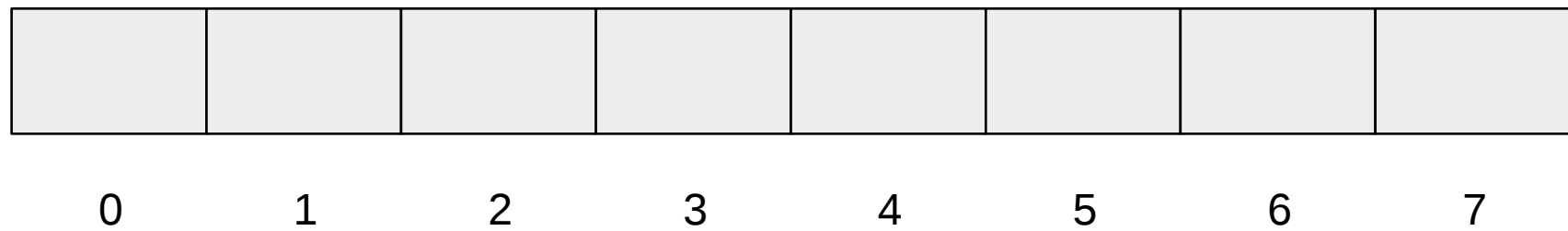
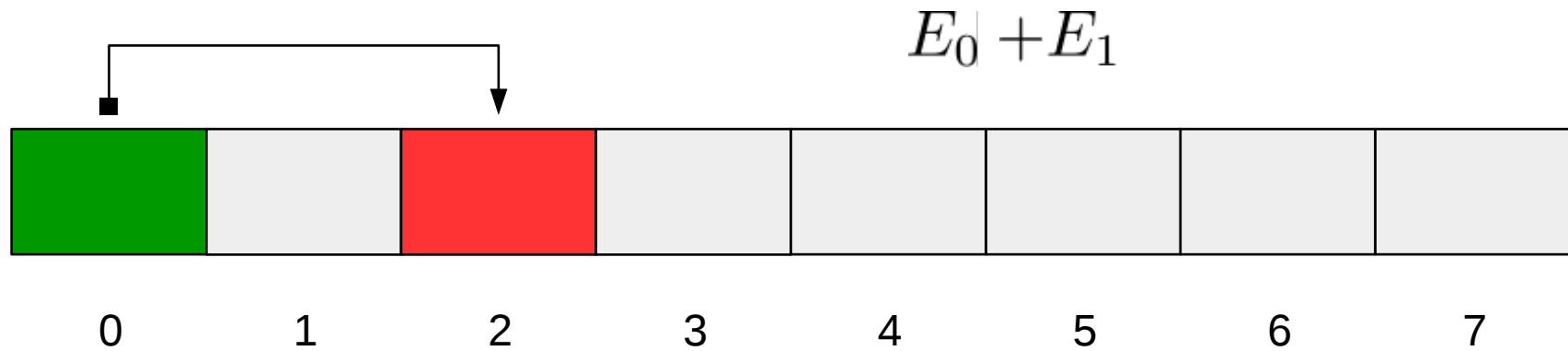


Modelling

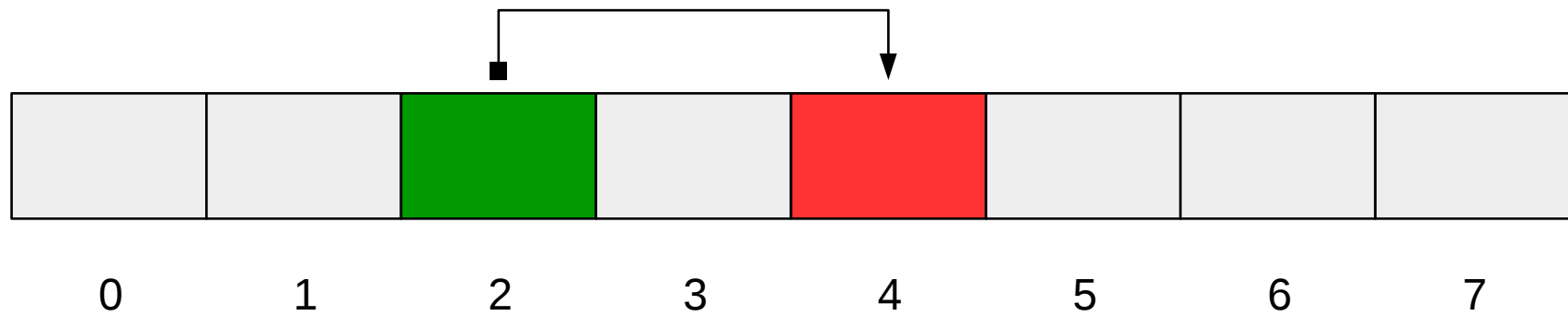
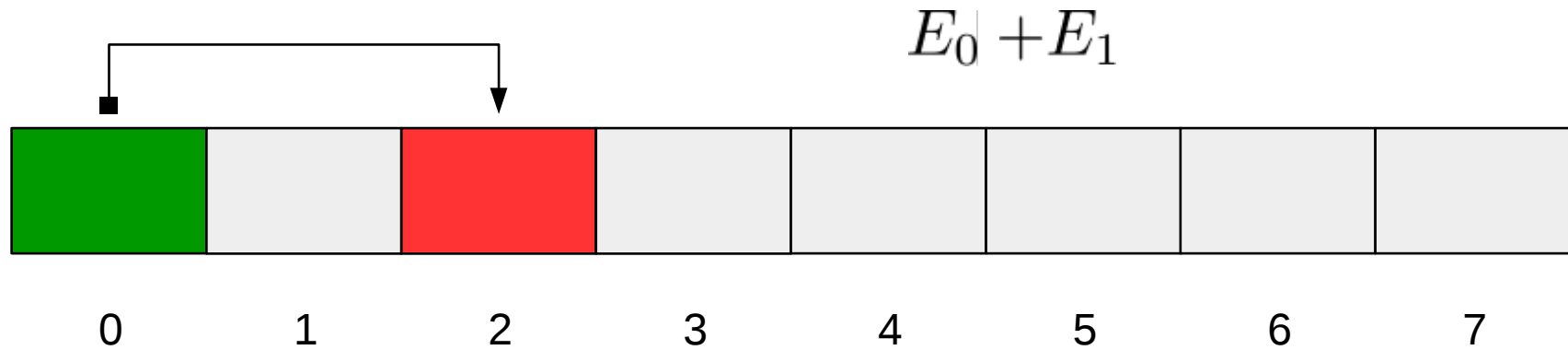
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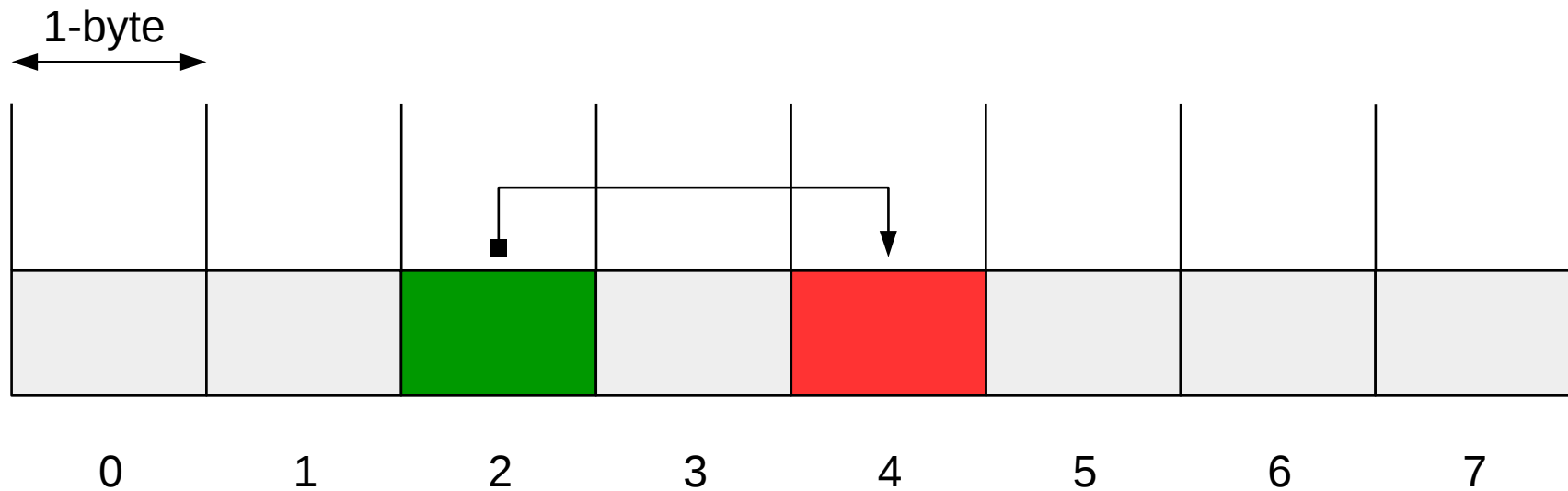
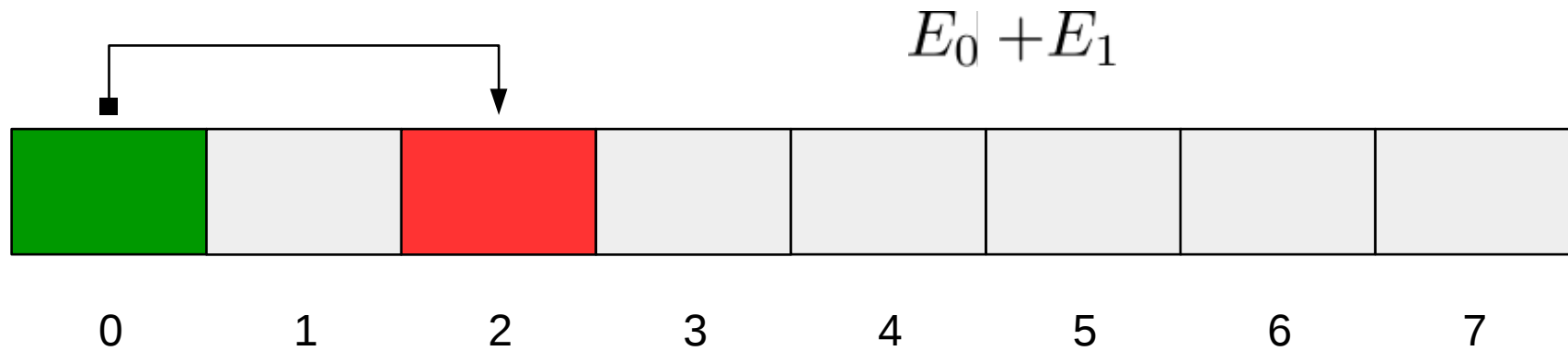
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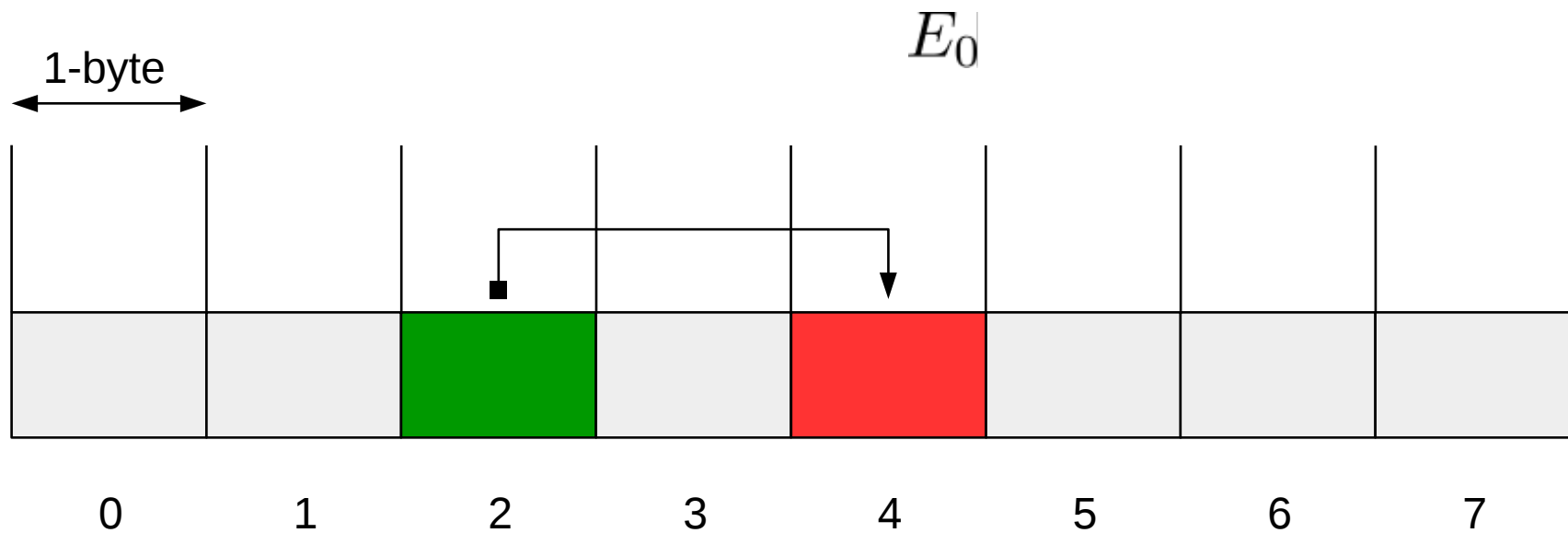
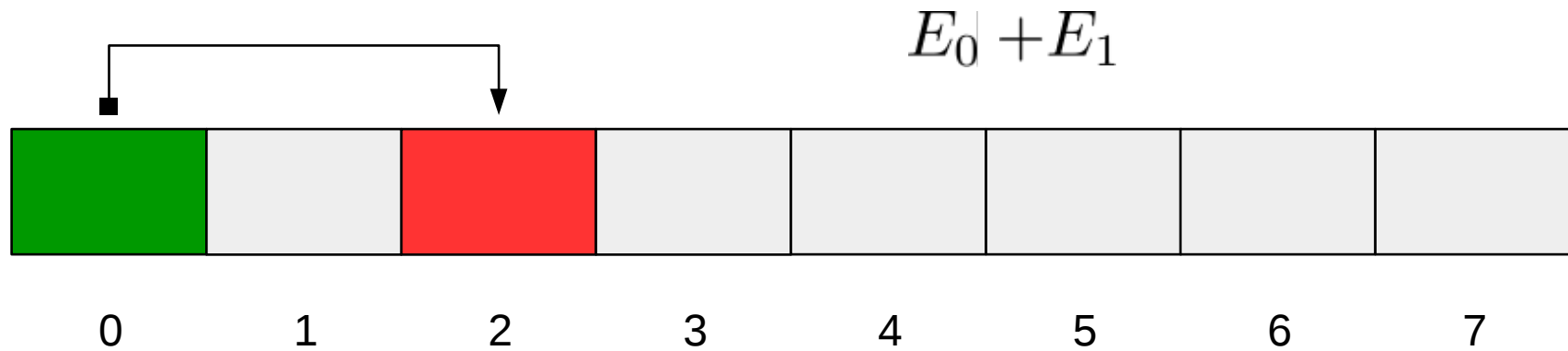
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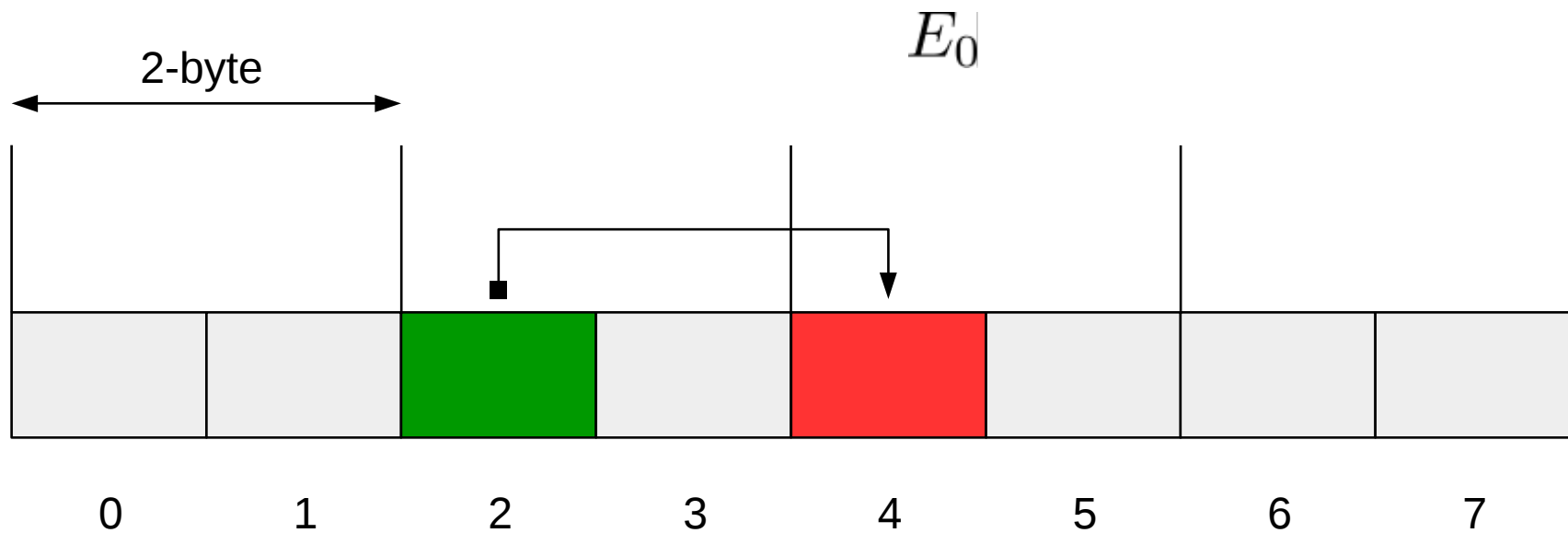
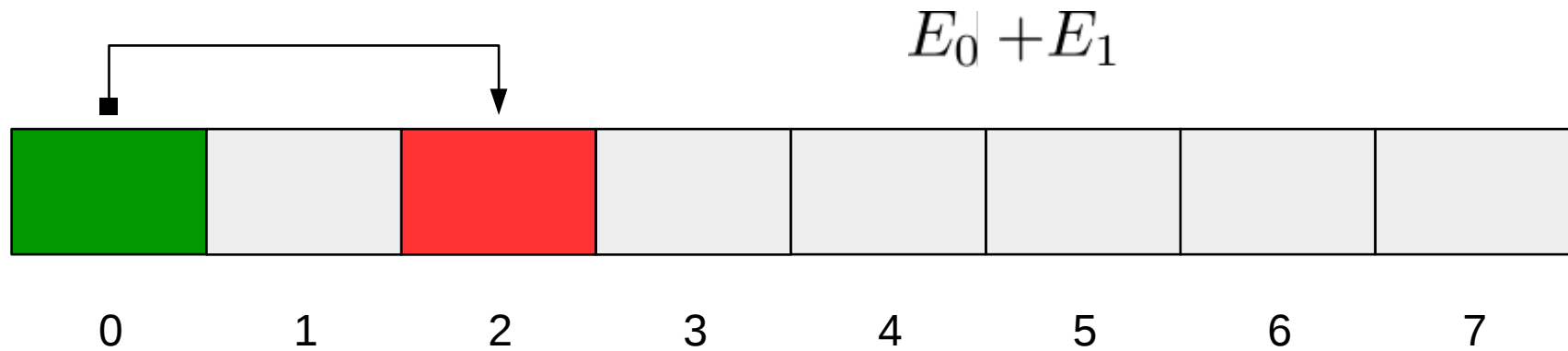
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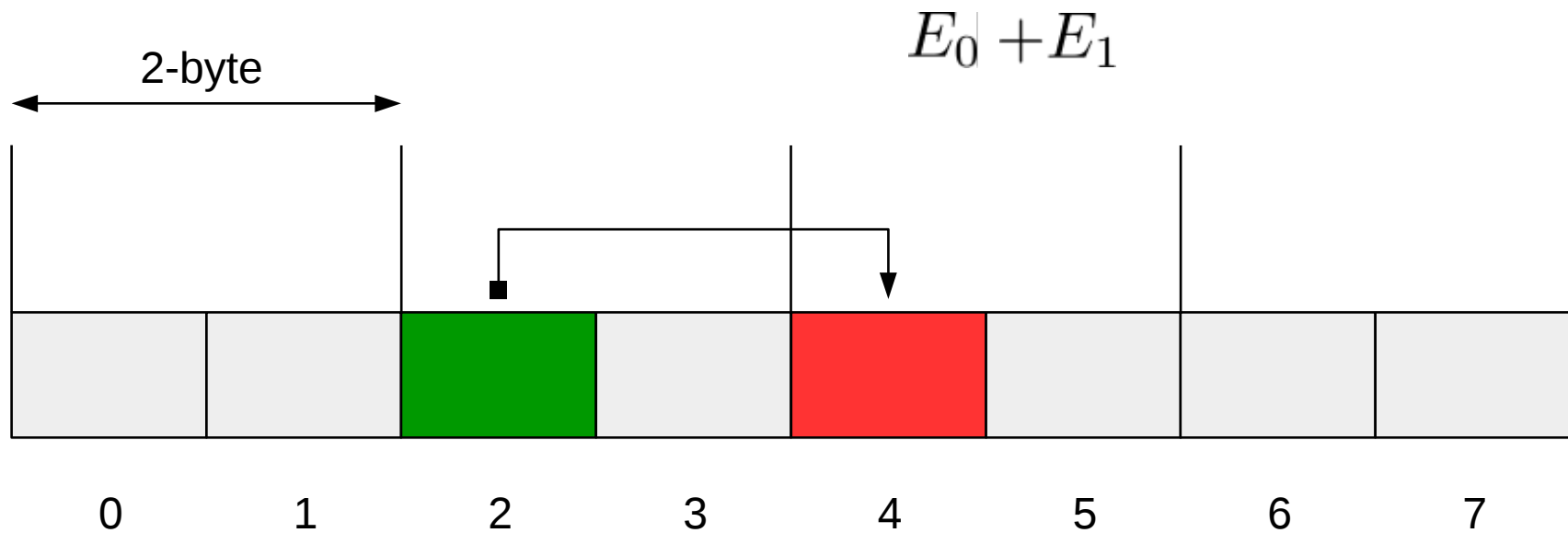
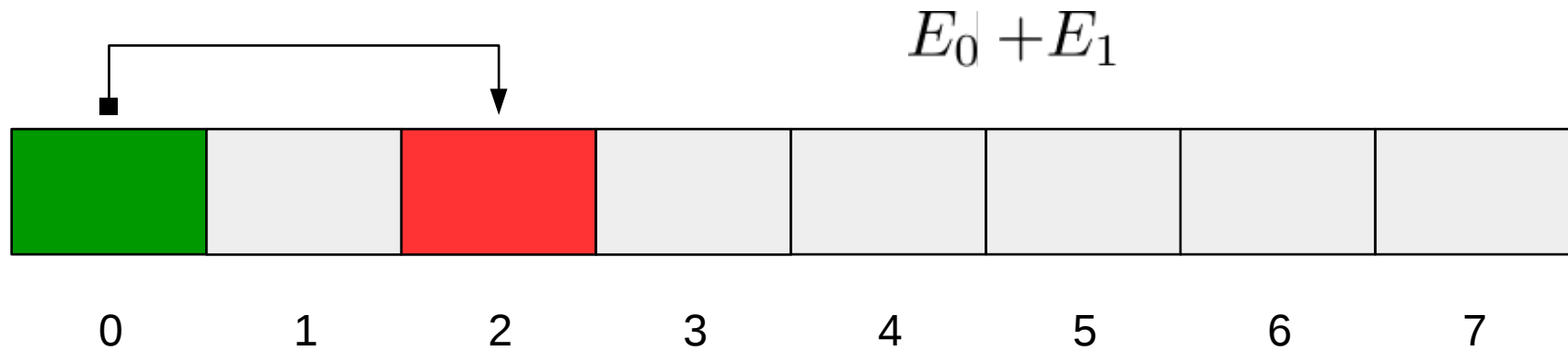
Modelling



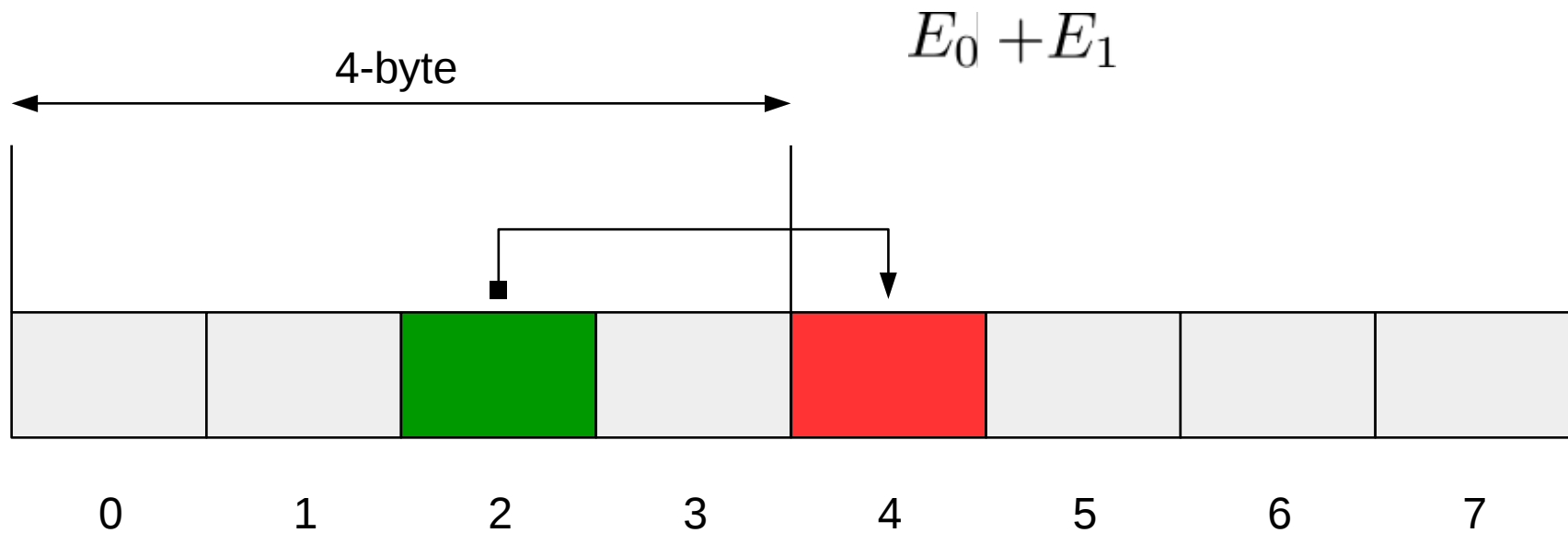
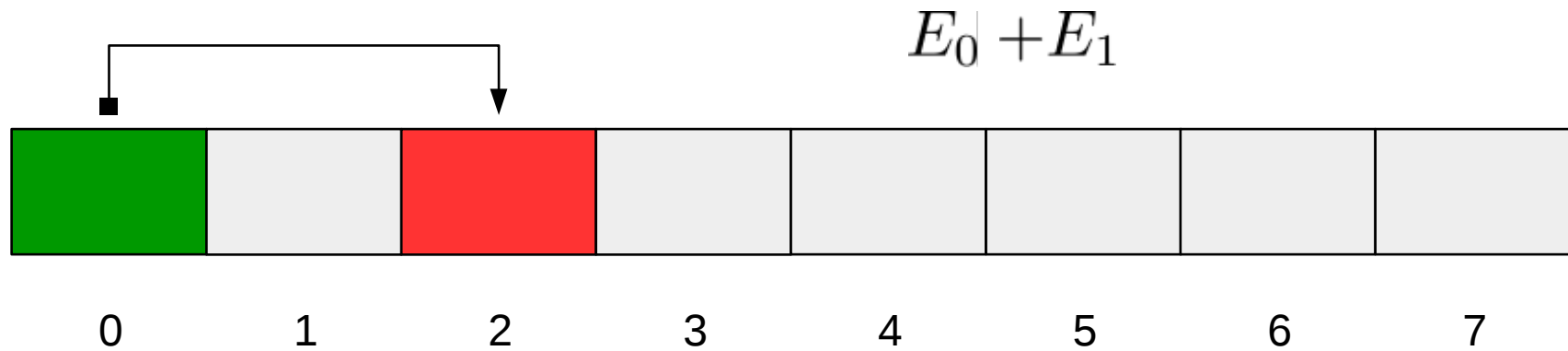
Modelling



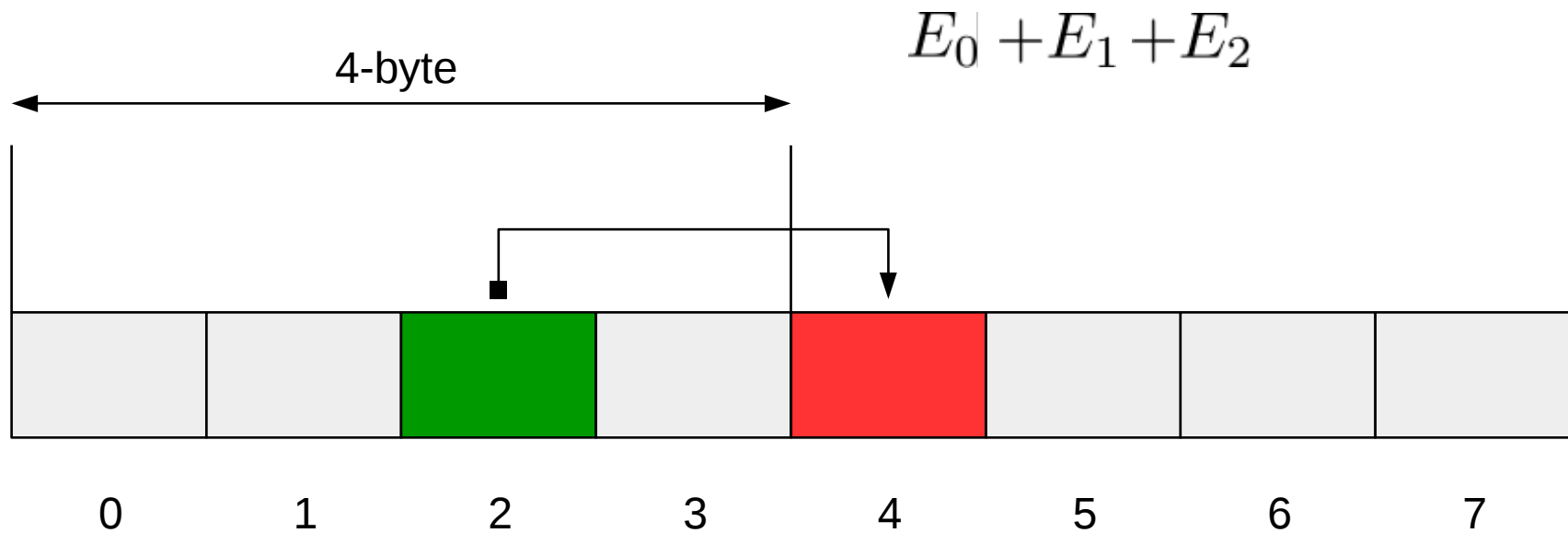
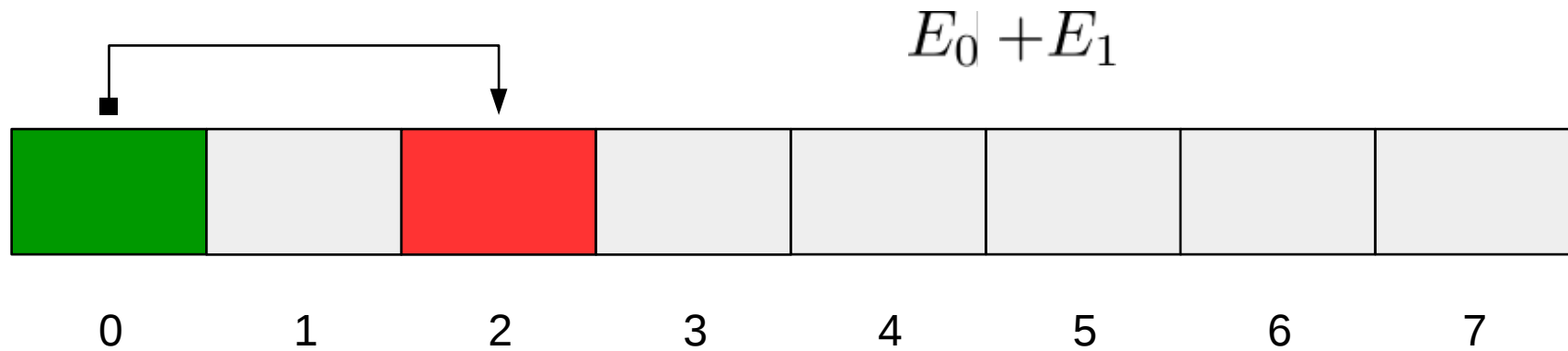
Modelling



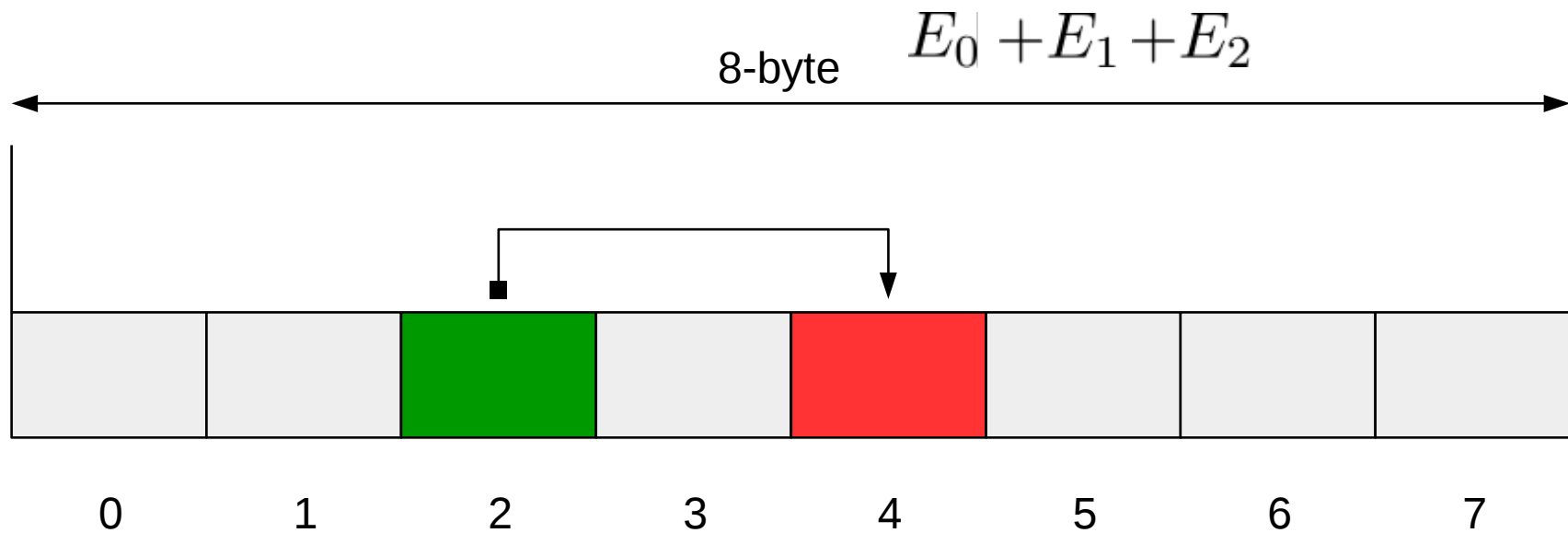
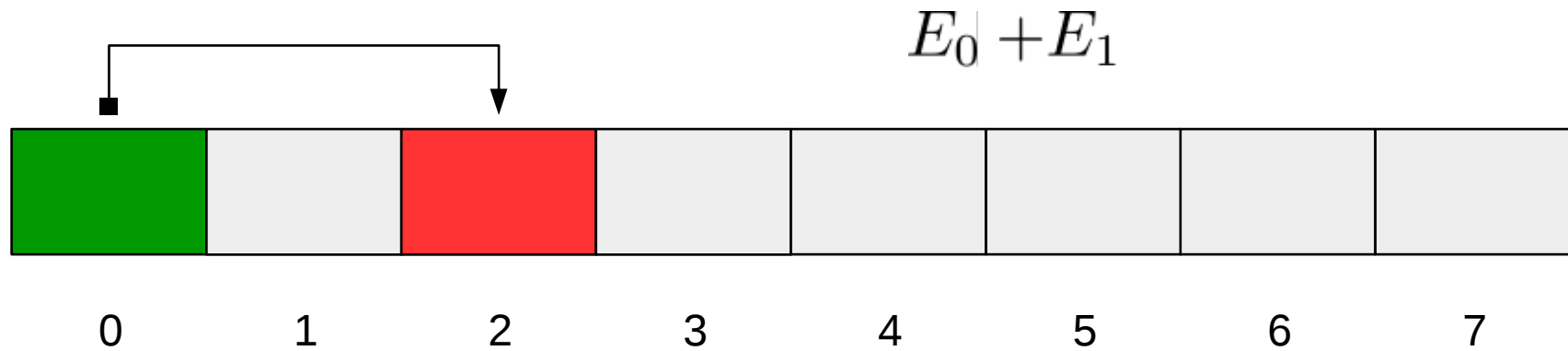
Modelling



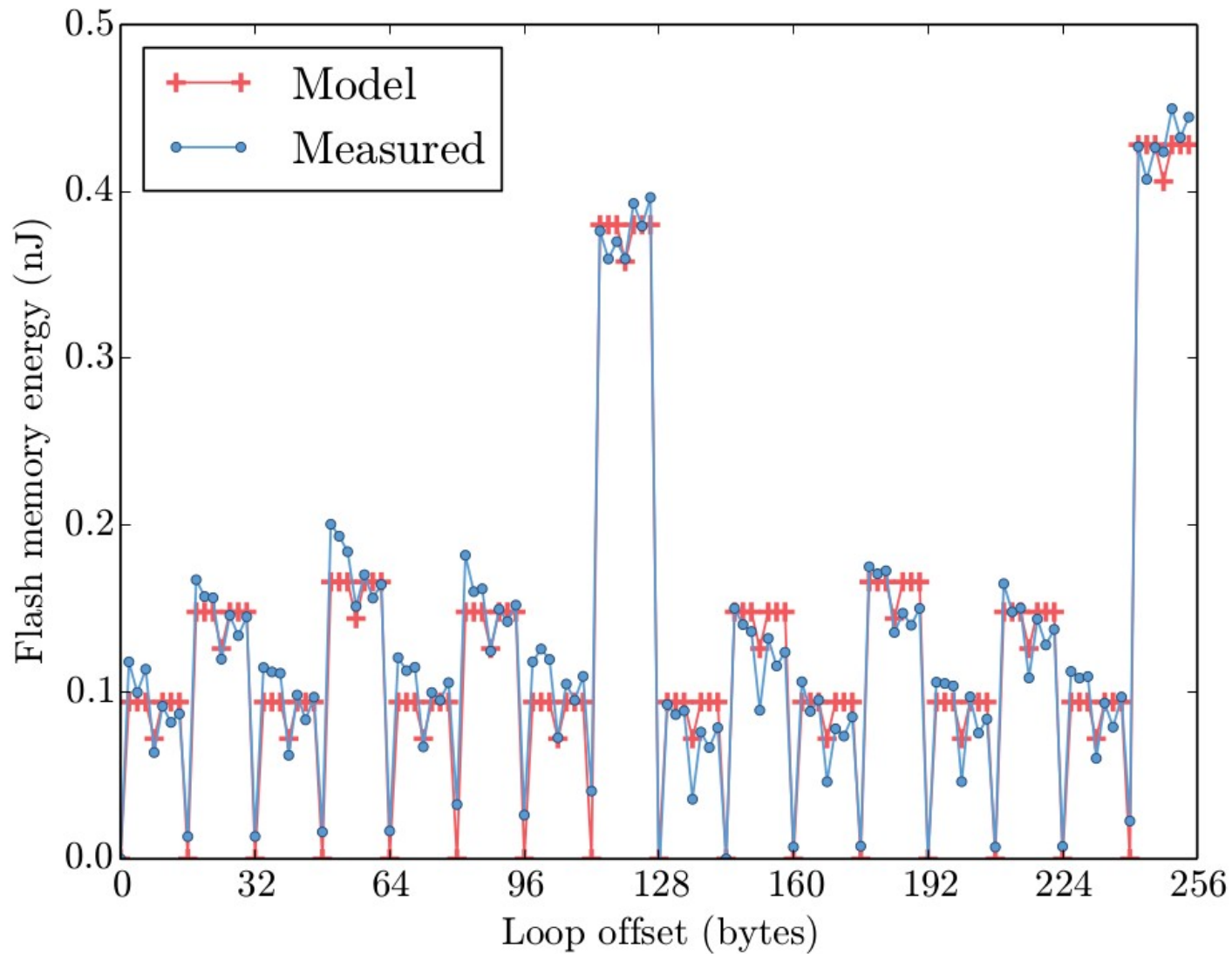
Modelling



Modelling



Cross validation



STM32F0

A potential optimisation

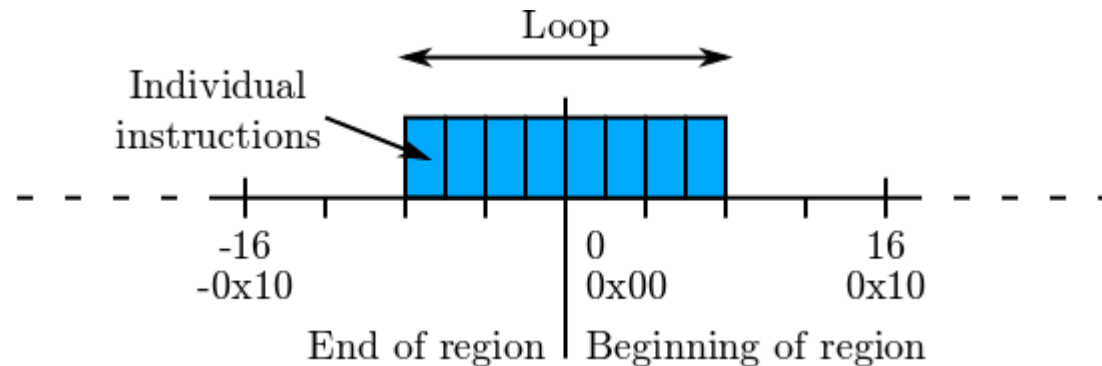
For code which is executed frequently, ensure it crosses as few costly boundaries as possible.

Use the model to make these decisions.

A potential optimisation

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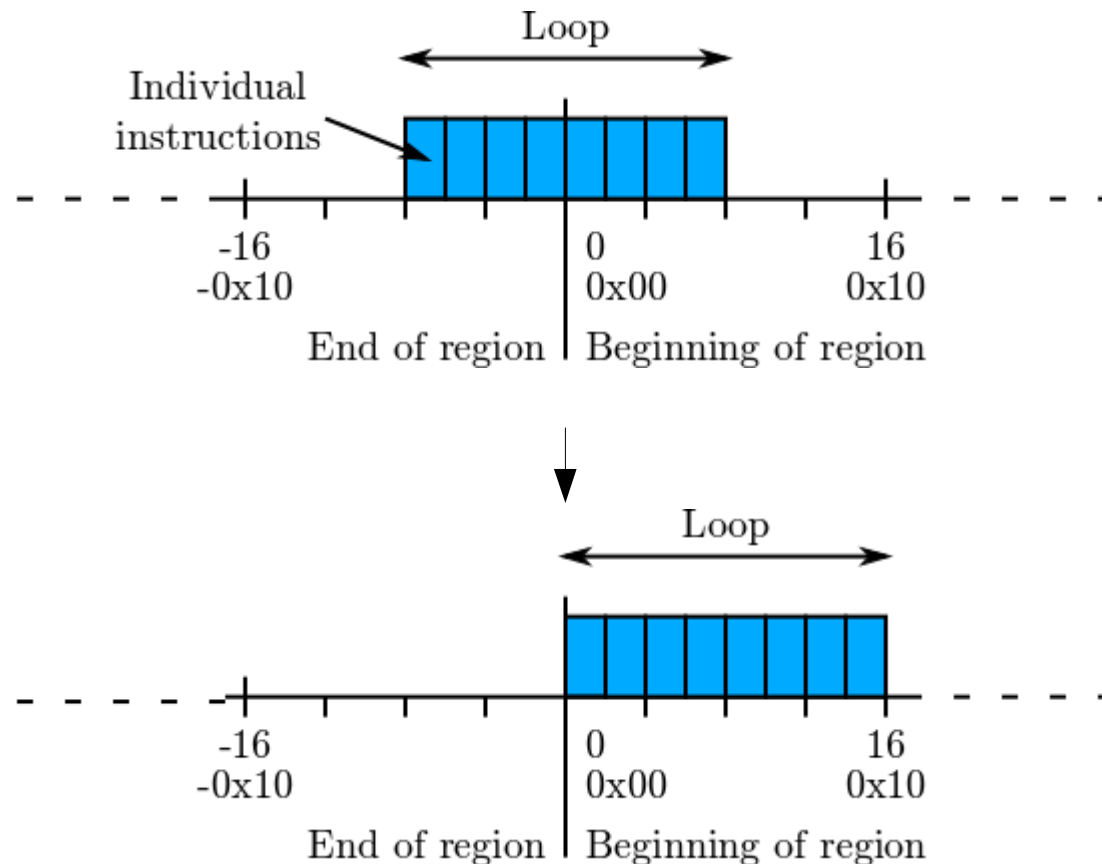
Use the model to make these decisions.



A potential optimisation

For code which is executed frequently, ensure it crosses as few costly boundaries as possible.

Use the model to make these decisions.



A potential optimisation

Unfortunately it doesn't save energy

Overhead of aligning loops outweighs the potential benefit

- Many boundary crossings are necessary
- Smaller boundary crossings happen more frequently

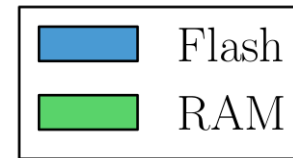
More sophisticated implementation may be able to save energy

Flash or RAM



Flash or RAM

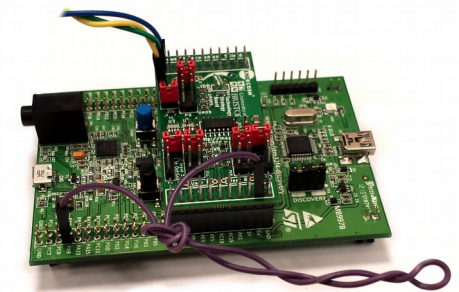
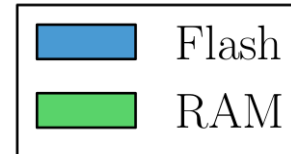
Execute instructions from



Flash or RAM

Execute instructions from

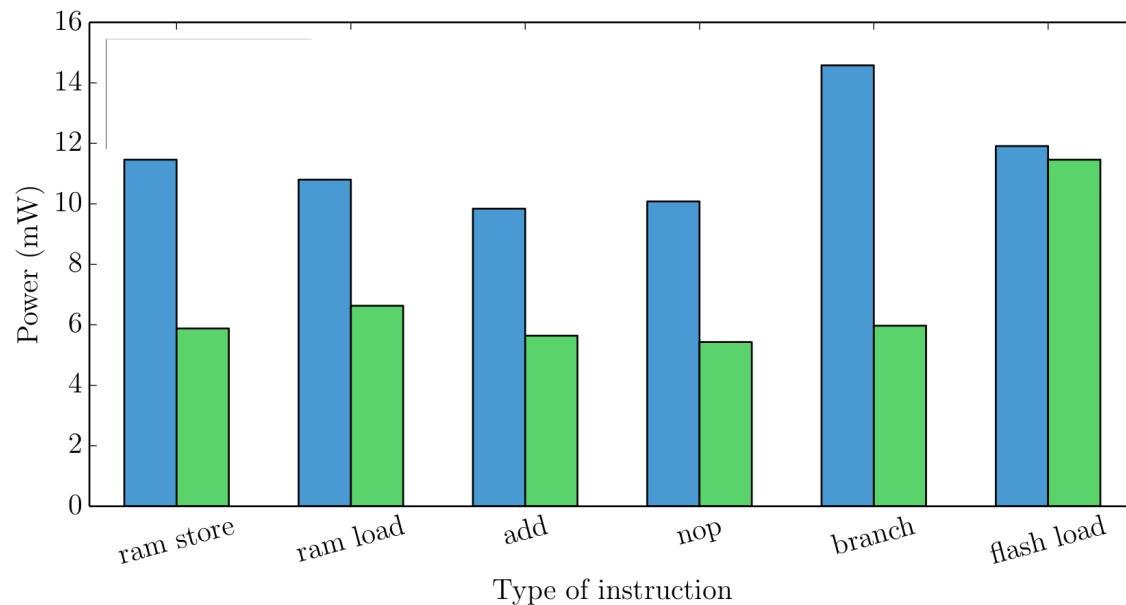
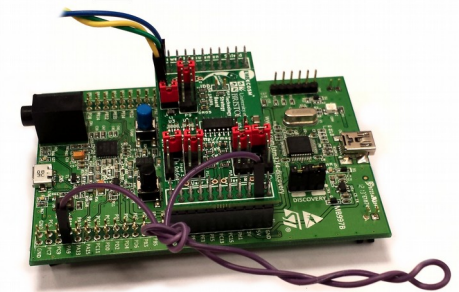
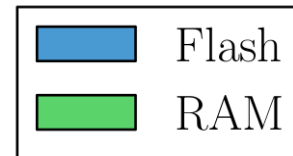
Measure the power dissipation



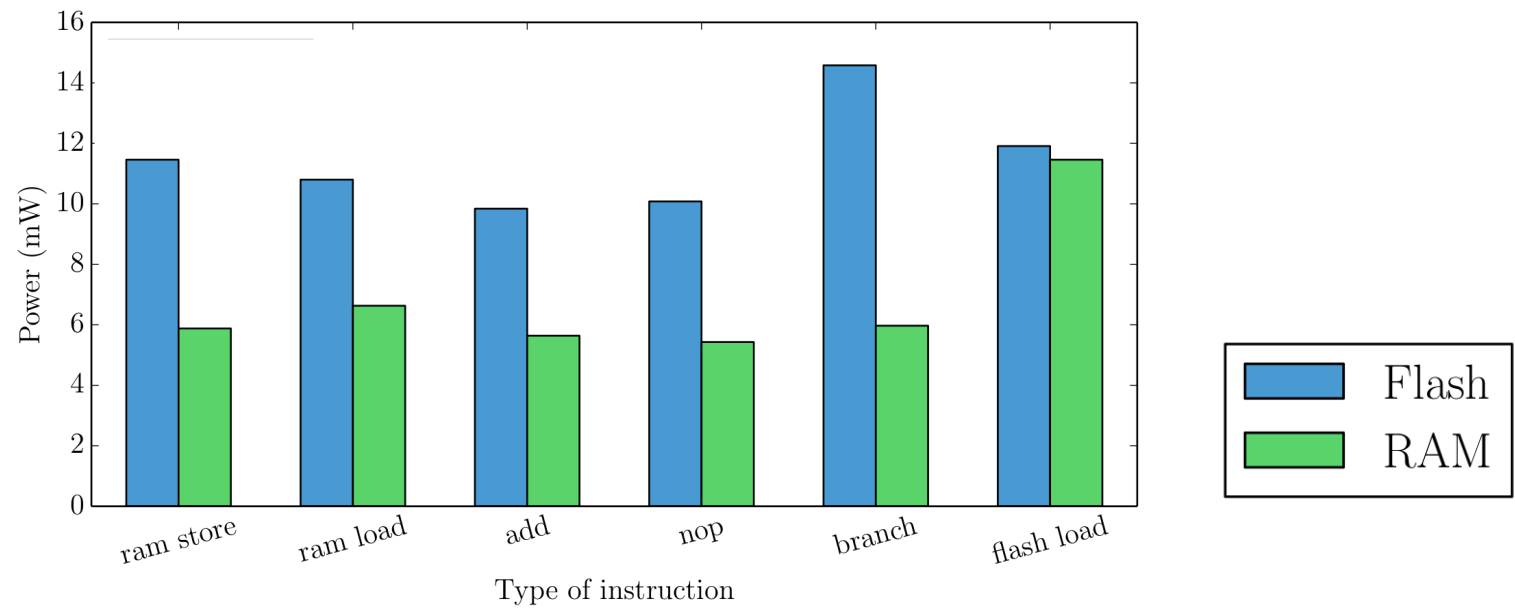
Flash or RAM

Execute instructions from

Measure the power dissipation

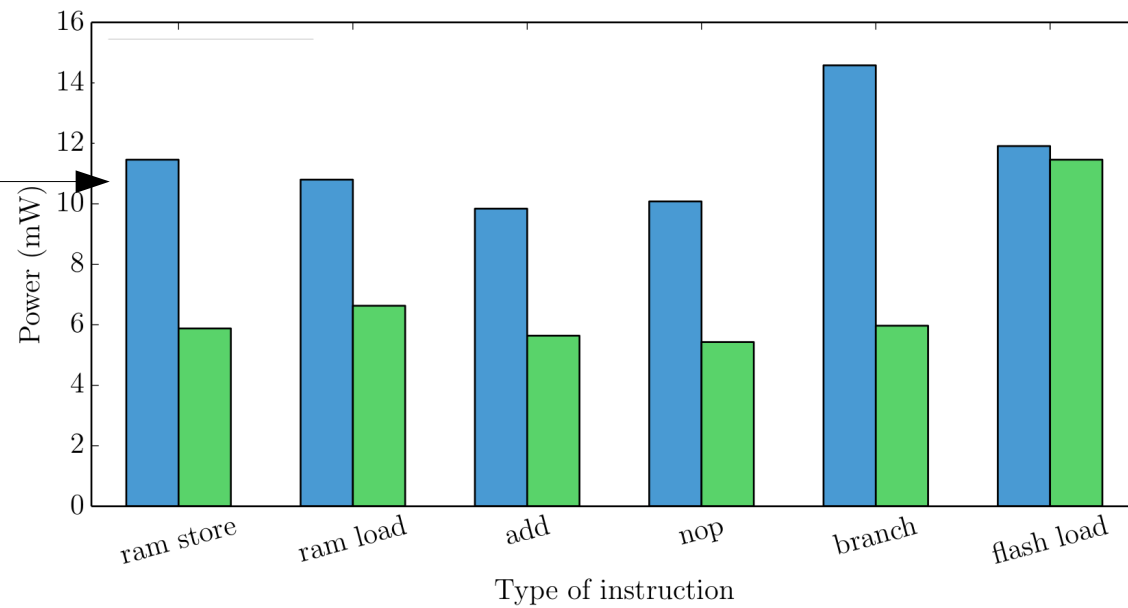


Flash or RAM



Flash or RAM

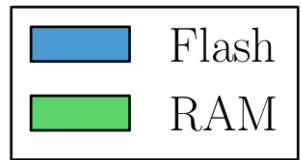
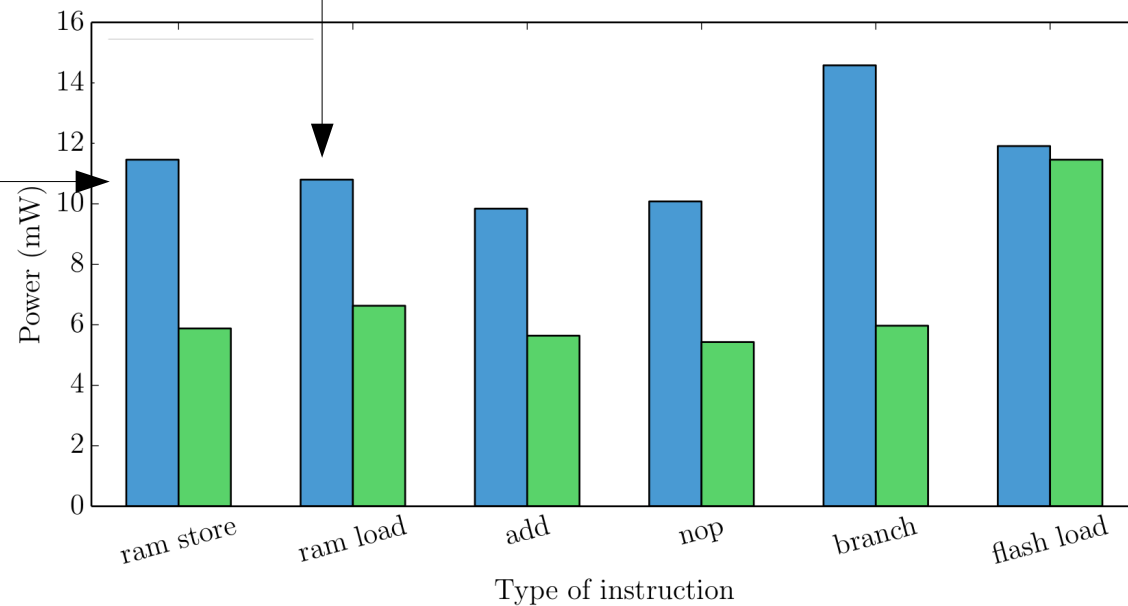
```
; r1 in RAM  
str r0, [r1]
```



Flash or RAM

```
; r1 in RAM  
str r0, [r1]
```

```
; r1 in RAM  
ldr r0, [r1]
```

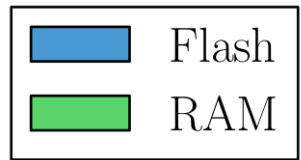
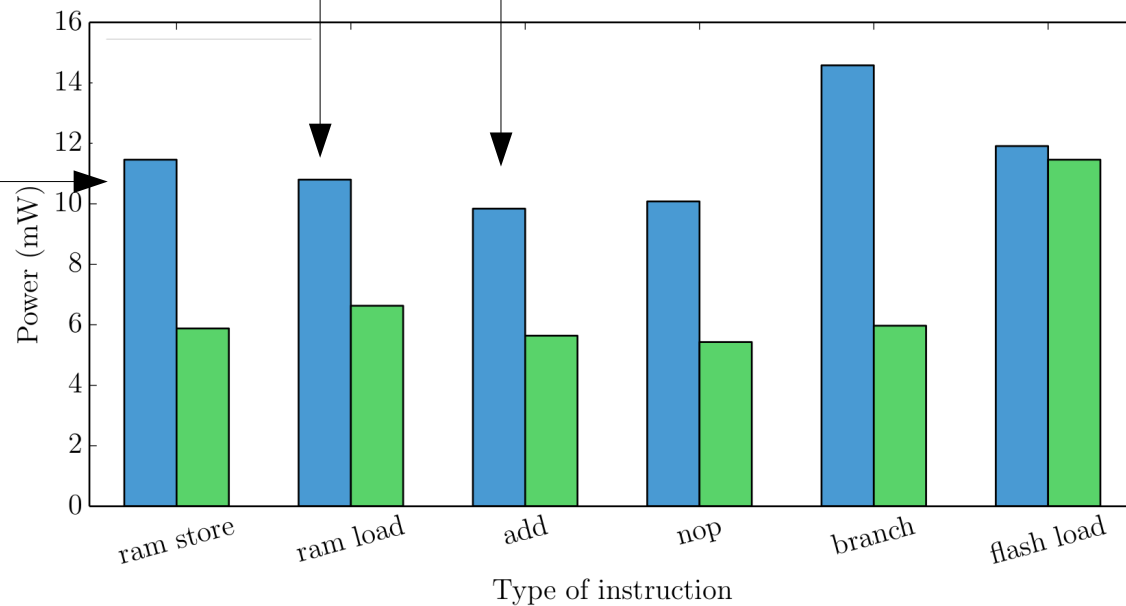


Flash or RAM

```
; r1 in RAM  
str r0, [r1]
```

```
add r0, r1
```

```
; r1 in RAM  
ldr r0, [r1]
```



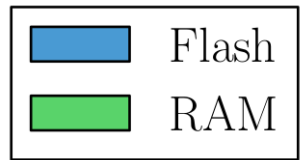
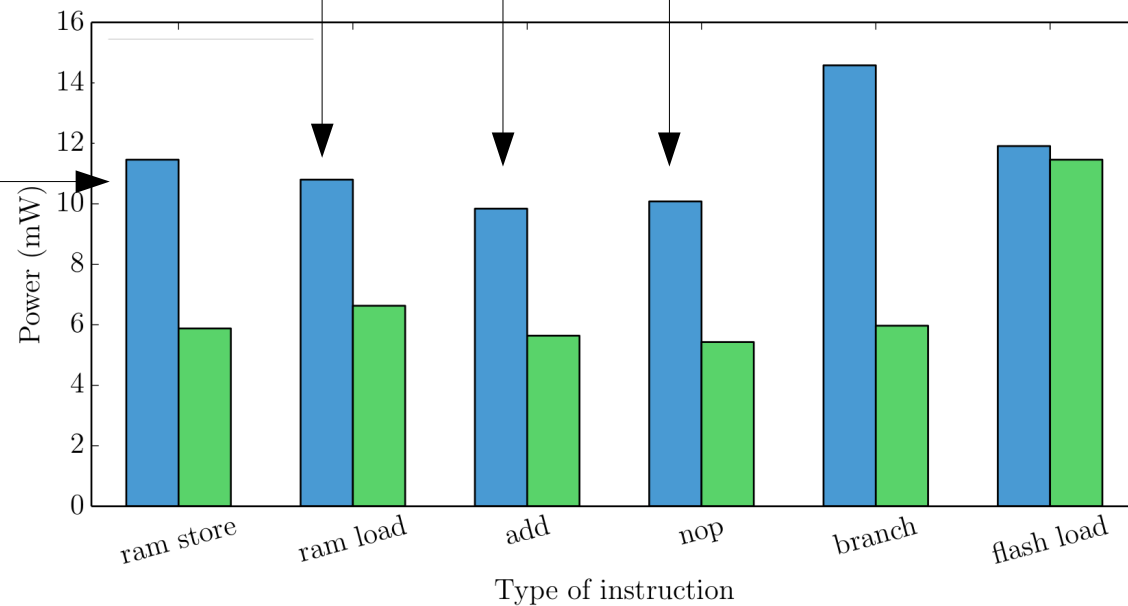
Flash or RAM

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add r0, r1
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; r1 in RAM  
ldr r0, [r1]
```

```
nop
```



Flash or RAM

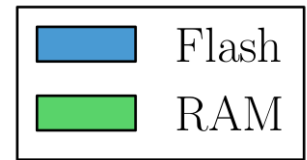
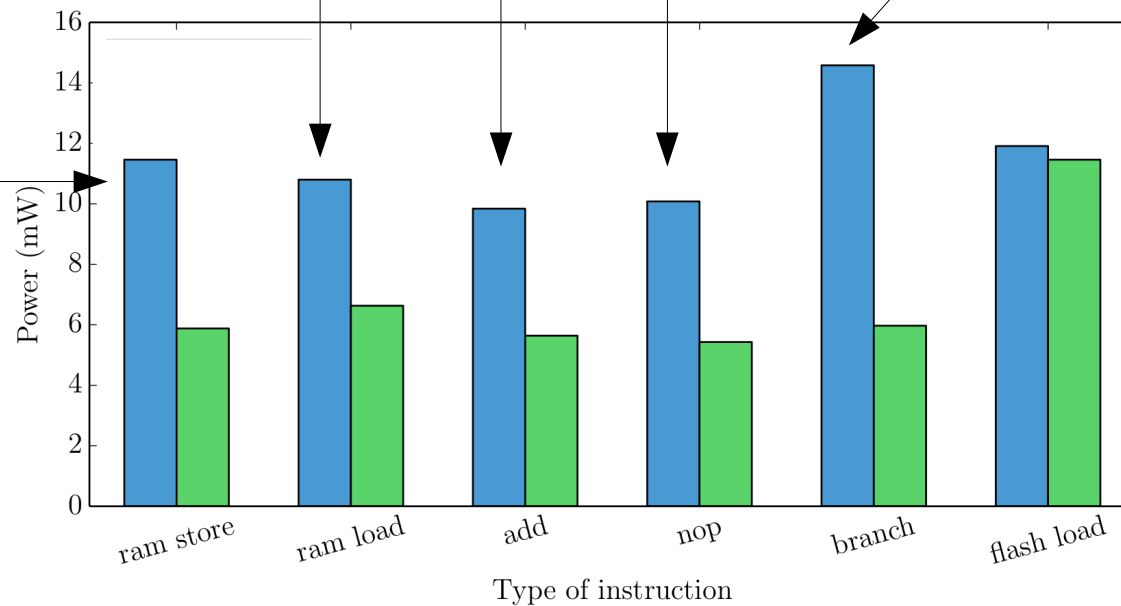
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add r0, r1
```

```
b label
```

```
; r1 in RAM  
ldr r0, [r1]
```

```
nop
```



Flash or RAM

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; r1 in RAM  
str r0, [r1]
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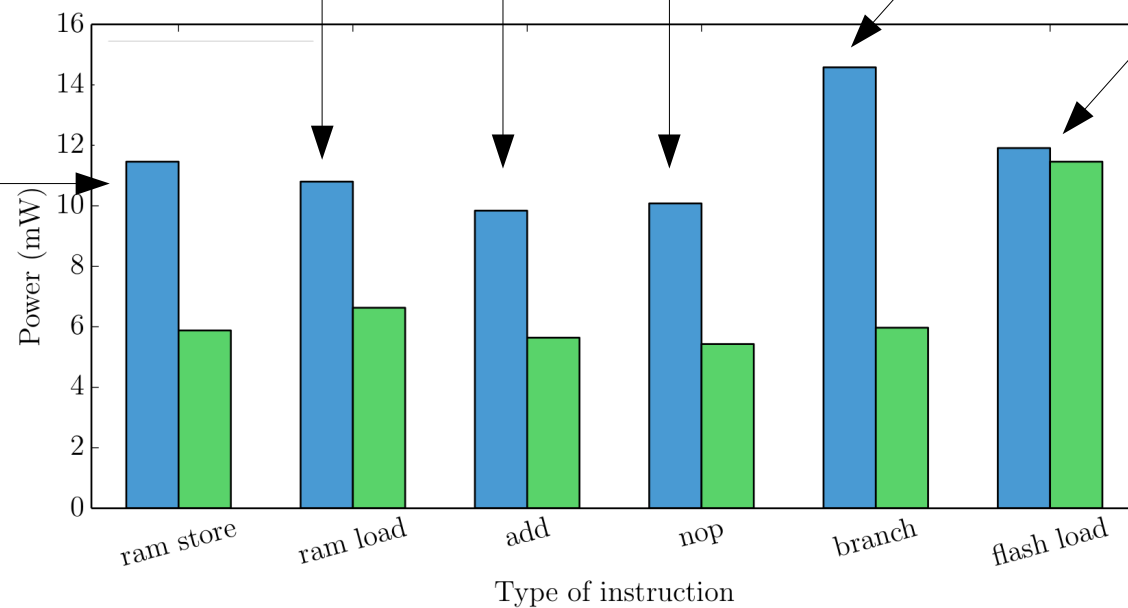
```
add r0, r1
```

```
b label
```

```
; r1 in RAM  
ldr r0, [r1]
```

```
nop
```

```
; r1 in flash  
ld r0, [r1]
```



Move basic blocks into RAM

Original code

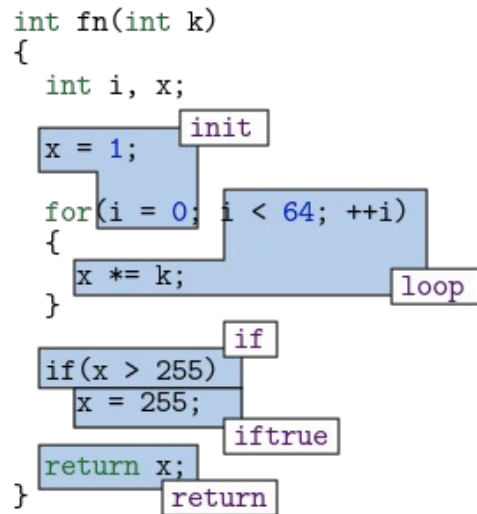
```
int fn(int k)
{
    int i, x;
    x = 1;
    for(i = 0; i < 64; ++i)
    {
        x *= k;
    }
    if(x > 255)
    {
        x = 255;
    }
    return x;
}
```

The diagram illustrates the control flow of the provided C code. Basic blocks are represented by blue-shaded rectangular regions: the initialization block (x = 1;), the loop body block (for loop), the conditional block (if), and the return block (return x;). Purple labels in small boxes identify these blocks: 'init' for the initialization, 'loop' for the loop body, 'if' for the conditional, and 'return' for the return statement. The flow starts at the 'init' block, proceeds to the 'loop' block, then to the 'if' block, and finally to the 'return' block.

Move basic blocks into RAM

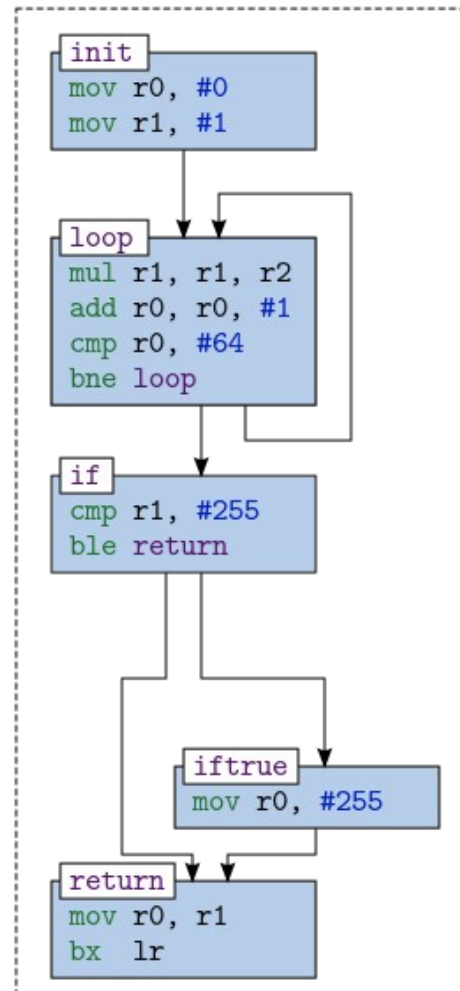
Original code

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}
```



Original compiled code

Flash



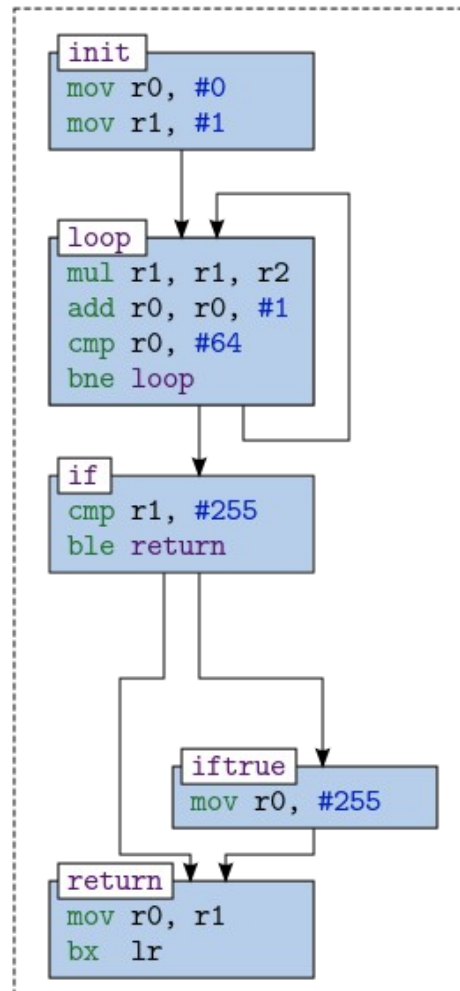
Move basic blocks into RAM

Original code

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int fn(int k)
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Original compiled code

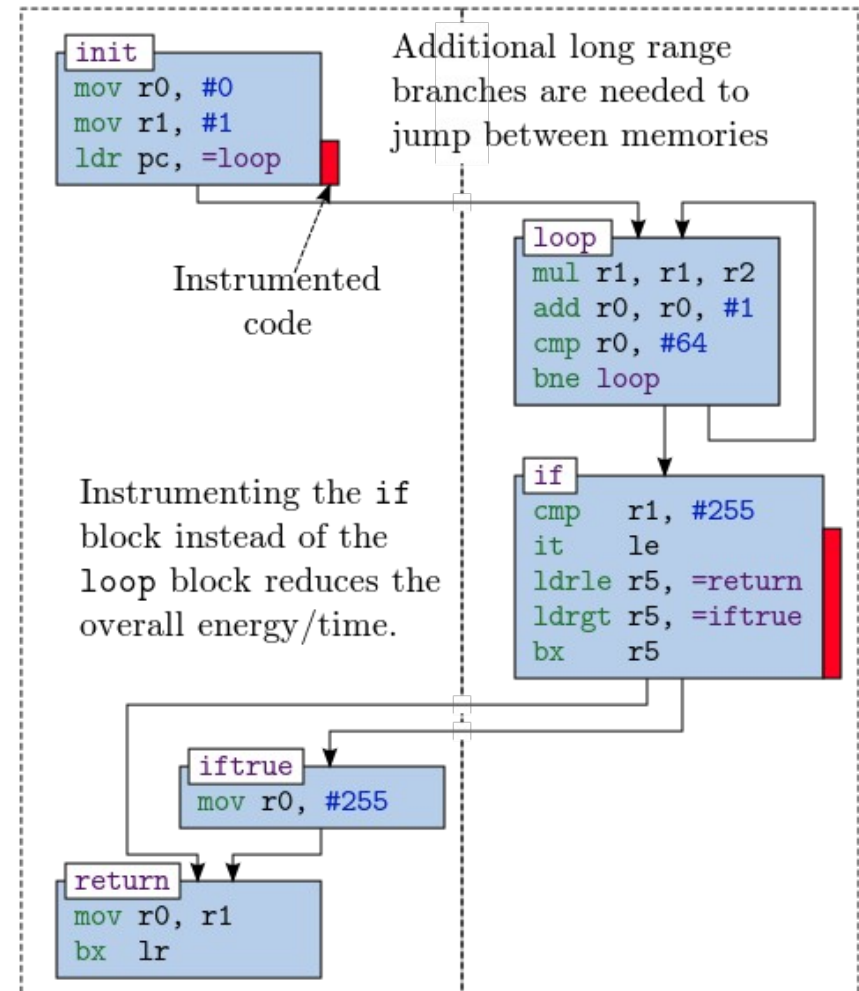
Flash



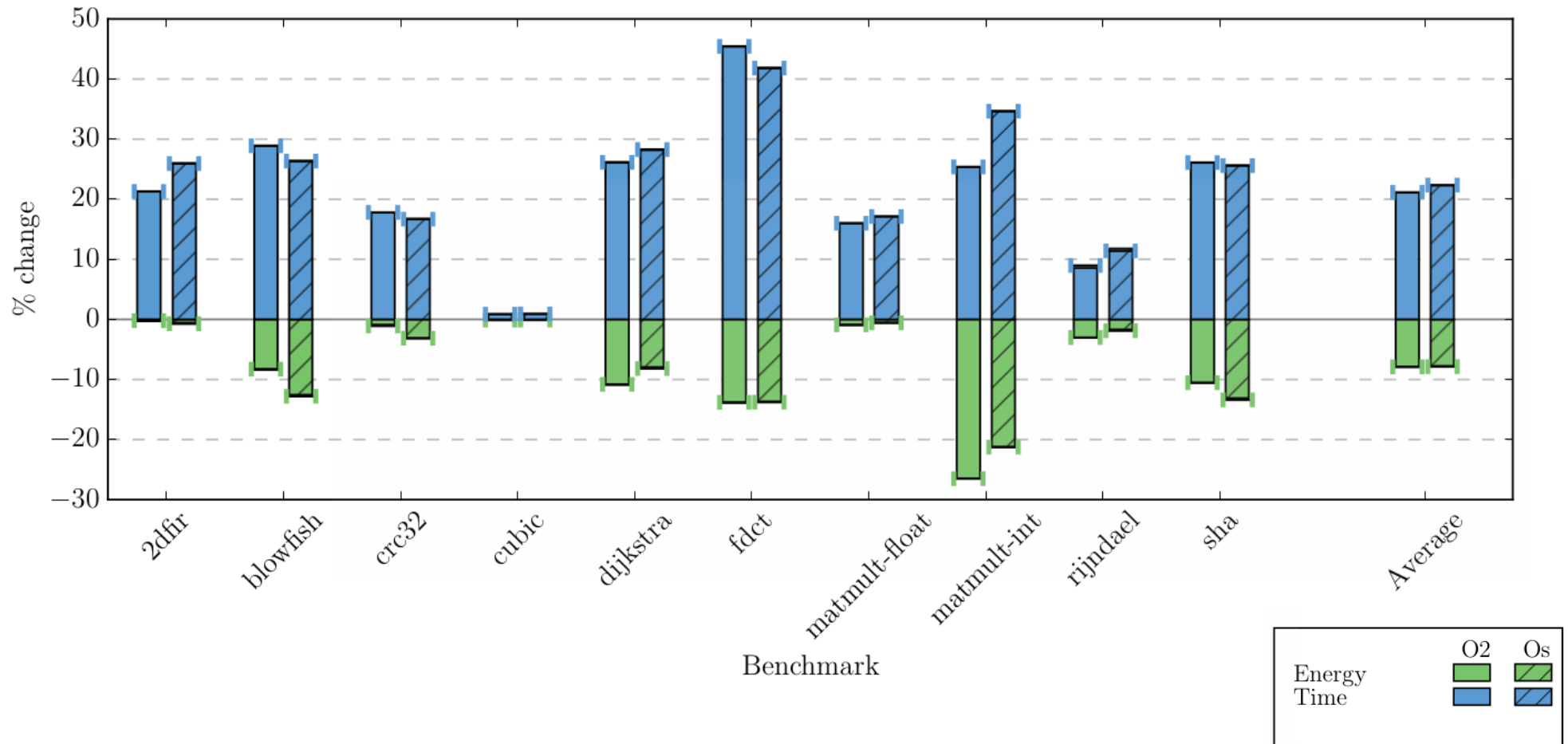
Optimized compiled code

Flash

RAM



Results



Optimisations for energy

The RAM overlay can save significant energy

- Up to 26%

This is achieved by reducing the k_P coefficient

- The execution time actually increases.

Aligning to flash boundaries is currently ineffective.

- Many of the boundary changes are necessary
- Other types of optimisations may succeed

Overview

Introduction

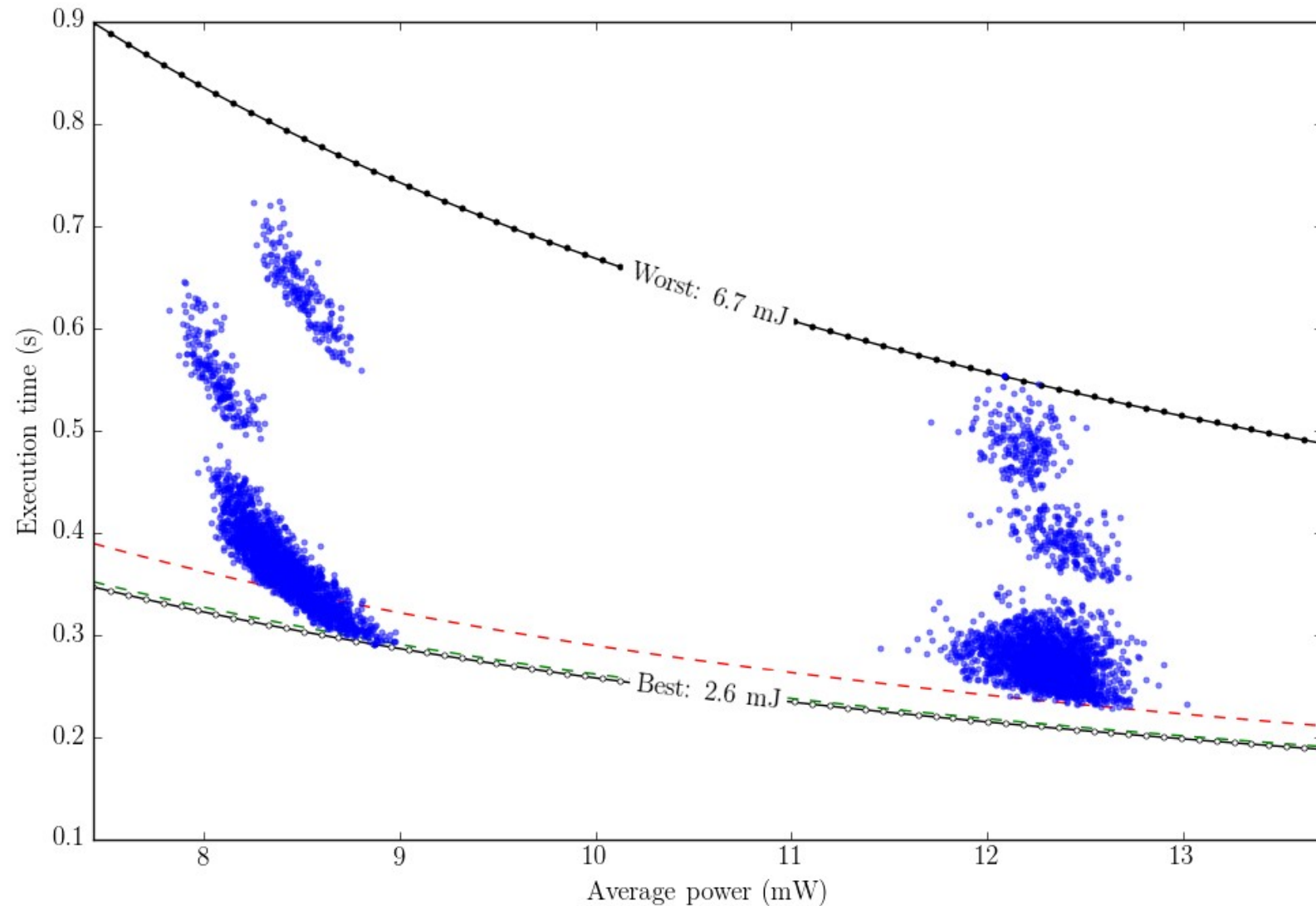
Optimisations for execution time

Optimisations for energy consumption

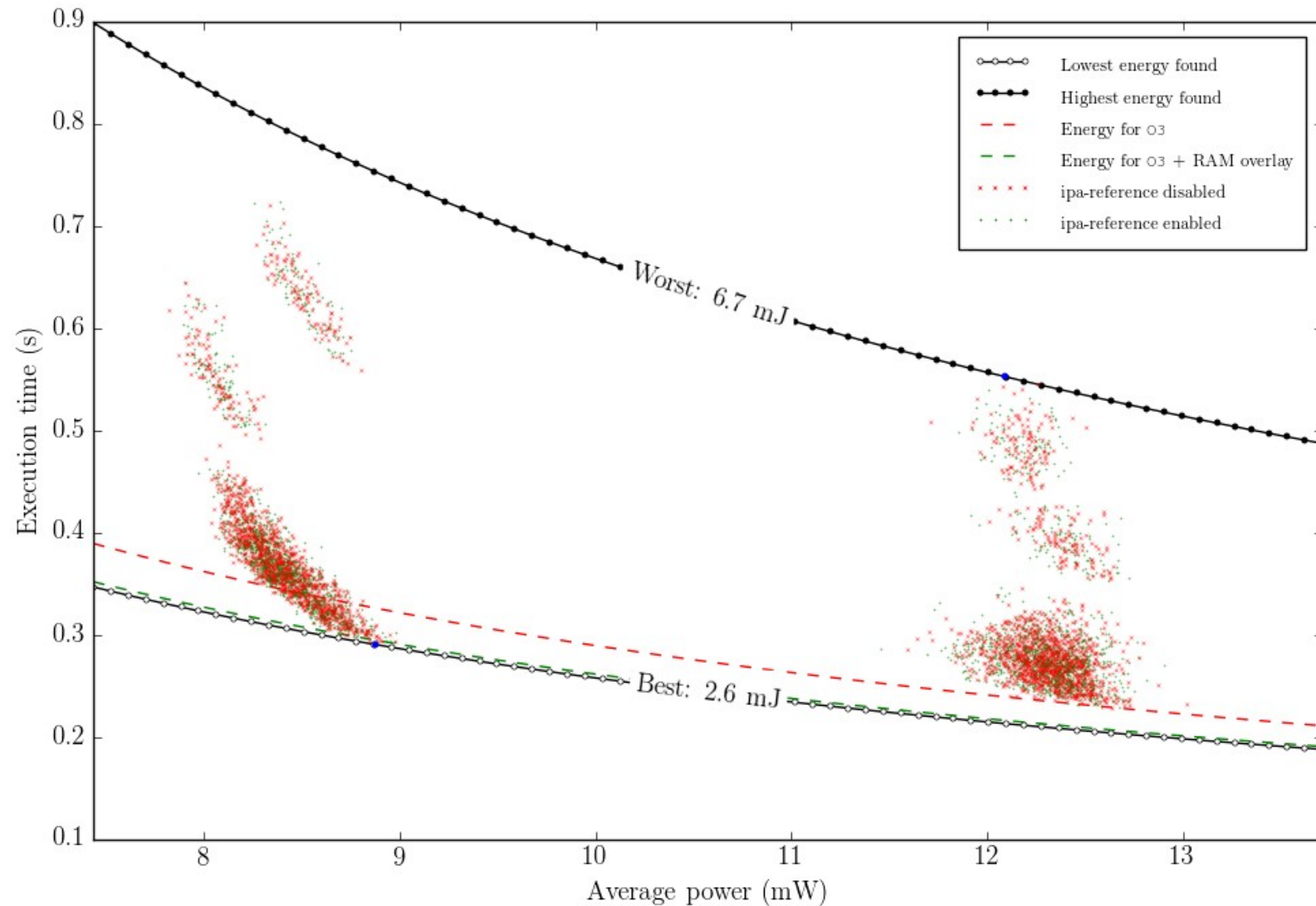
▶ ***Combining optimisations for energy and time***

Conclusion

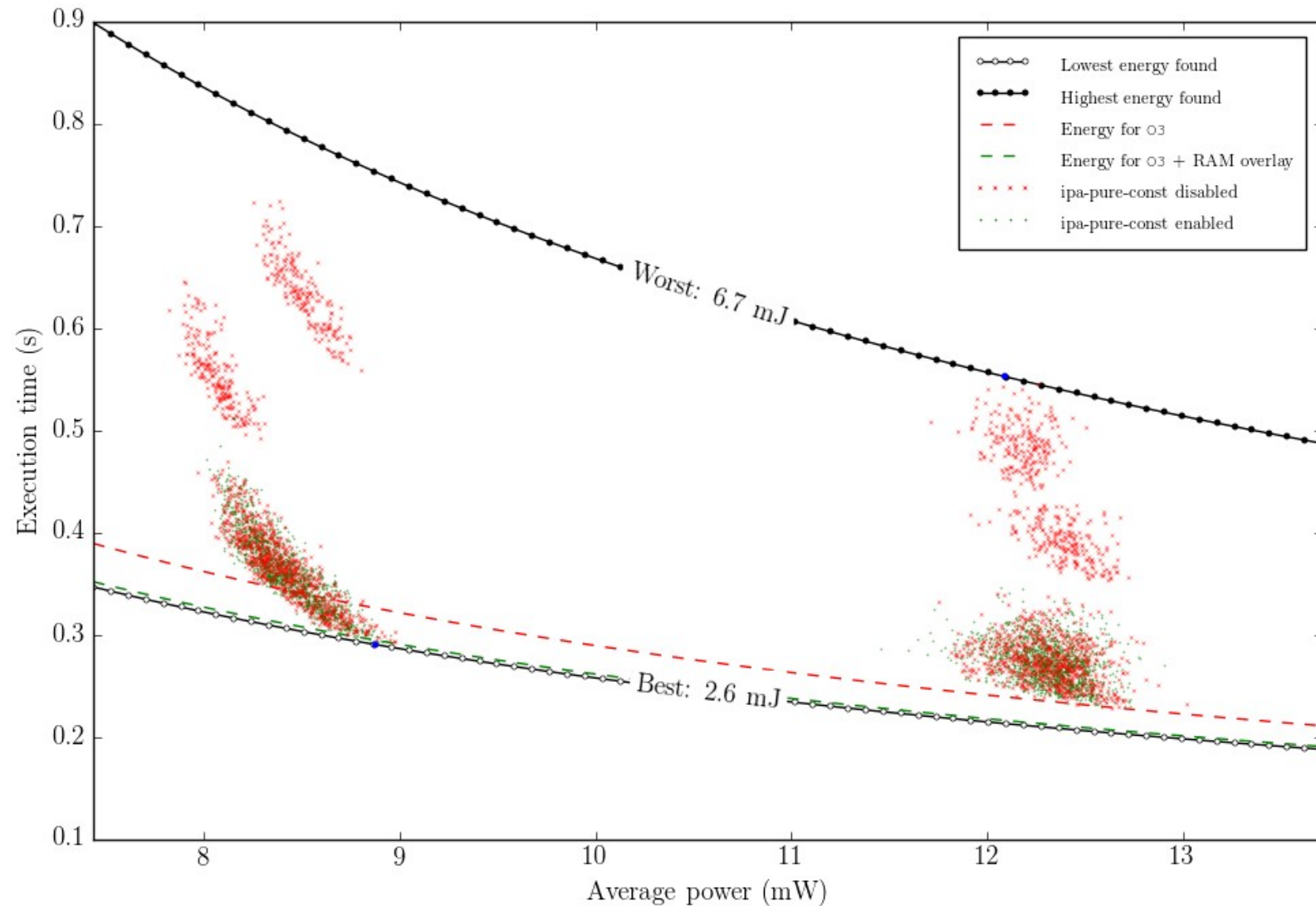
Combining optimisations



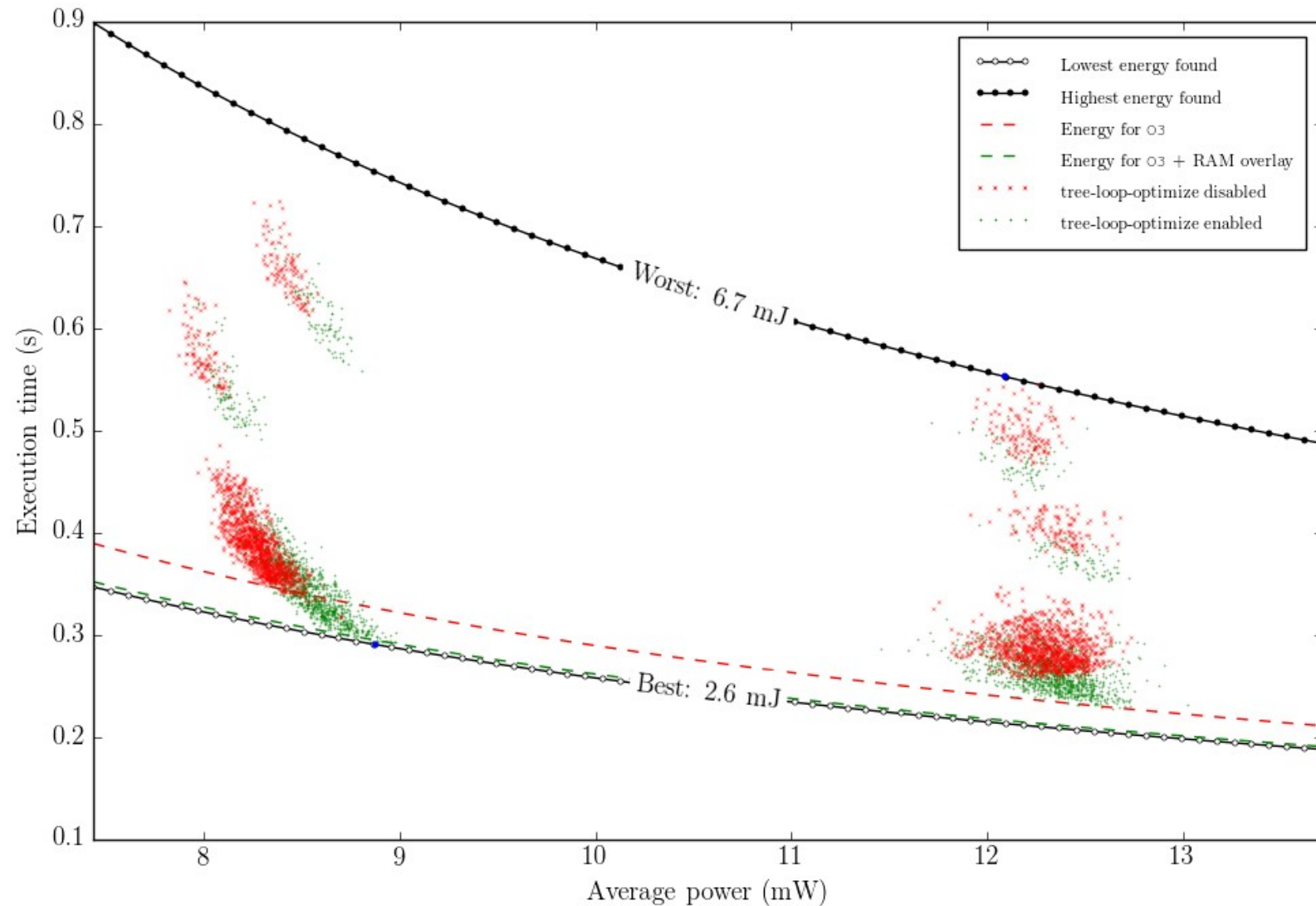
Combining optimisations



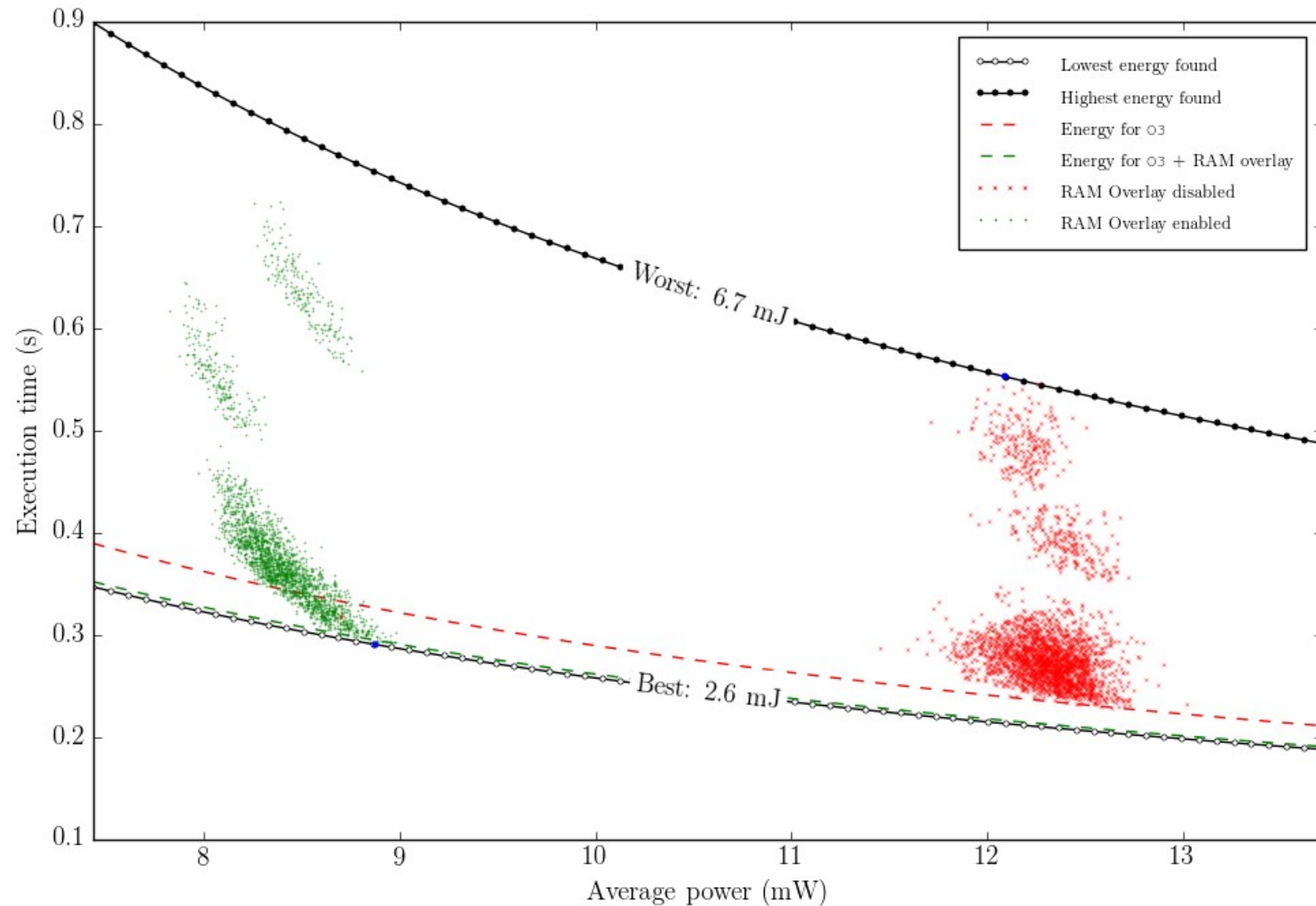
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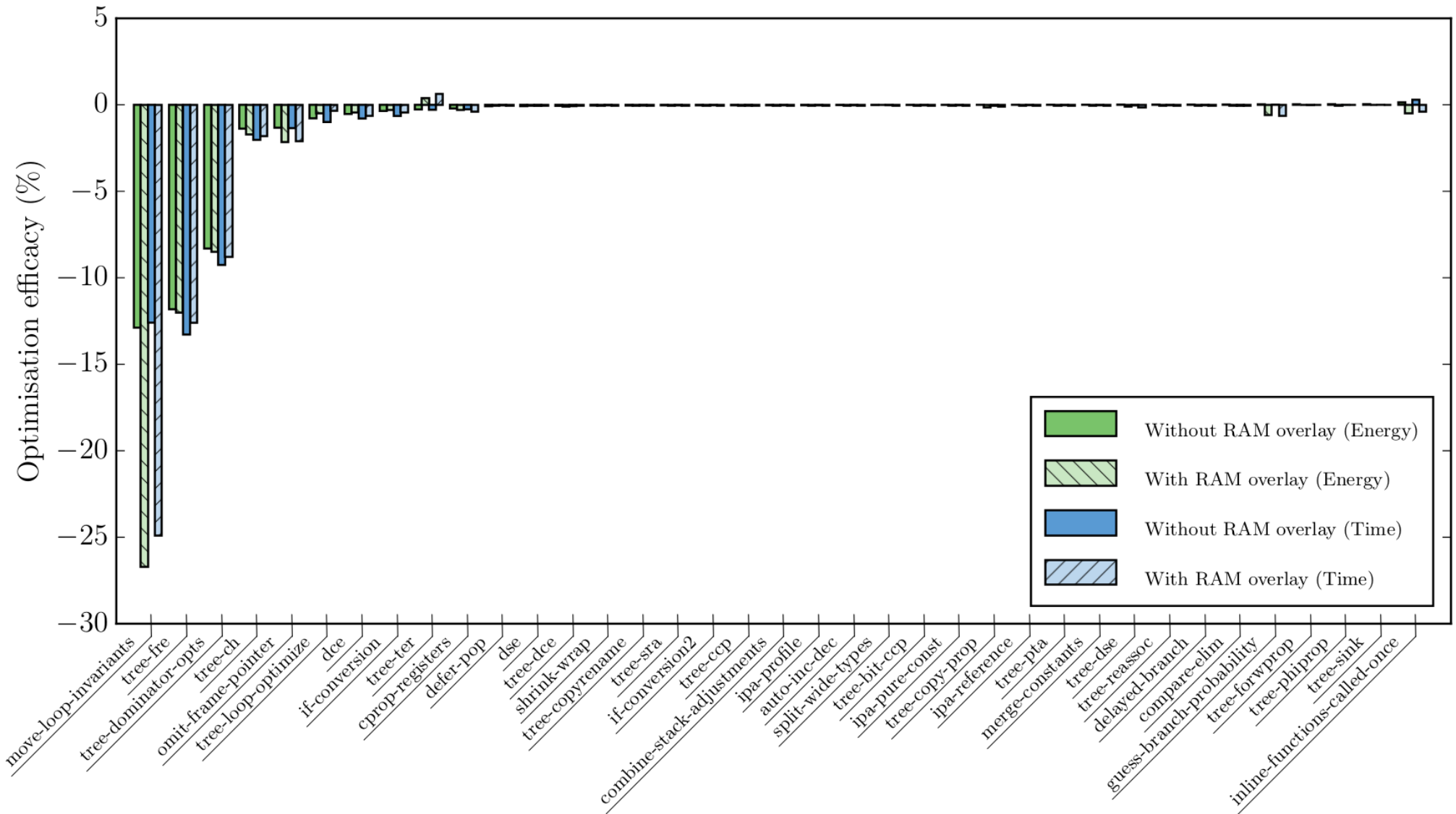
Combining optimisations



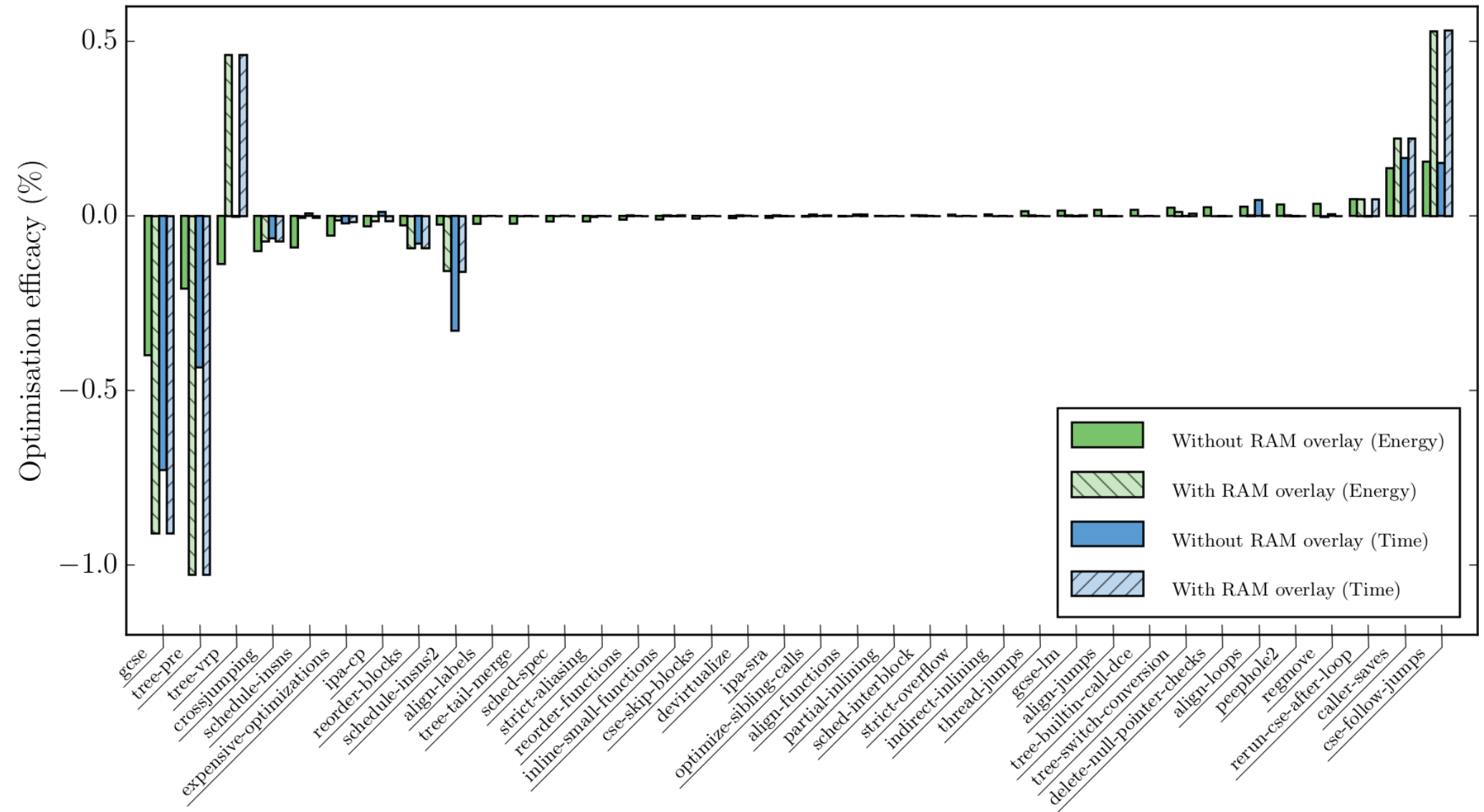
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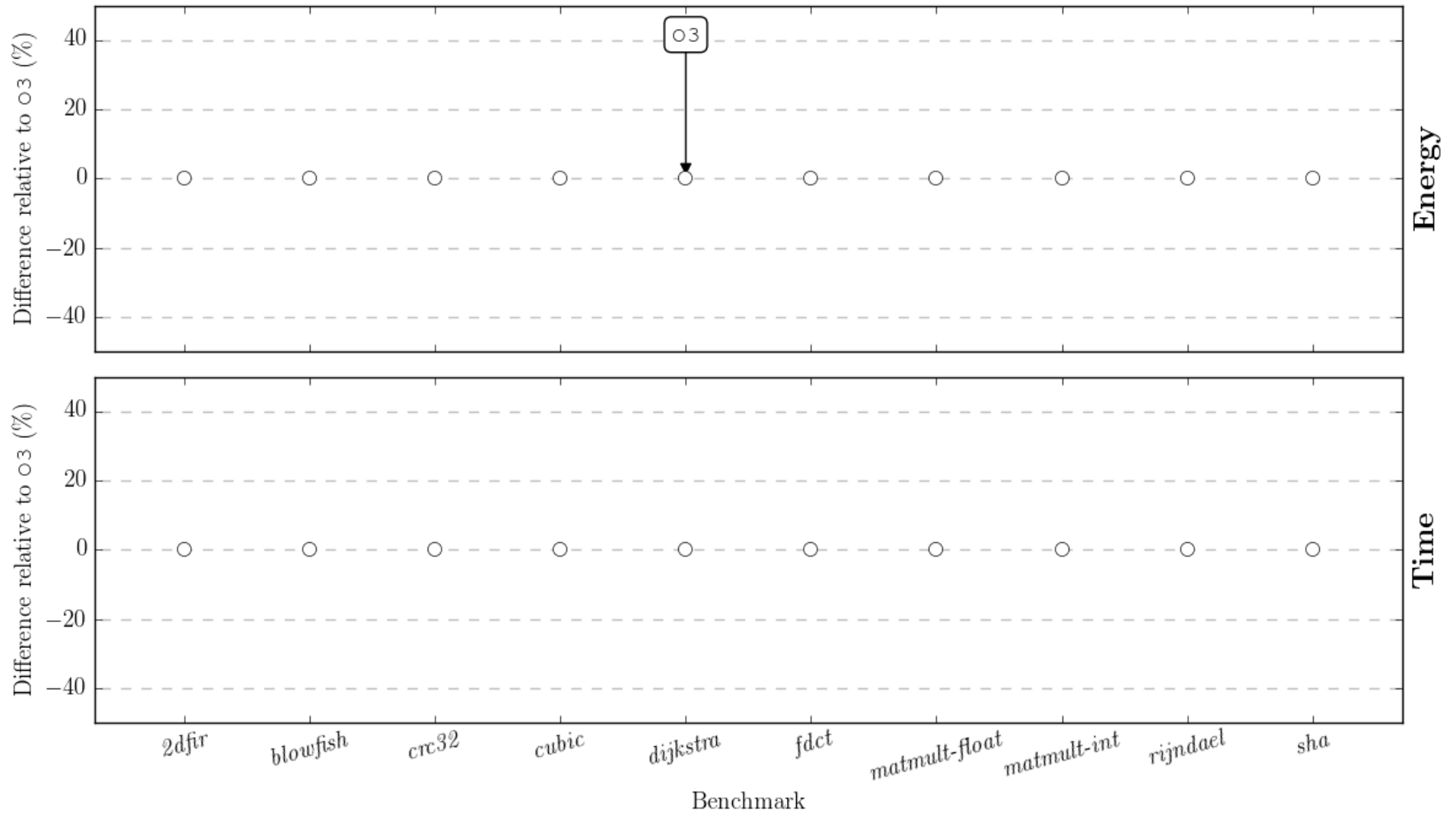
Fractional factorial design again



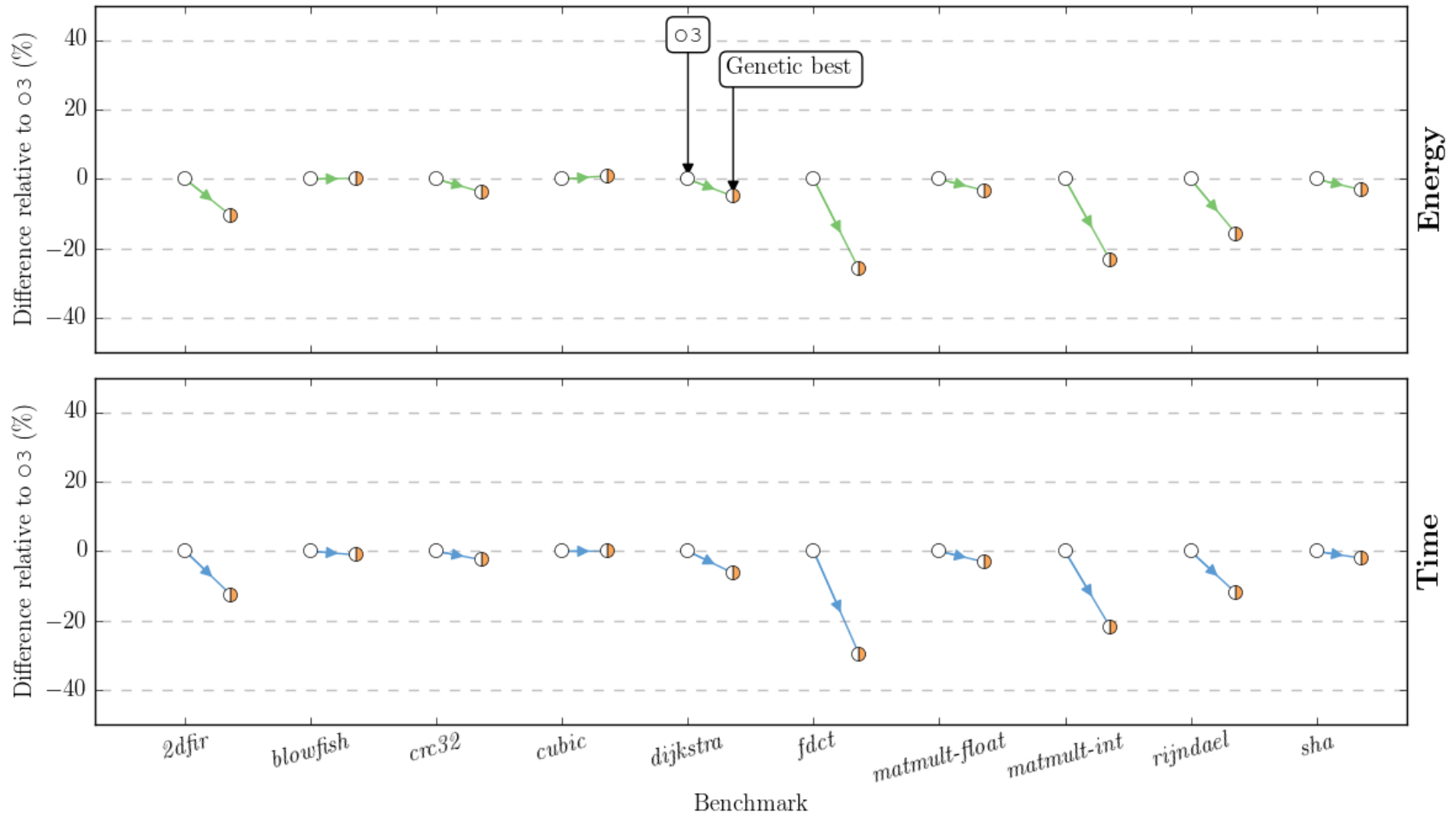
Fractional factorial design again



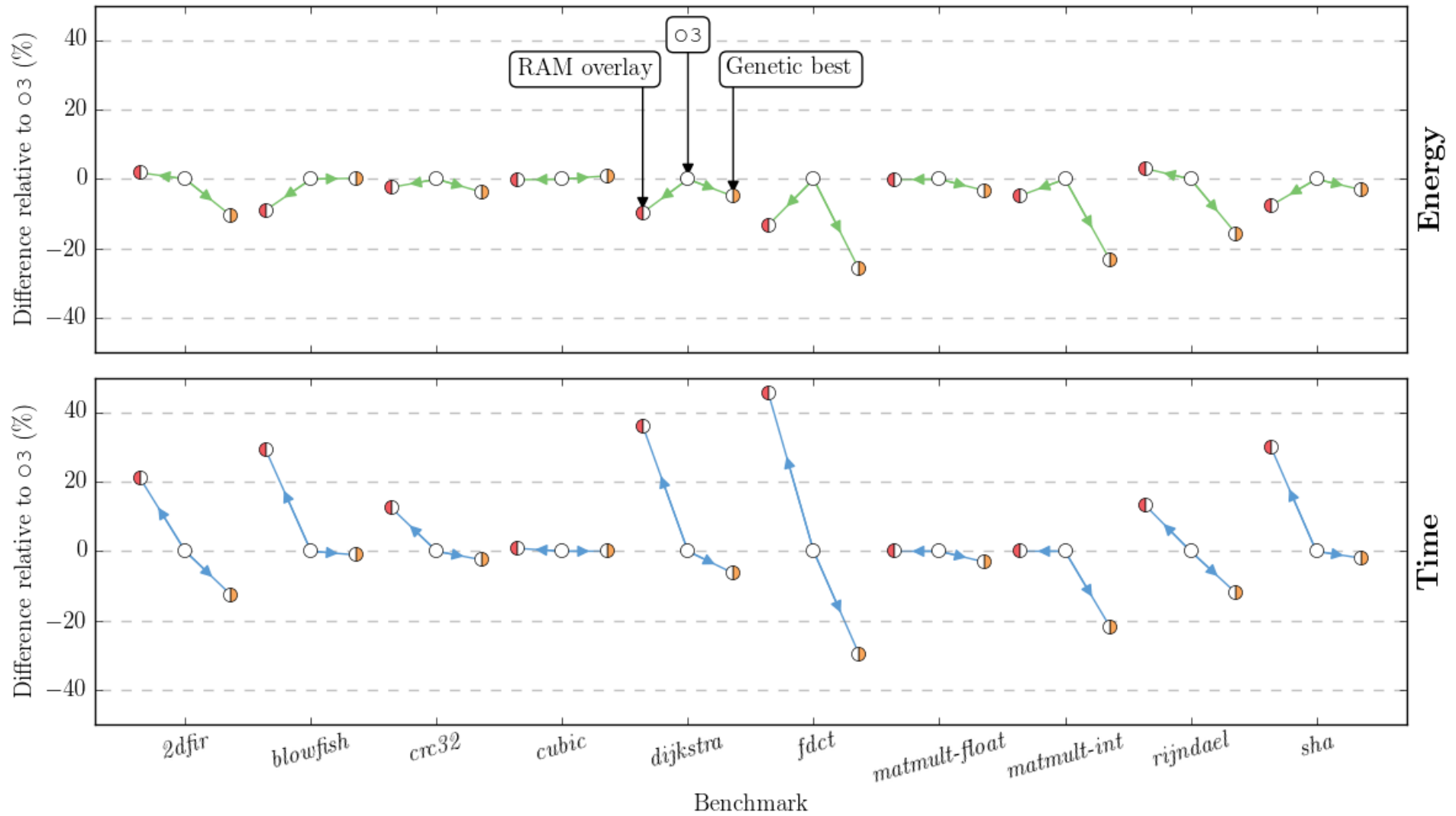
Composability



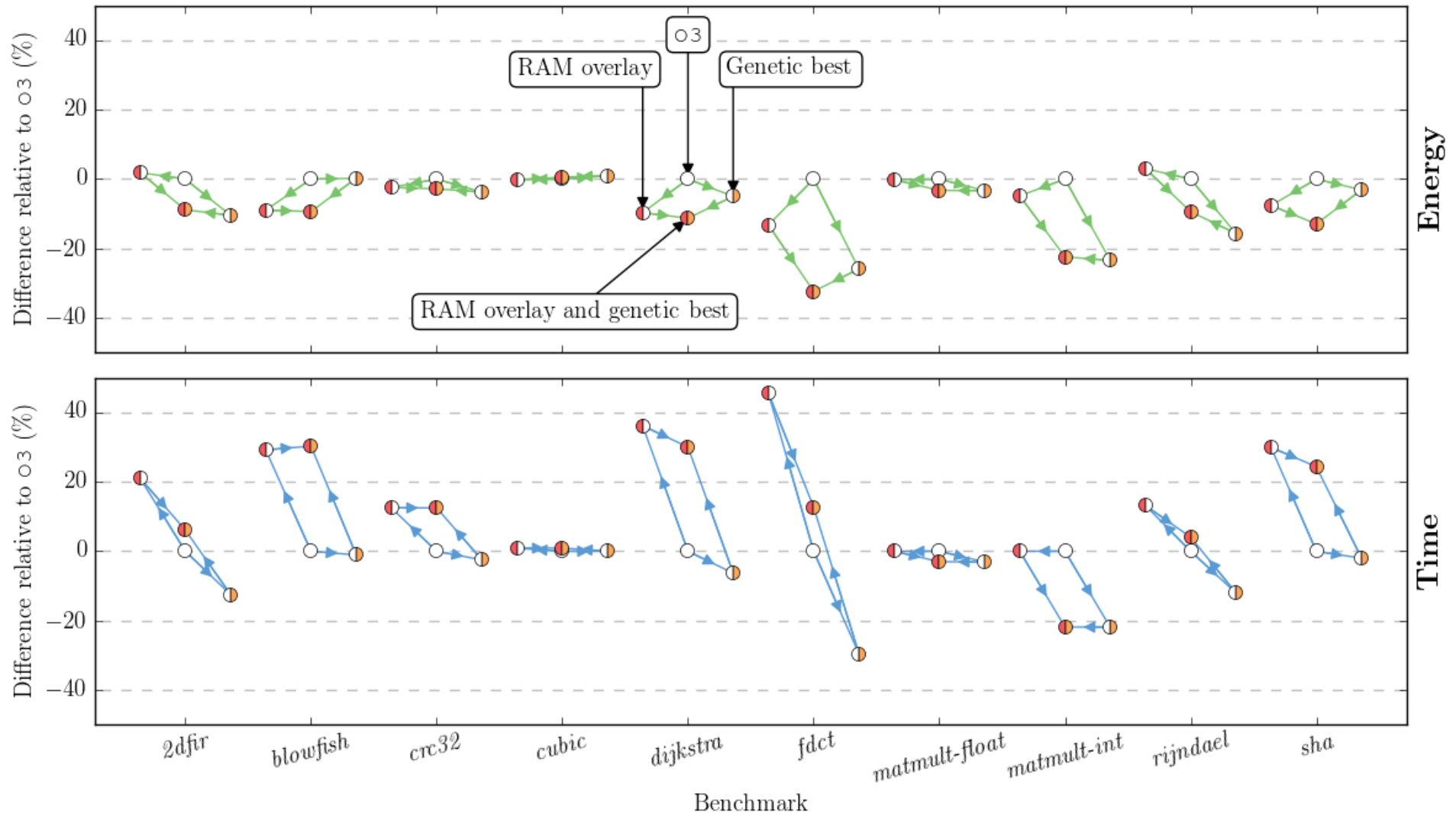
Composability



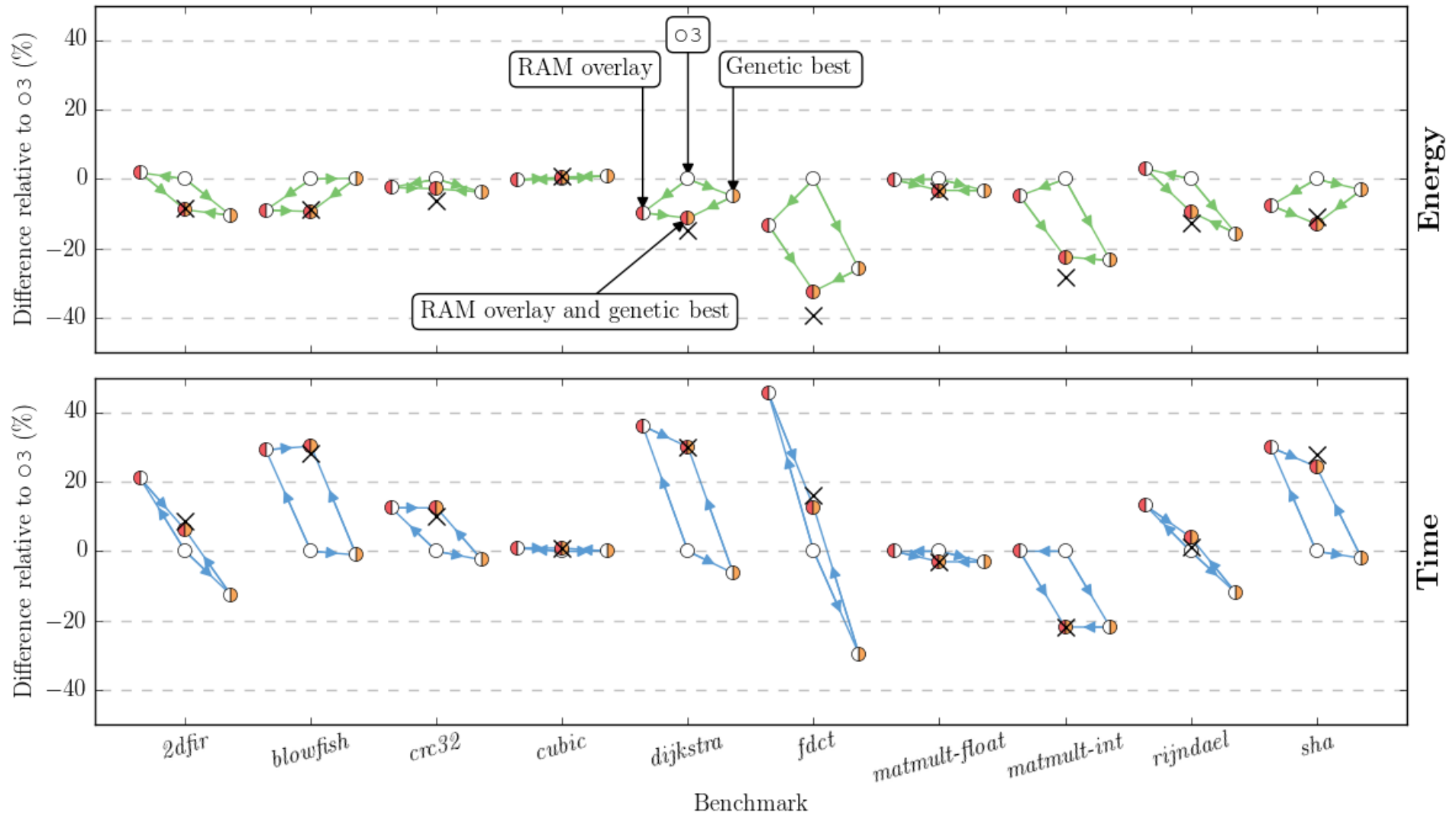
Composability



Composability



Composability



Combining optimisations

- The optimisations do not significantly interact.
- The same set of “base” optimisations can be applied
 - i.e. we do not need a new optimisation level to apply energy on top of.

Conclusion



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Existing optimisations affect execution time by design.

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Existing optimisations affect power by chance.

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Optimisations for energy *do* exist, they reduce energy by reducing average power.

Conclusion

Existing optimisations affect execution time by design.

Existing optimisations affect power by chance.

Optimisations for energy *do* exist, they reduce energy by reducing average power.

These optimisations combine linearly with existing optimisations.

Future work



Future work

How to find new energy optimisations?

Future work

How to find new energy optimisations?

Do all energy optimisations combine linearly?

Future work

How to find new energy optimisations?

Do all energy optimisations combine linearly?

Do the findings apply outside of embedded systems?

Future work

How to find new energy optimisations?

Do all energy optimisations combine linearly?

Do the findings apply outside of embedded systems?

Does the efficacy of the optimisations change when adding more cores/threads?

Thanks!

Questions?

More info:

James Pallister, Simon J. Hollis and Jeremy Bennett. “Identifying compiler options to minimize energy consumption for embedded platforms”. In: *The Computer Journal*. 2015.

James Pallister, Kerstin Eder, Simon J. Hollis and Jeremy Bennett. “A high-level model of embedded flash energy consumption”. In: *CASES’14 Proceedings of the 2014 international conference on Compilers, Architecture, and Synthesis for Embedded Systems*. New Delhi, India. ACM Press, 2014, p. 74.

James Pallister, Kerstin Eder and Simon J. Hollis. “Optimizing the flash-RAM energy trade-off in deeply embedded systems”. In: *CGO’15 Proceedings of the 2015 international symposium on Code Generation and Optimization*. San Francisco, USA. ACM Press, 2015.

Embedded systems



Embedded systems

Board Name	SoC Processor	RAM	ROM	Clock	Compiler	
					GCC	LLVM
STM32F0DISCOVERY	STM32F051 Cortex-M0	SRAM 8kB	Flash 64kB	8MHz	✓	✓
STM32VLDISCOVERY	STM32F100 Cortex-M3	SRAM 8kB	Flash 128kB	8MHz	✓	✓
Breadboard	ATMEGA328P AVR8	SRAM 2kB	Flash 32kB	8MHz	✓	✗
XMEGA-A3BU Xplained	ATXMEGA256A3BU AVR8	SRAM 16kB	Flash 256kB	8MHz	✓	✗
Breadboard	PIC32MX250F128B MIPS32	SRAM 32kB	Flash 128kB	8MHz	✓	✗
MSP-EXP430F5229LP	MSP430F5529 MSP430	SRAM 10kB	Flash 128kB	8MHz	✓	✗
MSP-EXP430FR5739LP	MSP430FR5739 MSP430	SRAM 1kB	FRAM 16kB	8MHz	✓	✗
Beagle Bone	AM335x Cortex-A8	DRAM 256MB	SD-Card	800MHz	✓	✓
EME4 Dev Board	EME4 Epiphany	SRAM 32kB [†]	None	800MHz	✓	✗
XK-1A	XS1-L8-64 XMOSES1	SRAM 64k	None [‡]	400MHz	✗	✓

Individual optimisations

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

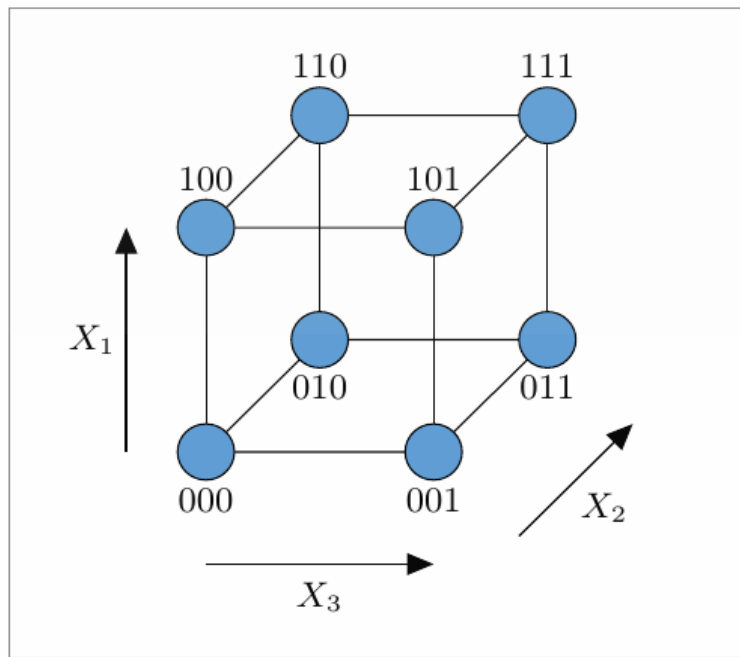
Individual optimisations

Fractional factorial design

“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Individual optimisations

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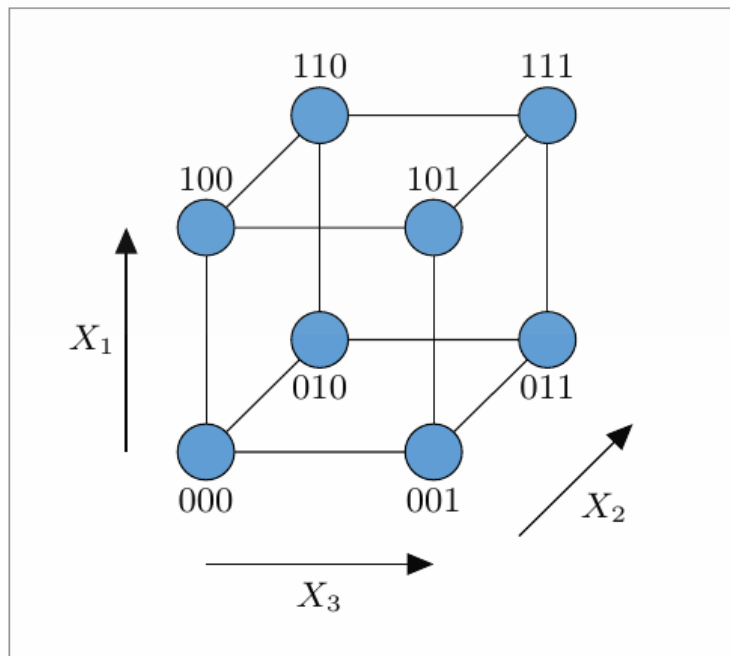


Full factorial design

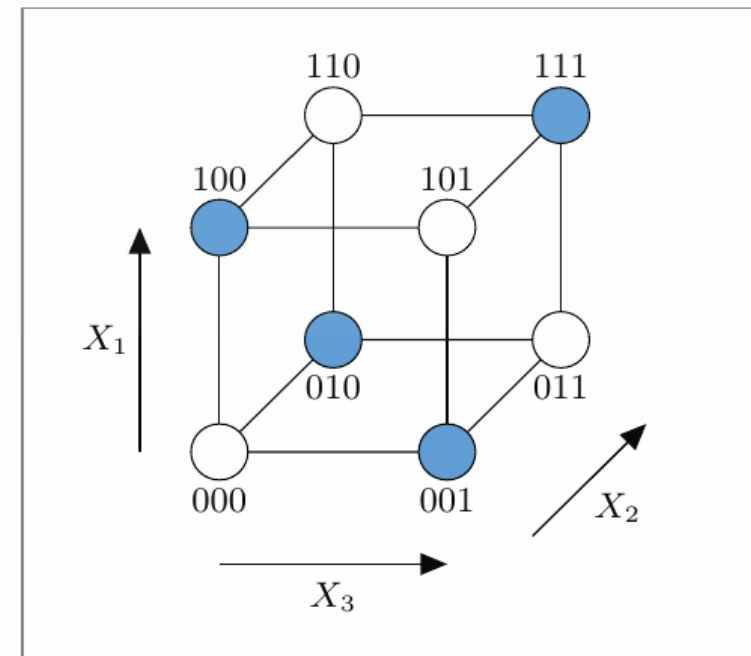
“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

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Full factorial design



Fractional factorial design

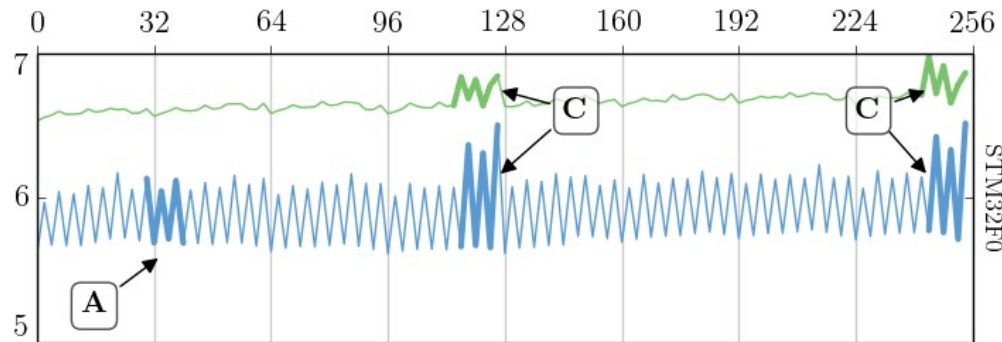
“Do existing compiler optimisations save energy purely by reducing the k_T coefficient?”

Parameters

SoC	Model parameters (pJ)						
	E_2 (A)	E_3	E_4 (B)	E_5	E_6	E_7 (C)	E_8 (C)
STM32F0	300	27	6	0	9	100	6
STM32F1	500	0	6	34	4	10	190
ATMEGA328P	0	22	36	27	9	107	24
PIC32MX250F128B	225	0	10	18	8	13	113
MSP430F5529	408	0	34	26	15	13	13

Parameters

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